

MICRO THERMO TECHNOLOGIES

Supermarket Control System

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1 Overview of the MT Alliance System

1.1 MT Alliance Sub-Systems

The MT Alliance system is a software platform that interacts with intelligent distributed modules known as *nodes*. Nodes help monitor and control a supermarket's sub-systems (Figure 1.1):

- monitoring sub-system
- refrigeration sub-system
- HVAC sub-system
- lighting sub-system
- energy management sub-system

The *monitoring sub-system* monitors the refrigerated cases 24 hours a day to prevent product shrink. The monitoring system sends an alert when a perishable product is in danger of being lost and specifies the steps to take before losing the product. Sensors installed in the refrigerated cases measure the temperature of the refrigerated case and products, as well as detect the end of defrosting. Each sensor comprises:

- Lower limit for the programmable alarm
- Upper limit for the programmable alarm
- Programmable alarm set time
- Programmable alarm recall time

The monitoring sub-system carries out the following functions:

- Reads temperatures from sensors using a one-minute sampling interval
- Saves sensor data for a period of three (3) years
- Displays the various types of products stored in the refrigerated cases and their corresponding temperatures
- Graphically displays data from temperature sensors

The MT Alliance provides a graphic view (figures 1.2 and 1.3), which displays the position of the refrigerated cases, the type of product in each case and the product temperature. When the refrigerated case temperature exceeds the programmed limits (lower limit, upper limit and alarm set time), the MT Alliance system:

- Indicates the location of the case that triggers off the alarm by changing the refrigerated case color from green to red
- Generates an event in the alarm window: alarm origin, time and cause
- generates an alarm signal at the Alarm Center

After an alarm has been activated, the user can acknowledge the alarm and take steps to solve the problem. The MT Alliance system provides user names and access codes to each user, which makes it easier to trace the person who acknowledged the alarm.

The *HVAC sub-system* controls HVAC equipment: roof top units, central heating and air-conditioning, zone controllers, etc. With it, users can adjust the temperature and humidity set points in the different areas of a supermarket (Figure 1.4).

The *lighting sub-system* is used to program lighting schedules (Figure 1.5) based on the supermarket's opening and closing times, as well as on special days such as legal holidays. This sub-system also controls the intensity of supermarket lights based on the surrounding light intensity detected by the photocell sensor.

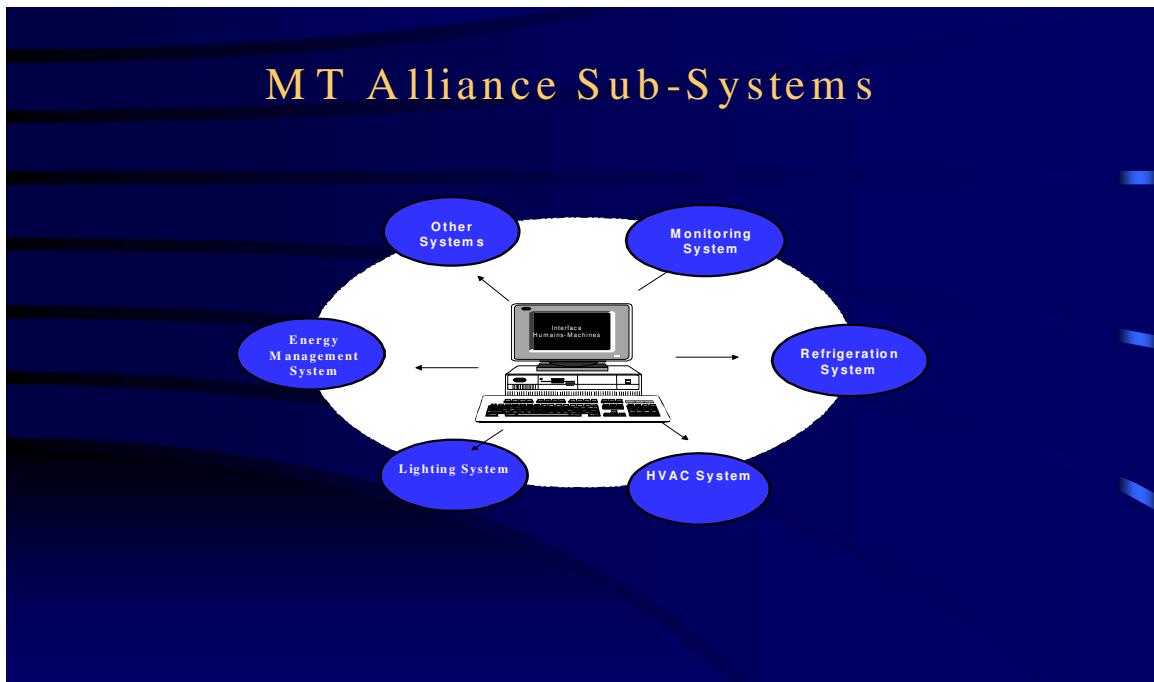


FIGURE 1.1

Sub-Systems	Description
Monitoring	<p>The main functions of the monitoring sub-system are:</p> <ul style="list-style-type: none"> monitoring the different types of sensors: case temperature, end-of-defrosting cycle sensor saving sensor information in the MT Alliance and drawing graphs based on this information generating local alarms when the temperature exceeds the limits and acknowledges them sending alarms to the Alarm Center
Refrigeration	<p>The main functions of the refrigeration sub-system are:</p> <ul style="list-style-type: none"> maintaining case temperatures so as to protect products defrosting cases according to a preprogrammed schedule
HVAC	<p>The main functions of the HVAC sub-system are:</p> <ul style="list-style-type: none"> maintaining a comfortable temperature in the occupied zones during occupancy mode lowering the temperature while in inoccupancy mode maintaining adequate humidity in the main area of the supermarket in order to reduce the frequency of defrosting in the refrigerated cases
Lighting	<p>The main functions of the lighting sub-system are:</p> <ul style="list-style-type: none"> maintaining adequate light intensity (clients & employees) in the various zones lowering or turning off lights according to a programmed schedule
Energy Management	<p>The main functions of the energy management sub-system are:</p> <ul style="list-style-type: none"> reducing energy consumption of the sub-systems by means of effective control strategies controlling electrical loads (load shedding) during periods of high energy consumption

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Overview of MT Alliance System:

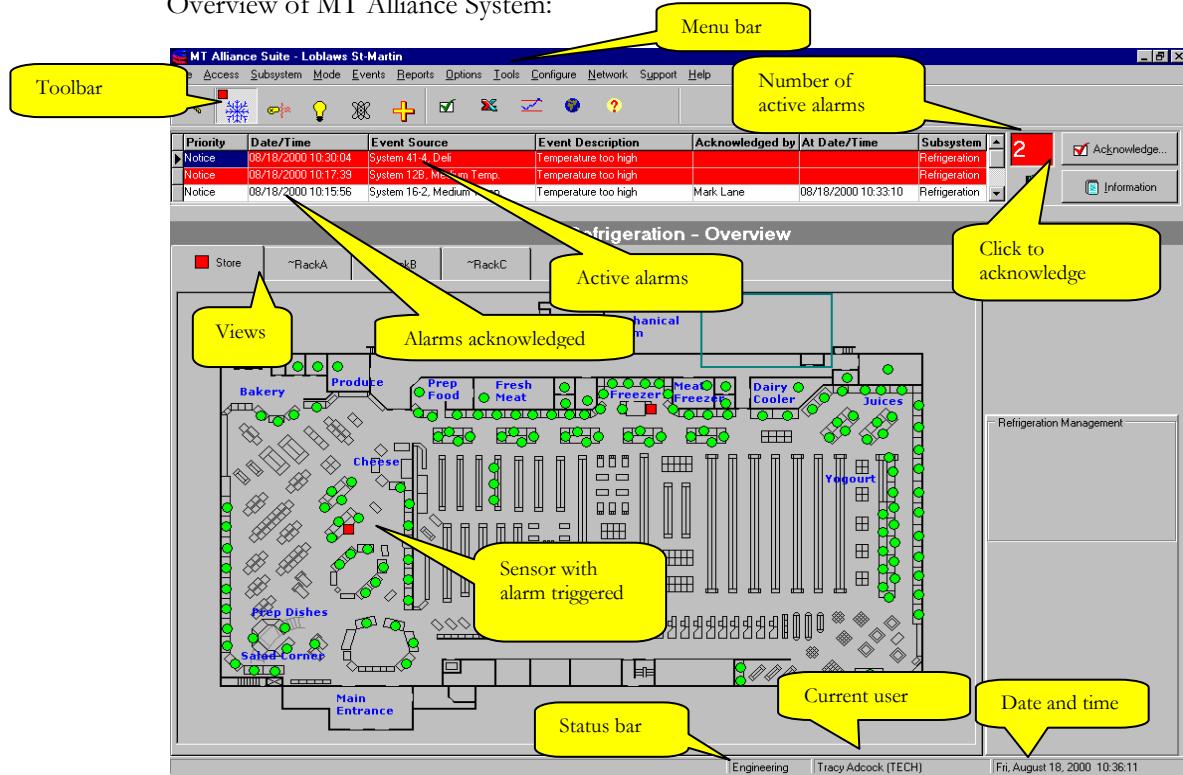


FIGURE 1.2

Zoomed view of MT Alliance System:

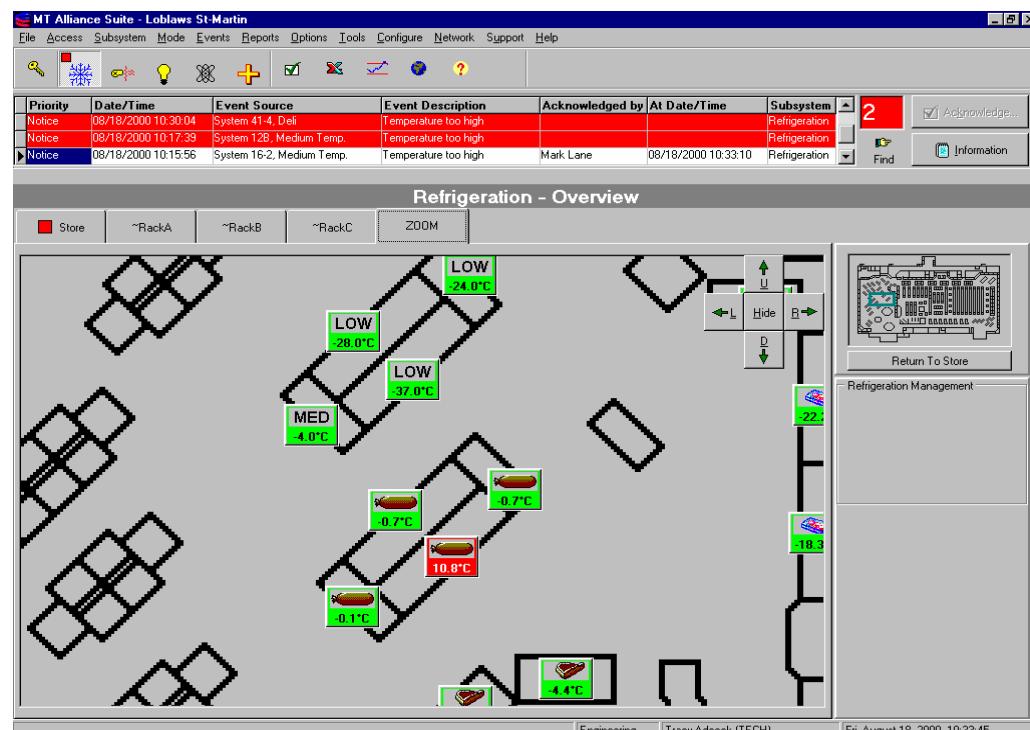


FIGURE 1.3

View of a window for adjusting temperature:

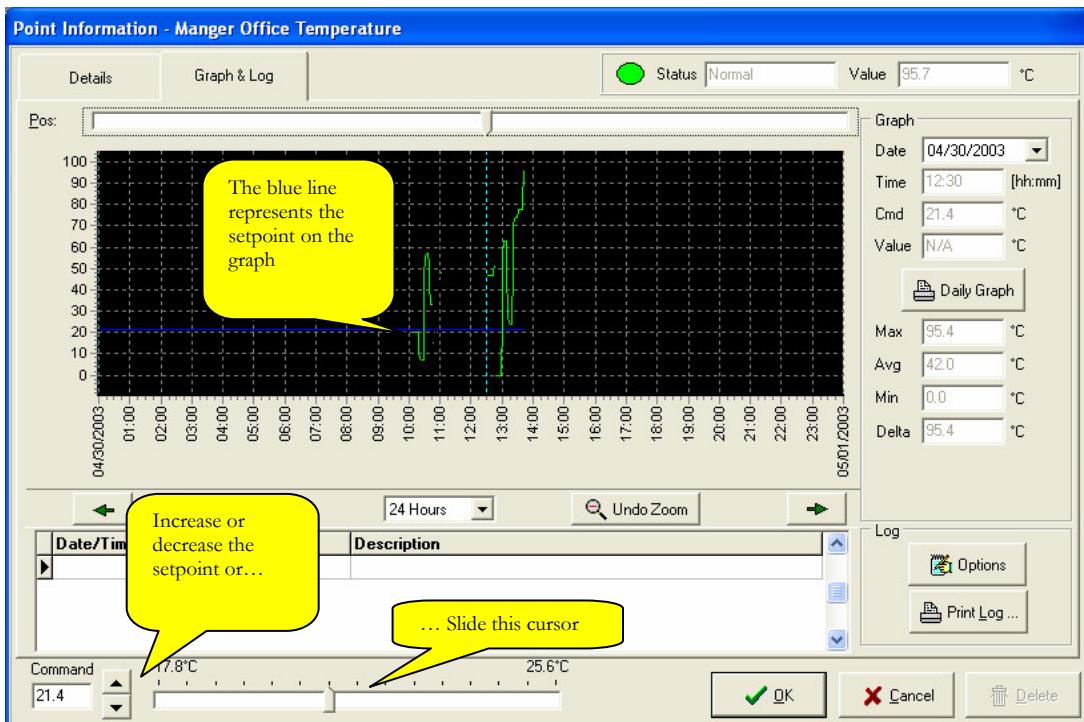


FIGURE 1.4

View of a lighting schedule:

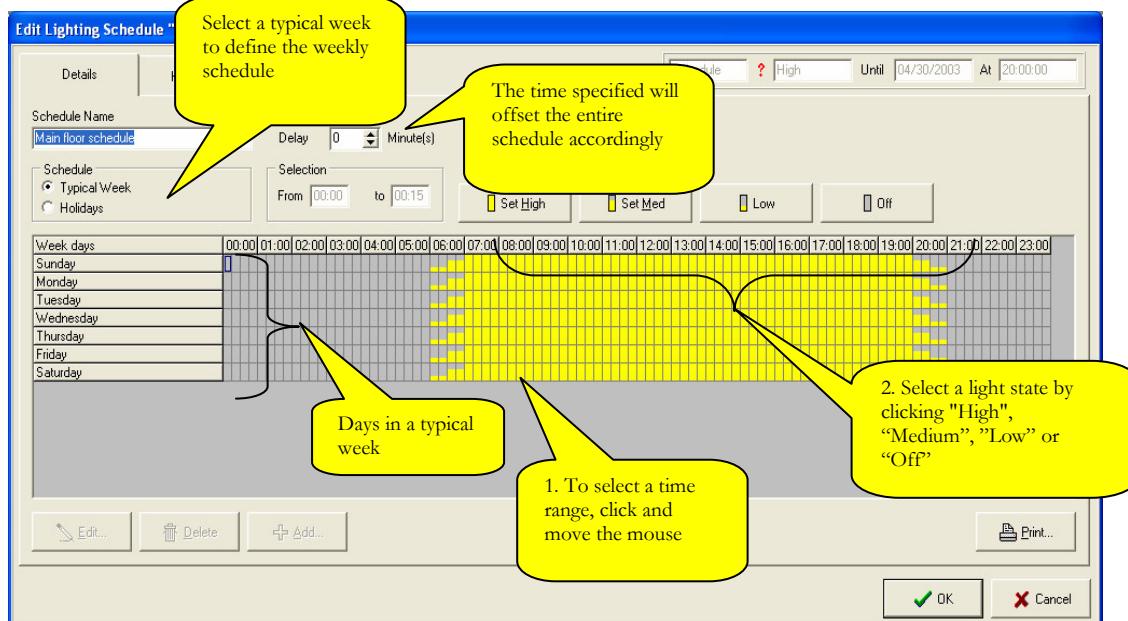


FIGURE 1.5

2 Architecture of a MT Alliance Distributed Control Systems

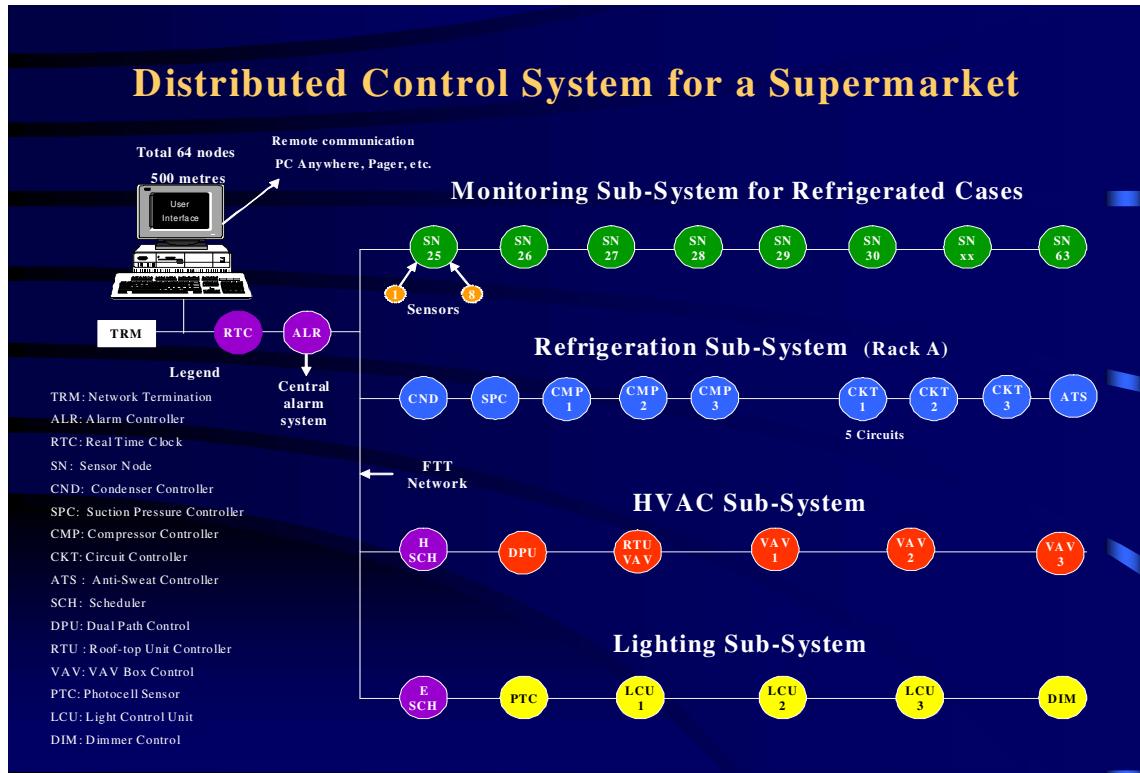


FIGURE 2.1

The distributed control system for a supermarket is made up of the following components:

- a personal computer
- a LonWorks communications network
- electronic modules called nodes or controllers that ensure the operation of the MT Alliance sub-systems

2.1 Personal Computer

The computer allows technicians and users to navigate through the different MT Alliance sub-systems. Therefore, the personal computer is used to carry out the following operations:

- Configuring the controllers of the different sub-systems
- Sending the configuration to the controllers via the LonWorks communications network
- Monitoring and controlling the different sub-systems
- Troubleshooting a technical problem on a sub-system using analysis tools

In a distributed system, controlling sub-systems is carried out by the different sub-system controllers and not by the personal computer. Therefore, if the PC crashes, sub-system operation is carried out by the different controllers and the alarms are sent to the Alarm Center. Only data from the sensors, which are normally saved, will be lost if the computer crashes.

2.2 LonWorks Communications Network

The LonWorks FIT (free topology) network is made up of a pair of twisted wires that link the controllers to each other without restriction in the controller connection topology. The polarity of the wire pairs can be reversed in the connector to each controller without causing operating problems with the MT Alliance System. To prevent the reflection of signals on the network, the network must have a termination point (end-of-line resistor).

The LonWorks network illustrated in the diagram (Figure 2.1) is limited to 64 nodes and to total length of 500 meters. In certain applications, network capacity can be increased to 124 nodes and to a total length of 1,500 meters, through the addition of two network amplifiers (Repeater).

The communications network has three main functions:

- Sending computer information (configuration settings, set points) to the controllers
- Sending controller information (sensor and detector signals, security device and actuator statuses) to the computer
- Sending information between controllers

Communications software in the chip of each controller is used to send data between controllers, and between the controllers and PC. The reliability and performance of the sub-systems are assured by the robustness of the communications software. This software re-sends information between controllers and between the controllers and PC following:

- A collision in data transmission over the network
- Unsuccessful data exchange between two controllers on the network

2.3 Description and Role of Controllers in the Different MT Alliance System Sub-Systems

2.3.1 MT Alliance Monitoring Sub-System

The table below lists various types of controllers and modules, as well as the main functions of each controller in the Monitoring Sub-System. Refer to the diagram illustrating the Distributed Control System for a Supermarket (Figure 2.1).

Controllers/Node	Legend	Modules	Functions
Sensor Node	SN	MT 500	<p>The <i>sensor node</i> is used to monitor eight (8) sensors and generate an alarm if the signal from a sensor exceeds the low or high limit programmed in the node.</p> <p>Different types of sensors can be connected to each input: Temperature sensor for refrigerated cases, temperature sensors for the end of defrosting, refrigerant leak detector, etc.</p>
Real Time Clock	RTC	Real Time Clock	Normally, the <i>computer's clock</i> synchronizes with the clock in each controller on the network by regularly sending the time over the network. When the computer crashes, the real-time clock takes over the computer and takes over this function.
Alarm Controller	ALR	Alarm Controller	<p>When a sensor node generates an alarm, the information is sent to the computer and alarm controllers:</p> <ul style="list-style-type: none">• The computer displays the alarm in the alarm banner• The alarm controller sends the alarm to the Alarm Center

2.3.2 Refrigeration Sub-System

The table below lists the various types of controllers for the refrigeration sub-system, the module type and the main functions of each controller. Refer to the diagram illustrating the Distributed Control System for a Supermarket (Figure 2.1):

Controllers/Node	Legend	Modules	Functions
Condenser Controller	CND	MT 504 MT 508 MT 512	<p>The condenser controller is used to maintain the condenser temperature at a temperature higher than the outside temperature; this allows accumulated heat to be evacuated from the refrigeration circuit. The controller carries out this function by comparing the pressure/temperature measured in the condenser at a programmed set point and starts one or more fans based on the difference of these two values.</p> <p>When the condenser temperature is higher than the outside temperature, the heat accumulated in the gaseous refrigerant from the refrigerated cases is released into the ambient air. This also causes the gaseous refrigerant to liquefy.</p> <p>The condenser controller can control up to twelve (12) fans with a MT 512 module.</p>
Suction Pressure Controller	SPC	MT 504	<p>The purpose of the suction pressure controller is to control the pressure of the refrigerant in the suction manifold. The controller carries out this function by comparing the pressure/temperature measured in the suction manifold to a programmed set point, and the controller starts one or more compressors based on the difference of these two values.</p> <p>The suction pressure controller can control up to ten (10) compressors.</p>
Compressor Controller	CMP	Compressor Ctrl	<p>In the refrigeration control system, there is one compressor controller for each mechanical compressor. Each compressor controller receives its start or stop command from the suction pressure controller to maintain the refrigerant temperature in the suction manifold. After receiving a start command, the compressor controller checks the compressor securities (oil pressure, compressor temperature, etc.). If conditions are normal, the compressor controller starts the compressor. If one of the security devices sends an abnormal condition signal, the compressor controller generates an alarm and stops the compressor from starting.</p>
Circuit Controller	CKT	Circuit Ctrl	<p>The refrigeration circuit controller controls the refrigeration and defrosting cycle of the refrigerated cases connected to a circuit. A refrigeration system can have up to forty (40) circuits. All refrigerated cases <i>on a circuit</i> are defrosted simultaneously according to a preprogrammed schedule. The circuit controller carries out this operation by controlling the opening and closing of the refrigeration and defrosting valves of a circuit based on a programmed defrosting schedule.</p>
Anti-Sweat Controller	ATS	AntiSweat Ctrl	<p>In a glass refrigerated case, the anti-sweat controller prevents:</p> <ul style="list-style-type: none"> • The formation of sweat on the case glass • The door to stick in the door frame. <p>The anti-sweat controller carries out this function by measuring the humidity in the store by comparing it to a set point and, based on difference between these two values, the glass and door frame of the case are heated up accordingly.</p>

2.3.3 Heating/Air-Conditioning (HVAC) Sub-System

The table below lists the various types of controllers for the HVAC sub-system, the type of modules and the main functions of each controller. Refer to the diagram illustrating the Distributed Control System for a Supermarket (Figure 2.1):

Controllers/Node	Legend	Modules	Functions
Roof-Top Controller Scheduler	RTU	MT 504 MT 508 MT 512	<p>The standard roof-top unit controller controls the main area of a supermarket, i.e.,</p> <ul style="list-style-type: none"> • controls temperature • controls humidity <p>As well, through the occupation scheduler, it lowers the temperature during unoccupied periods. The type of modules used depends on the number of cooling and heating stages of the roof-top unit.</p>
Dual Path Controller	DPU	MT 508 MT 512	<p>The Dual Path Unit is a high energy efficiency air processing unit. The Dual Path controller:</p> <ul style="list-style-type: none"> • controls the temperature of a supermarket • Effectively controls humidity (typically 40% to 45%) in the main area of a supermarket. <p>As well, through the occupation scheduler, it lowers the temperature during unoccupied periods. The type of modules used depends on the number of cooling and heating stages of the Dual Path unit.</p>
VAV Roof -Top Controller	RTU/VAV	MT 504 MT 508 MT 512	<p>A VAV roof-top unit and the VAV boxes are used in conjunction to control the temperature of the areas surrounding a supermarket. The VAV roof-top controller controls the air temperature and volume in the main conduit of the unit. The VAV roof-top unit provides constant air pressure at the input of each surrounding area. A VAV roof-top unit can power several VAV boxes.</p> <p>The type of modules used depends on the number of cooling and heating stages connected to the unit.</p>
VAV Box	VAV	VAV Ctrl	<p>The VAV box is powered by a VAV roof-top unit, which provides air volume at the input of the VAV box. The VAV box controls the temperature of the surrounding areas by varying its dampers. Therefore, the box controls the quantity of air entering the surrounding area and activates electric heating at the end line if required.</p>
HVAC Scheduler	H SCH	Scheduler	<p>The scheduler enables the creation of occupied and unoccupied schedules for increasing and decreasing the temperature of a supermarket based on the opening and closing schedule of a supermarket. In addition, schedules can also be created to control the temperatures in different zones based on the occupied and unoccupied periods. A scheduler can control several Dual Path or roof-top units.</p>

2.3.4 Lighting Sub-System

The table below lists the different types of lighting sub-system controllers, the type of modules and the main functions of each controller. Refer to the diagram illustrating the Distributed Control System for a Supermarket (Figure 2.1):

Controllers/Node	Legend	Modules	Functions
Lighting Controller	LCU	Gentec: - Input Board - Output Board - Panel Relay	<p>The indoor and outdoor lighting system of a supermarket is:</p> <ul style="list-style-type: none"> subdivided in the lighting zones each zone includes one or more illuminating lights each lighting zone is controlled by a lighting schedule originating from the lighting scheduler. <p>The lighting controller of a supermarket includes the following:</p> <ul style="list-style-type: none"> <i>an eight-switch input module.</i> Each switch can be used to override the lighting schedule of a zone in order to manually control it <i>a 16-output power module</i> that powers the 16 relays of the lighting panel <i>16-relay panel.</i> Each relay is connected to one or more illuminating lights. Lighting configuration software groups together 16 relays of the lighting panel per zone. <p>The lighting controller controls the indoor and outdoor lighting zones of a supermarket based on:</p> <ul style="list-style-type: none"> a schedule programmed in a lighting scheduler or even the combination of a schedule and outdoor photocell. <p>If the light intensity measured by the photocell sensor is higher than the programmed set point, the controller overrides the lighting schedule and cancels the lighting in one or more zones of the supermarket.</p>
Lighting Intensity Controller	DIM	DimLight	The lighting intensity controller is used with the Lighting controller and photocell sensor. It controls the lighting intensity of the lights of a zone based on the light intensity measured by the photocell sensor located in the zone.
Photocell Sensor	PTC	Douglas - Photocell Sensor	The photocell sensor is used to measure the light intensity outside a supermarket or within a zone of the supermarket. The photocell sensor signal is sent to the lighting controllers throughout the communications network.
Light Scheduler	L SCH	Scheduler	<p>The scheduler creates the lighting schedules in order to control the lighting based on the opening and closing hours of the supermarket.</p> <p>As well, the schedules can also be created to individually control the lighting in different zones based on occupied and unoccupied periods. Several schedules can be created on a single scheduler. A schedule can control one or more zones.</p>

3 MT 500 Family

3.1 MT 500 Family Input-Output Configuration

The MT 500 family is a line of electronic modules developed by Micro Thermo Technologies. The modules in the MT 500 family have a variety of input-output configurations for different supermarket applications. The table below shows the different models of the MT 500 family and their configurations.

M T 5 0 0 F a m i l y I n p u t - O u t p u t C o n f i g u r a t i o n				
	M T 5 0 0	M T 5 0 4	M T 5 0 8	M T 5 1 2
Analog Inputs	8	8	8	8
Digital Inputs			4	8
Digital Outputs		4	8	12
Analog Outputs		4	4	4

TABLE 3.1

3.2 3.2 – Table of MT Alliance Controller using the 500 Family

MT 500 Family Specifications		MT-504	MT-508	MT-512
Applications	See Section 4.0 for the different MT 504 applications	See Section 4.0 for the different MT 508 applications.	See Section 4.0 for the different MT 512 applications.	
Universal Inputs	Eight (8) universal inputs (analog or digital): 0-5 V, 0-10 V, 4-20 mA, 10 K Thermistor. Low-pass filter on each input.	Eight (8) universal inputs (analog or digital): 0-5 V, 0-10 V, 4-20 mA, 10 K Thermistor. Low-pass filter on each input.	Eight (8) universal inputs (analog or digital): 0-5 V, 0-10 V, 4-20 mA, 10 K Thermistor. Low-pass filter on each input.	
Digital Inputs	None	Four (4) digital inputs: Each input is optically isolated (0-15V)	Eight (8) digital inputs: Each input is optically isolated (0-15V)	
Digital Outputs	Four (4) type-C relays: SPDT, 2A, 250 VAC. Protected by fuses on the module	Eight (8) type-C relays: SPDT, 2A, 250 VAC. Protected by fuses on the module	Twelve (12) type-C relays: SPDT, 2A, 250 VAC. Protected by fuses on the module	

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MT 500 Family Specifications		MT-504	MT-508	MT-512
Analog Outputs	Four (4) configurable analog outputs: 0-20 mA, 0-5V, 0-10V, 2-10V. Protected by a current limiter (max 20 mA)	Four (4) configurable analog outputs: 0-20 mA, 0-5V, 0-10V, 2-10V. Protected by a limiting current limiter (max 20 mA)	Four (4) configurable analog outputs: 0-20 mA, 0-5V, 0-10V, 2-10V. Protected by a limiting current limiter (max 20 mA)	
Dimensions	8.0" x 4.0" x 1.5" 204 mm x 102 mm x 38 mm	12.25" x 4.0" x 1.5" 312 mm x 102 mm x 38 mm	16.375" x 4.0" x 1.5" 416 mm x 102 mm x 38 mm	
Set-up	Mounted on wall or on snaptrack	Mounted on wall or on snaptrack	Mounted on wall or on snaptrack	
Power	24 VAC transformer 12 VA with center tap	24 VAC transformer 12 VA with center tap	24 VAC transformer 12 VA with center tap	
Environment	-40 to 75°C (-40 to 168°F) 5% to 95% R.H.	-40 to 75°C (-40 to 168°F) 5% to 95% R.H.	-40 to 75°C (-40 to 168°F) 5% to 95% R.H.	
Certification	UL, CSA approved	UL, CSA approved	UL, CSA approved	

TABLE 3.2

4 Description and Features of Micro Thermo Controllers

The table below outlines the MT Alliance controllers used in the MT 500 line. In the table, the controllers are grouped by sub-system.

Sub-Systems & Controllers	MT 500	MT 504	MT 508	MT 512
Monitoring Sub-System				
Sensor Node	X			
Refrigeration Sub-System				
Suction Pressure Controller		X		
Condenser Controller		X	X	X
Sub-Cooling Controller			X	
Secondary Cooling System				X
Evaporative Condenser Controller			X	
HVAC Sub-System				
Standard Roof-top Controller		X	X	X
VAV Roof-top Controller		X	X	X
Dual Path Controller (1 Coil)			X	
Dual Path Controller (2 Coils)				X
Lighting Sub-System				
<i>Lighting Intensity Controller</i>		X		
Other Application Controllers				
Mechanical Room Controller			X	
X6T2P Applications Controller	X	X	X	X
X4P4T Applications Controller	X	X	X	X

Table 4.0

4.1 **Refrigeration System Controllers**

4.1.1 Condenser Controller (MT 504, MT 508 or MT 512)

Inputs	Alarm	Outputs	Control Configuration and Strategy
Analog:			
UI1 *Discharge Pressure (DP) ¹	Yes	AO1 Variable Speed Drive (VFD)	Condenser Type: Air , Evaporative (See Note) Condenser Config.: One or two rows No. of Fans: Max. 12 fans Control Point: Selection from sensors on physical and logical inputs. Operating Set Point: Pressure/Temperature depending on the sensors chosen
UI2 *Condenser Inlet Press (CIP)	Yes		Conversion Table: Pressure/Temperature conversion (depending on the type of refrigerant)
UI3 *Condenser Outlet Press (COP)	Yes		Control Strategy: Single: DP, COP, DLT, etc. Differential (floating Head): OAT & COP OAT & DLT etc.
UI4 *Drop Leg Temp (DLT)	Yes		
UI5 *Outdoor Air Temp (OAT)	Yes		
UI6 *Liq Header Press (LHP)	Yes		
IU7 *Liq Header Temp (LHP)	Yes		
UI8 Inverter Fault IIVF)	Yes		
Digital:			
None			Split Mode Control Strategy and Configuration
			Configuration: Split on outdoor temperature Split on Heat Reclaim 1 Split on Heat Reclaim 2 Split on Heat Reclaim 1 & 2 Split on Out Temp and Heat Reclaim - Split Temperature Set Point - Unsplit Discharge Press Set Point - Unsplit Discharge Press Auto Reset - Split Minimum On Time
			Set Point:
			Note: Evaporative condenser controller (MT 508) A specific plug-in is used for configuring and adjusting the set points and monitoring the evaporative condenser.

¹ All inputs tagged with an « * » in this table, and in subsequent tables (paragraphs 4.1.1 throught 4.3.2), means that the sensor signal can also originate from the LonWork network (logical connection).

Suction Pressure Controller (MT 504)

Inputs	Alarm	Outputs	Control Configuration and Strategy
Analog: UI1 *Discharge Pressure (DP) UI2 Suction Pressure (SP) UI3 Liquid Header Press (LHP) UI4 *Heat Reclaim1 (HR1) UI5 *Heat Reclaim 2 (HR2) UI6 *Phase Lost (PLM) UI7 Refrig Leak Sensor (RLS) UI8 *Suction Pressure Shift (ECE)	Yes Yes Yes Yes Yes Yes	Analog: OA1 Compressor Variable Frequency Drive (VFD)	Control Configuration and Strategies Three suction pressure controllers can be installed on the refrigeration rack to control three suction groups. A suction pressure controller (SPC) can control up to ten compressor controllers. Suction Pressure Control Strategy The suction pressure controller controls the pressure in the suction manifold. The pressure is controlled by activating one or more compressors based on the difference between the suction pressure and suction pressure set point. Type of Refrigerant: R22, etc. Control Point: Suction Pressure (U2) Control Set Point: Pressure/Temperature Control Type: PID
Logical Network Variables (SNVT) * Main Defrost Valve Logical connection to Circuit controller * Split Valve Logical connection to Condenser controller		Digital: DO1 Heat Reclaim 1 DO2 Split Valve DO3 Main Defrost DO4 Heat Reclaim 2	Floating Suction Pressure Reset Strategy Compares the coldest temperature in the refrigerated cases with the temperature case set point and automatically readjust the suction pressure. This strategy is used to save energy. Configuration Settings: No. of Defrosting Circuits: Circuit selection No. of Sensors: Max. six sensors Control Strategy: Min, Max, Med. Sampling Period: 0–60 minutes Pressure Step: 0–3 Psig (Kpa) Min. Pressure Delta: - 20 Psig (Kpa) Max. Pressure Delta: + 20 Psig (Kpa) Suction Pressure Shift Strategy: Pressure Offset: 0 – 20 Psig (Kpa) Offset Time: Programmable (0–60 Minutes)

4.1.2 Compressor Controller

Inputs	Alarm	Outputs	Control Configuration and Strategy
Analog: - None		Analog: - None	Control Configuration and Strategies Compressor controllers are controlled by the Suction pressure controller. The pressure is controlled by activating one or more compressors depending on the difference between the suction pressure and the suction pressure set point. An optional module controls the Unloaders.
Digital - Low Pressure Switch - Safety Line - Proof of Running Note: Connector on the front of the controller.	Yes Yes	Digital: Compressor Cmd Unloader 1 Unloader 2 Note: Optional electronic module is needed for the unloaders control	Compressor Controller Configuration Settings - Compressor Type: Recip, Scrool, Screw - Compressor Capacity: hp - Variable Speed Compressor: Yes - Min. Speed: 0–100% - Max. Speed: 0–100% - Option Unloader : Yes - Number of Unloaders: 1–2 - Capacity of Each Unloader: 25% or 33%

4.1.3 Refrigeration Circuit Controller

Inputs	Alarm	Outputs	Control Configuration and Strategy
Analog: - None		Analog - None	Control Configuration and Strategies The Circuit controller controls five refrigeration circuits. Up to eight (8) circuit controllers can be used on one rack. Thus, 40 refrigeration circuits can be controlled in the rack.
Logical Network Variables (SNVT) * Case Temperature * Defrost Termination * Defrost Termination Switch * Door Ajar		Digital . Defr Valve 1 . Refr Valve 1 . Defr Valve 2 . Refr Valve 2 . Defr Valve 3 . Refr Valve 3 . Defr Valve 4 . Refr Valve 4 . Defr Valve 5 . Refr Valve 5	Refrigeration Cycle Control: Mode: - Refrig. Valve on/off control - Mechanical EEPR - Electronic EEPR Control Point: Refrigerated case temperature Control Set Point: Desired case temperature Dead Band Set Point: Prevents cycling Defrosting Cycle Control: Defrosting Type: Hot Gas, Off Cycle, Electric Defrost Strategy: On Time, On Temp, Pulse No. Defrostings/Day: 1–8 Max Defrost Time: Programmable Min. Defrost Time: Programmable Circuit Load: Kilo Btu End of Defrosting Sensor: Analog or Digital No. of Sensors: Max. six sensors Defrosting Strategy: Analog: Min, Max, Med. Digital: On state Pump Down Cycle: Pump Down Time Programmable Drain Cycle: Drain Time: Programmable

4.1.4 Sub-Cooling System Controller

Inputs	Alarm	Outputs	Control Configuration and Strategy
Analog		Analog	Control Configuration and Strategies
UI1 * Mech Subcooler Temp In (LQT in) UI2 * Mech Subcooler 1 Temp Out (LQTOut 1) UI3 * Mech Subcooler 2 Temp Out(LQTOut2)	Yes Yes Yes	AO1 SPR/CTRL Valve AO2 Receiver Out Valve AO3 Mech Subcooler 1 Valve AO4 Mech Subcooler 2 Valve	The sub-cooler controller can control different sub-cooling systems: - A condenser sub-cooling system - A mechanical 1 sub-cooling system - A mechanical 2 sub-cooling system The mechanical cooling systems can control two stages.
Digital - None		Digital DO1 Drain Valve DO2 SPR/CTRL Valve DO3 Subcooler 1 Stage 1 DO4 Subcooler 1 Stage 2 DO5 Subcooler 2 Stage 1 DO6 Subcooler 2 Stage 2 DO7 Receiver Out Valve	The mechanical sub-cooling system can be configured as an autonomous refrigeration system or dedicated refrigeration circuit. Each sub-cooling sub-system (condenser, mechanical) can be configured to work autonomously or in mixed mode (condenser & mechanical). Mixed mode is very useful in hot climates.
Logical Network Variables (SNVT) - Logical connections to the condenser controller: * Condenser Saturated Temp * Drop Leg Temp * Outdoor Temp - Logical connection to the suction pressure controller: * Suction Pressure			<ul style="list-style-type: none"> - Condenser Sub-Cooling System: - SPR/CTRL Valve Control Control Point: Condenser Saturated Temp (Cop 2 Cot) – Drop Leg Temp Set Point: Desired sub-cooling Control Type: PID Analog Output: -Modulating SPR/CTRL valve - Modulating Receiver Outlet Valve Digital Output: - Selenoid SPR/CTRL valve - Receiver Outlet Valve - Drain Valve Control: Control Point: Suction pressure Set Point: Suction pressure that determines whether at least one compressor is working Control Type: On/Off control Digital Output: Drain Valve - Mechanical 1 & 2 Sub-Cooling System Configuration: - Autonomous refrigeration system - Dedicated refrigeration circuit Control Point: Mech Subcooler Temp In Set Point: Absolute temperature of liquid Control Type: PID Analog Output: Modulating valve of the mechanical sub-cooling system Digital Outputs: Stage 1 of mechanical sub-cooling system Stage 2 of mechanical sub-cooling system

4.2 HVAC Controller

4.2.1 Roof-Top Unit Controller (MT 504, MT 508 or MT 512)

Inputs	Alarm	Outputs	Control Configuration and Strategy
Analog: UI1 *Space Air Temp (SPT) UI2 Return Air Temp (RAT) UI3 Mixed Air Temp (MAT) UI4 Supply Air Temp (SAT) UI5.*Outdoor Air Temp (OAT) UI6 *Space Air Humidity (SPH) UI7 Static Diff Pressure (SDP) UI8 *Outdoor Air Humidity(AOH) Digital: DI1 Fan Status (FNS) DI2 Occupancy Timer (OCC) DI3 Air Filters (OAF) DI4 Safety Line Switch (SLS)	Yes	MT 504: 4 digital outputs 4 analog outputs MT 508: 8 digital outputs 4 analog outputs MT 512: 12 digital outputs 4 analog outputs Digital and analog outputs can be configured. The maximum limits set for the outputs are: Analog output: Modulating heating Modulating cooling Modulating Heat Reclaim Outdoor air inlet damper Bypass damper Digital output: 1 fan motor 6 cooling stages 6 heating stages 3 Heat Reclaim stages	Control Configuration and Strategies - Fan Motor Control: Modes: On, Off, Auto, Occupy/On Unoccupy/Auto - Outdoor Air Inlet Damper Control: Control: On/Off Modes: - Occupy Mode Open at %, - Unoccupy Mode Close at %) - Modulating (Free cooling) Control Point: Outdoor temperature (Free cooling) - Bypass Damper Control: Control Type: Modulating Control Point: Static pressure in conduit Set Point: Desired static pressure - Air-Conditioning Control: Control Type: Modulating/ Stage (6 Maximum) Control Point: Indoor temperature Set Point: Cooling temperature set point in occupied/unoccupied mode - Heating Control Via Heat Reclaim: Control Type: Modulating/Stage (3 Maximum) Control Point: Indoor temperature Set Point: Desired indoor temperature - Auxiliary Heating Control: Control Type: Modulating/Stage (6 Maximum) Control Point: Indoor temperature Set Point: Heating temperature set point in occupied or unoccupied mode - Humidity Control - Modes: Off, Humidification, Dehumid, Auto - Humidification: Modulating control Control Point Space Humidity/Saturation point Set Point: Humidity/Saturation point. - Dehumidification: Stage control (6 cooling stages max.) Control Point Humidity/Saturation point Set Point: Humidity/Saturation point. - Auto: Humidification/Dehumidification Dead Band: Humidity & Dehumid dead band Set Point: Humidity or saturation point shifted by the dead band Load Shedding Control: With a load shedding request (Logical network variable). The following elements can be load shedded: - Fan motor - Cooling, heat reclaim and heating stages - Auxiliary modulating heating and heat reacclaim - Outdoor air inlet and bypass damper

4.2.2 VAV Roof-Top Unit Controller (MT 504, MT 508 or MT 512)

Inputs	Alarm	Outputs	Control Configuration and Strategy
Analog: UI1 Return Air Temp (RAT) UI2 Mixed Air Temp (MAT) UI3 Supply Air Temp (SAT) UI4 Return Air Pressure (RAP) UI5 Return Air Humidity (RAH) UI6 Mixed Air Filter (MAF) UI7 *Outdoor Air Temp (OAT) UI8 Supply Air Pressure (SAP)	Yes	MT 504: 4 digital outputs 4 analog outputs MT 508: 8 digital outputs 4 analog outputs MT 512: 12 digital outputs 4 analog outputs Digital and analog outputs can be configured. The maximum limits set on the outputs are: Analog: Bypass damper Outdoor air damper Modulating heating Modulating cooling Modulating humidifier Modulating fan Digital: 1 fan motor 6 cooling stages 6 heating stages	Control Configuration and Strategy - Fan Motor Control: Modes: On, Off, Auto, Occupy/On Unoccupy/Auto - Outdoor air inlet damper control: Control: On/Off Modes: - Occupy Mode Open at %, - Unoccupy Mode Closed at % - Modulating (free cooling) Control Point: Outdoor temperature (free cooling) - Humidity Control: Modes: Off, Humid., Dehumid, Auto - Humidification : Modulating control Control Point: Humidity/Saturation point in the return air Set Point: Humidity/Saturation point. - Dehumidification: Stage control (6 cooling Stages max.) Control Point: Humidity/Saturation point in the return air Set Point: Humidity/Saturation point. - Auto: Dead Band: Humidity & Dehumid dead band Set Point: Humidity or saturation point shifted by the dead band - Supply Air Pressure Control: - Modes: Bypass damper or Fan speed control - Control Point: Supply air pressure - Set Point: Desired supply air pressure - Modulating Out : Bypass damper or Fan speed control - Supply Air Temperature Control: - Mode: - Outside Temp. - Return Temp - VAV box request - Control Type: Modulating or stages - Control Point: Supply air temperature - Set Point: Depends on mode: - Supply temp. readjust by outside temperature - Supply temp. readjust by return temperature - Supply temp. readjust by VAV box request Load Shedding Control: With a load shedding request (Network variable), the following items can be load shedded: - Fan motor - Cooling, heat reclaim and heating stages - Auxiliary modulating heat reclaim and heating - Outdoor air intake damper - Bypass damper
Digital: DI1 Fan Status (FNS) DI2 Occupancy Timer (OCC)	Yes		

4.2.3 Dual Path (MT 508) Controller

Inputs	Alarm	Outputs	Control Configuration and Strategy
Analog: UI1*Space Air Temp (SPT) UI2 Return Air Temp (RAT) UI3 DX Coil Temp (DXT) UI4 Supply Air Temp (SAT) UI5 *Outdoor Air Temp (OAT) UI6 *Space Air Humidity (SPH) UI7 Liquid Saturated Temp(LST) UI8 *DX Coil Diff Press (DXDP)	Yes Yes Yes Yes Yes Yes Yes	MT 504: 4 digital outputs 4 analog outputs MT 508: 8 digital outputs 4 analog outputs MT 512: 12 digital outputs 4 analog outputs Digital and analog outputs can be configured. The maximum limits set on the outputs are: Analog Outside damper Bypass damper Return damper Modulating heating Digital 1 Fan motor 6 cooling stages 6 heating stages 3 reclaim stages	Control Configuration and Strategy - Fan Motor Control: Modes: On, Off, Auto, Occupy/On , Unoccupy/Auto Speed: Low, High, High/Occ & Auto/Unocc, Continuous + Off on Drip Time - Damper Control: Adjustments made by balancing technicians - Mode: OAD BAD RAD - Unoccupied % % % - Occupied % % % - Emergency Cooling % % % - Winter Occupation Mode % % % - Cooling Control: - Control: Stage (6 maximum) - Control Point: Indoor temperature - Set Point: Cooling temperature set point, occupied/unoccupied mode - Heat Reclaim Control: - Control: Stage (3 maximum) - Control Point: Indoor temperature - Set Point: Desired indoor temperature - Heating Control: - Control: Modulating - Control Point: Indoor temperature - Set Point: Heating temperature set point in occupied/unoccupied mode - Dew Point Control: - Control: Stage (6 maximum) - Control Point: Indoor temp. & humidity - Set Point: Desired dew point - Load Shedding Control: With an load shedder request (network variable), the following items can be load shedded: - Fan motor - Cooling and reclaim stages - Modulating heating - Outdoor air inlet damper - Bypass damper - Return damper
DI1 Fan Status (FNS) DI2 Occupancy Timer (OCC) DI3 Return Air Filter (RAF) DI4 Outside Air Filter (OAF)	Yes Yes Yes Yes		

4.3 Lighting Controllers

4.3.1 Relay Lighting Controller

Inputs	Alarm	Outputs	Control Configuration and Strategy
Logical Network Variables (SNVT) Analog: *Lux Level Sensor Digital: - Groups 1 to 6: (Zone) * Occupancy Sensor * Group Override Switch * Occupancy Schedule		Digital: 16 pulsed relays Analog: - None	Control Configuration and Strategy By configuring the 16 lighting relays in six different groups, relay lighting controller can control six lighting zones. <ul style="list-style-type: none"> - Configuration of groups of relays 1 to 6 - Used to assign a relay to a group. - For each group. If the light operation time equalization option is activated, the relays for a group may be assigned to one of the two sub-groups to equalize the light operation time of the sub-groups. <ul style="list-style-type: none"> - Control of Groups 1-6: <ul style="list-style-type: none"> - <i>Light Operation Time Equalization Control for a Group</i> Alternates between the sub-groups of a lighting group in order to equalize the light operation time - <i>Lighting Control Logic :</i> <ul style="list-style-type: none"> - Schedule Only - Logical function AND between photocell sensor and schedule - Logical function OR between photocell sensor and schedule - Motion Detector Control The motion detector can override the lighting schedule for a given period of time. The period of time is programmable. - Override Control: Override command from a switch, which temporarily activates a lighting group. The activation time is programmable. <ul style="list-style-type: none"> - Day/Night Control Specifies day/night status - Control: On/Off - Control Point: Intensity sensor (Lux) - Day/Night Set Point: Value of day/night set point - Set Point Dead Band: Prevents cycling - Day/Night Time: Programmable <ul style="list-style-type: none"> - load Shedding Control: <ul style="list-style-type: none"> - <i>Configuration:</i> A load shedding level from 1 to 4 can be assigned to each lighting relay. Therefore, each relay belongs to a group of load shedding levels 1-4. - <i>Control:</i> An external load shedding command (Levels 1-4) Load shed a specific group.

4.3.2 DimLight Controller (MT 504)

Inputs	Alarm	Outputs	Control Configuration and Strategy
<p>Analog</p> <p>Zone 1:</p> <p>UI1 Light Level Sensor 1 UI2 Light Level Sensor 2 UI3 Light Level Sensor 3 UI4 Local Override Switch</p> <p>Zone 2:</p> <p>UI5 Light Level Sensor 1 UI6 Light Level Sensor 2 UI7 Light Level Sensor 3 UI8 Local Override Switch</p> <p>Network Logical Variables (SNVT)</p> <p>* DimLight 1 Command * DimLight 2 Command</p> <p>Note: Commands that can control intensity (Low, Med and High) of the Dimlight lighting. These commands come from the Light Scheduler Controller.</p> <p>* Zone 1 Remote Override * Zone 2 Remote Override</p> <p>Note: Override commands have higher priority than the lighting schedule</p> <p>* Relay Command 1 * Relay Command 2 * Relay Command 3 * Relay Command 4</p> <p>Note: Commands that individually activate the relays on outputs DO1- DO4</p>	<p>Yes Yes Yes Yes Yes Yes Yes</p>	<p>Analog:</p> <p>AO1 Dim Control 1 AO2 Dim Control 2 (For HID Offload Ctrl)—</p> <p>Digital</p> <p>DO1 Relay out 1 DO2 Relay out 2 DO3 Relay out 3 DO4 Relay out 4</p> <p>Note: Reserve relays activated by the Relay Command 1-4 commands</p>	<p>Control Configuration and Strategy</p> <p>The Dimlight controller takes into account the day's lighting when controlling the lighting intensity of the main area of a supermarket. Intensity is controlled by the modulating the HID lights ballast. The Dimlight controller can control two zones.</p> <p>The Dimlight controller uses the relay lighting controller, which:</p> <ul style="list-style-type: none"> - Configures the lighting groups (zones) - Controls lighting schedules - Carries out overrides of lighting schedules <p>- Lighting Set Point Zone Control with DimLight</p> <p>Control Point: Analog photocell sensors (Light Level Sensor 1-3)</p> <p>Strategy: Minimum, Maximum, Medium</p> <p>Set Point:</p> <ul style="list-style-type: none"> - Low Set Point: For the Low Dimlight command - Med Set Point: For the Med. Dimlight command - High Set Point: For the High Dimlight command <p>The commands are from the Scheduler Controller</p> <p>Control Type PID</p> <p>Analog Output: Dimmer Control 1- 2</p> <p>- Override Commands:</p> <p>Mode: Local/Remote</p> <p>Value: Intensity can be programmed</p> <p>Time: Time can be programmed</p> <p>- Load Shedding Control:</p> <p>A Load Shedding command (logical network variable) in % used by Dimlight to reduce the lighting intensity to a given value</p>

Appendices

1 Introduction to Supermarket Refrigeration Systems

1.1 Purpose of a Supermarket Refrigeration System

A supermarket refrigeration system has two main functions:

- to refrigerate cold storage rooms used to store products before they are transferred to the refrigerated cases;
- to maintain an optimal temperature in cold storage rooms and refrigerated cases in order to conserve products.

The storage temperature of products in the cold storage rooms and refrigerated cases varies according to the type of product. The table below lists several products and their conservation temperature range.

Types of Products	Temperature (°C)	Temperature (°F)	Case Types
Vegetables, fruits, flowers	2°C and higher	35°F and higher	
Meat, seafood	-1.1°C to 0.0°C	30°F to 32°F	
Dairy products, beer, soft drinks	1.1°C to 2.2°C	34°F to 36°F	
Food preparation room	4.4°C to 7.2°C	40°F to 45°F	
Deep-frozen products	-31.7°C to -26.1°C	-25°F to -15°F	
Ice cream, frozen food	-37.2°C to -31.7°C	-35°F to -25°F	Low temperature

1.2 Operation and Type of Refrigerated Cases

The main function of refrigerated cases is to display products so that clients can easily access them. A typical supermarket has 70 to 90 refrigerated cases. Refrigerated cases are selected based on the following criteria:

- ability to conserve products during their life
- ability to showcase product quality to increase sales

In general, there are several types of refrigerated cases:

- refrigerated cases equipped with glass doors
- well-type refrigerated cases
- multideck refrigerated cases
- refrigerated display cases: seafood/delicatessen meats/ready-made meals

The low-temperature and very-low-temperature refrigerated cases must be defrosted on a regular basis to remove frost that has accumulated on the evaporator as a result of the humidity in the supermarket. Defrosting can be carried out in different ways:

- Cold liquid refrigerant circulation is stopped in the evaporator and the electrical heater that heats the evaporator starts up
- Cold liquid refrigerant circulation is stopped in the evaporator and hot gas is circulated in the evaporator
- in certain cases, cold liquid refrigerant circulation is simply stopped and the ambient air defrosts the evaporator

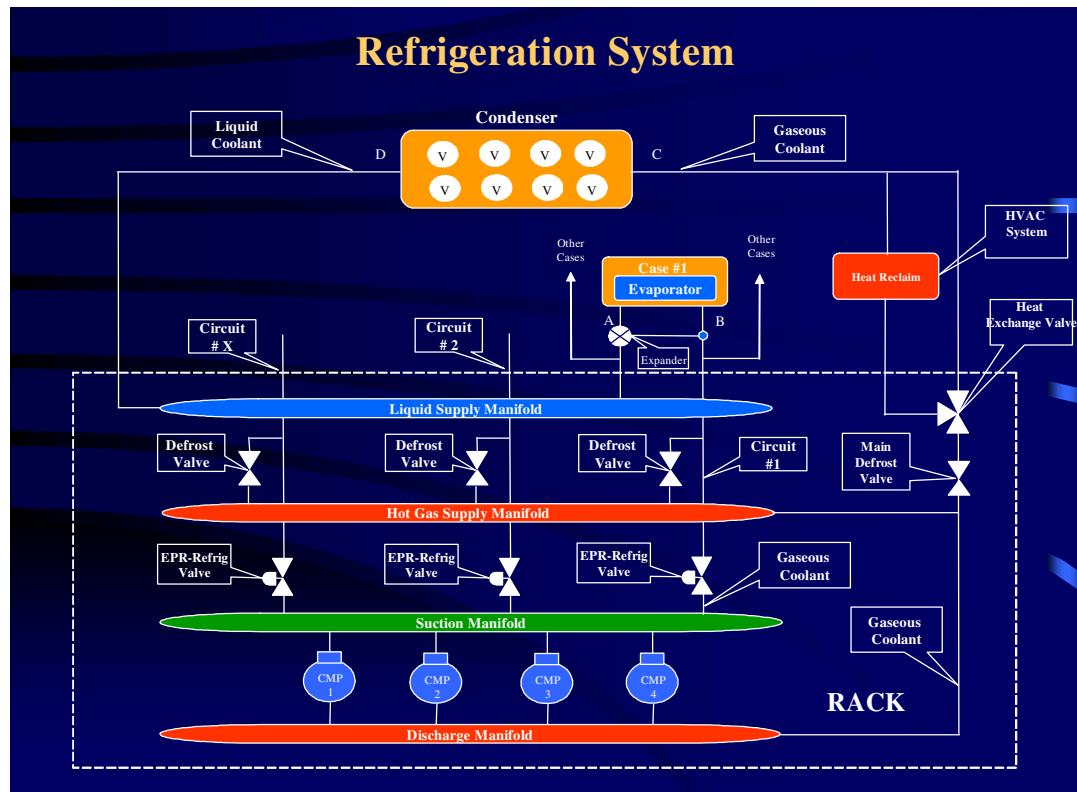


FIGURE 1.1

1.3 Thermodynamic Principles of Refrigeration

The operating cycle for a refrigeration system is based on the two following physics principles:

1. *Heat transfer* always occurs from a hot area to a colder area.
2. If the *pressure* in a refrigerant increases, its *temperature* will also increase. (saturated range)

1.4 Refrigeration System Components and Functions

In the figure above, the components inside the dashed box represent the components of a refrigeration rack. Refrigeration racks are normally located in the mechanical room behind the supermarket. The cold liquid refrigerant of the refrigeration rack is fed to the refrigerated cases in the main area of the supermarket by the conduits called *circuits*. In general, a supermarket has two refrigeration racks. Each rack can feed up to **40 refrigeration circuits**: there are **one to ten refrigerated cases per circuit**.

The operating temperature of each refrigeration rack depends on the type of products that are to be stored in the refrigerated cases. The operating temperature of a rack depends on the pressure/temperature of the refrigerant in the suction manifold. In general, the racks are classified as follows:

Name of Rack	Temperature (°C) Suction Manifold	Temperature (°F) Suction Manifold
Low temperature	-37.2°C to -3.9°C	-35°F to 25°F
Average temperature	-34.4°C to -9.4°C	-30°F to 15°F

The table below describes the components of a *refrigeration rack* and their functions:

Components	Numbers	Functions
Compressors (CMP)	2 to 10/Rack	The compressors (CMP) are at the heart of a refrigeration system: They help circulate the refrigerant throughout the system. They increase the pressure/temperature of the gaseous refrigerant at the condenser inlet. The number and power rating of compressors in a refrigeration system depend on the refrigeration system load, i.e., the number of refrigerated cases connected to the system.
Condenser	1/Rack	The condenser is located on the supermarket roof. It transfers to the ambient air the heat absorbed by the refrigerant during its passage in the evaporators of the refrigerated cases. This heat transfer process is based on the fact that the temperature of the gaseous refrigerant at the condenser input is at a higher temperature than the ambient temperature. (Principe 1). In addition, during this process, the gaseous refrigerant at the condenser input is transformed into liquid refrigerant at the condenser output.
Circuits	10 to 40 / Rack	Conduits between the mechanical room and the main area of a supermarket, which are used to transport: <ul style="list-style-type: none"> • Cold liquid refrigerant during the refrigeration cycle. • Hot gas during the defrosting cycle.

Components	Numbers	Functions
Defrost Valve	1/Circuit	<p>During the defrosting cycle:</p> <ul style="list-style-type: none"> • The defrost valve is open and allows hot gas from the hot gas supply manifold flow into the circuit to defrost the refrigerated cases. • The refrigeration valve is closed. <p>The frequency for defrosting a circuit is based on a programmed schedule. The defrosting schedule is programmed so that one or two circuits are defrosted simultaneously depending on the load of each circuit (number of refrigerated cases on the circuit and their temperature).</p>
Refrigeration Valve	1/Circuit	<p>During the refrigeration cycle:</p> <ul style="list-style-type: none"> • The refrigeration valve is open and lets cold liquid circulate in cases connected to the circuit. • The defrost valve is closed.
EPR Valve	1/Circuit	The EPR valve is used to adjust the refrigerated cases temperature (evaporators) connected to a circuit.
Main Defrost Valve	1/Rack	The main defrost valve is opened during hot gas defrosting in one of the circuits. Opening the valve creates differential pressure, which lets hot gas circulate in the defrost circuit(s).
Heat Reclaim Valve	1/Rack	When this valve has been activated, the warm gas from the discharge flows through the heat reclaim system located in the main conduit of the HVAC system. This heats the air circulating in the main conduit of the HVAC system. This valve is activated following a heating or dehumidifier request from the HVAC control system.
Suction Manifold	1/Rack	During the refrigeration cycle, the suction manifold receives, via each circuit, the gaseous refrigerant from the refrigerated cases. The suction manifold is used to supply the compressors with refrigerant.
Discharge Manifold	1/Rack	The discharge manifold is connected to the compressor discharge. The compressors compress the gas refrigerant in the discharge manifold at a very high pressure/temperature.
Liquid Supply Manifold	1/Rack	The liquid supply manifold receives the liquid refrigerant from the condenser. The liquid supply manifold is used to supply the refrigerated cases by cooling the liquid in order to lower the temperatures of the refrigerated cases.
Hot Gas Manifold	1/Rack	The hot gas manifold is fed by the compressor discharge manifold. During a defrosting cycle, the defrost valve is open and supplies the defrost circuit with hot gas to defrost the refrigerated cases.

Components	Numbers	Functions
Evaporator	1 to 3/case	The evaporator is used to cool the refrigerated case. During the refrigeration cycle, the cold liquid refrigerant runs through the evaporator that absorbs the heat from the case and cools the refrigerated case. During this process, the liquid refrigerant is transformed into gas refrigerant as it absorbs heat.
Thermostatic Expansion Valve	1 to 3/case	This valve has three functions: Firstly, and most importantly, it lowers pressure (thus temperature) of the liquid refrigerant from the liquid supply manifold, to provide very cold liquid refrigerant to the evaporator (Principle 1). Secondly, it controls the flow of refrigerant into the case, according to the load demand from the case (products removed and added, etc.). Thirdly, the valve controls the superheat to prevent liquid refrigerant at the inlet of the compressors, thus preventing physical damage of the compressors.
Fan-Evaporator	1 to 3/case	The fan/evaporator circulates cold air over the products as well as creates an air curtain that separates the products from the warmer ambient air in the supermarket.

1.5 Refrigeration Cycle

The refrigeration cycle is described in the refrigeration system diagram above. The main components of the refrigeration cycle are the compressor, condenser, thermostatic expansion valve and evaporator. The refrigeration cycle is described in points A, B, C and D in the Refrigeration System diagram.

Point A: Since the thermostatic expansion valve lowers the pressure/temperature of the liquid refrigerant (Principle 2), the liquid refrigerant in Point A is very cold. As the liquid refrigerant flows through the evaporator, it absorbs the heat from the refrigerated case and cools the refrigerated case.

Point B: By absorbing the heat from refrigerated case, the liquid refrigerant passes to a gaseous state at the evaporator outlet. The temperature differential (Superheat) between the inlet and outlet of the evaporator is controlled by the thermostatic expansion valve. This valve maintains this temperature differential by varying the flow rate of the refrigerant into the evaporator based on the refrigerated case load (quantity and temperature of the products in the case). During the refrigeration cycle, the refrigeration valve on the circuit is open and the refrigerant is passed to the suction manifold and compressors.

Point C: When the gaseous refrigerant moves to the compressors, the pressure/temperature of refrigerant is increased, and the gaseous refrigerant temperature in the discharge manifold and at the inlet of the condenser becomes very high.

Point D: Since the gaseous refrigerant temperature in the condenser is higher than the temperature of the outdoor ambient air, there is a heat exchange between the gaseous refrigerant and the ambient air (Principle 1). In turn, the heat absorbed by the refrigerant (heat from the refrigerated case) is released into the ambient air when it moves to the condenser. As well, this heat exchange liquefies the refrigerant in the condenser. Therefore, the refrigerant in Point D is in a liquid state. The liquid

refrigerant at the outlet of the condenser is passed to the liquid supply manifold and to the thermostatic expansion valve and the refrigeration cycle starts all over again.

1.6 Defrosting Cycle

During the defrosting cycle, a circuit defrost valve is open and the circuit's EPR-Refrigeration valve is closed. The hot gas refrigerant in the defrost supply manifold from the compressor defrost manifold is circulated into the refrigerated case evaporators of the defrost circuit; this operation defrosts the evaporators. Since the evaporators are very cold, the gaseous refrigerant becomes liquid and sent to the liquid supply manifold.

1.7 Heat Reclaim Exchanger

The heat reclaim unit is located in the main conduit of the HVAC system. Following a heat or dehumidification request, a signal is sent from the HVAC controller to the Suction pressure controller. The Suction pressure controller opens the heat reclaim valve, enabling the hot gas refrigerant in the discharge manifold to pass through the heat reclaim valve. This, in turn, heats the air circulating in the main conduit of the HVAC system.

2 Introduction to the Supermarket HVAC System

2.1 Purpose of the HVAC System

A supermarket HVAC system has two main functions:

- To control the temperature in the main and peripheral zones so that customers and staff are comfortable
- To control the humidity in the main area of the supermarket

Temperature and humidity in the *main area of a supermarket* are controlled by different means in different supermarkets:

- A big Air Handler Unit (AHU)
- One or more standard roof-top units (RTU)
- A Dual Path unit (DPU)

Temperature and humidity in the *peripheral zones of a supermarket* is controlled in different ways:

- One or more standard roof-top units with supply conduits for the different zones; or
- A VAV roof-top unit and VAV boxes for the peripheral zones

The roof-top unit will be used to describe how the HVAC system works:

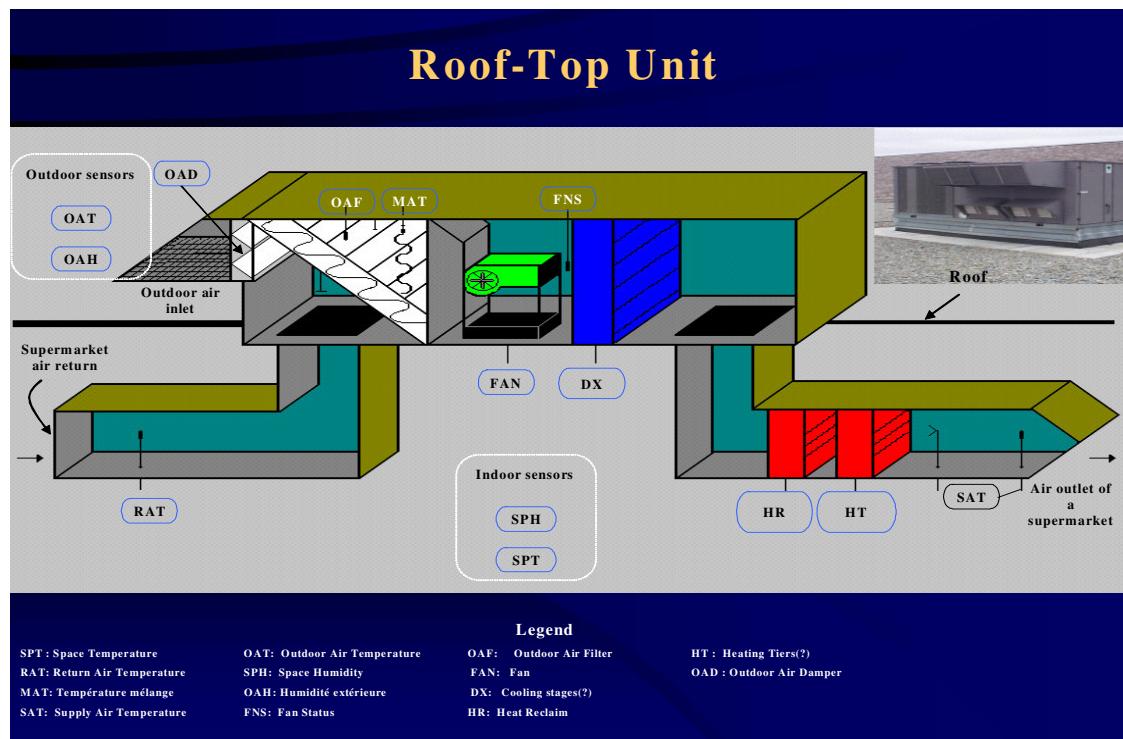


FIGURE 2.1 Appendix

2.2 Mechanical Components of Roof-Top Units

2.2.1 The table below describes the mechanical components for a roof-top unit and their functions:

Components	Legend	Number/Unit	Functions
Outdoor Air Damper	OAD	1	This damper lets fresh air enter the unit in order to improve the air quality in the supermarket. This damper is open during the day and closed at night.
Mechanical Air Filter	OAF	1	This filter traps dust from the outdoor air and return air of the supermarket. A pressure differential detector installed the filter terminals detects whether the filter must be replaced.
Fan	FAN	1	The fan circulates air through the air treatment units: cooling unit, heat reclaim unit and the heating coil.
Cooling Unit	DX	1 to 6	The cooling unit (refrigeration system evaporator) has one or more stages depending on the cooling load.
Heat Reclaim Unit	HR	1 to 3	The heat reclaim unit recovers the heat from the refrigeration system. Instead of the condenser releasing heat to the outside, this heat is recovered in the heat reclaim unit to heat the supermarket.
Heating Unit	HT	1 to 6	The heating unit has one or more stages depending on the heating load. The heating unit can be gas or electric.

2.3 Electronic Components (Sensors) of Roof-Top Units

2.3.1 The table below describes the electronic components for a roof-top unit and their functions:

Components	Legend	Number/Unit	Functions
Outside Air Temperature Sensor	OAT	1	This sensor is used to measure the outdoor air temperature.
Outside Air Humidity Sensor	OAH	1	This sensor is used to measure the humidity of the outdoor air.
Space Air Temperature Sensor	SPT	1	This sensor is used to measure the temperature of the indoor air.
Space Air Humidity Sensor	SPH	1	This sensor is used to measure the humidity of the indoor air.
Return Air Temperature Sensor	RAT	1	This sensor is used to measure the return air temperature originating from the supermarket.
Mixed Air Temperature Sensor	MAT	1	This sensor is used to measure the mixed air temperature (return air and outdoor air).
Supply Air Temperature Sensor	SAT	1	This sensor is used to measure the temperature of the supply air at the unit outlet. This air is sent to the supermarket by the conduits.
Differential Pressure Sensor	OAF	1	This sensor is used to measure the differential pressure to the mechanical filter terminals. It determines whether the filter must be replaced.
Fan Status	FNS	1	This digital sensor is used to measure the air flow. It is used to show the fan is working.

2.4 Heating Cycle

Before activating the heating cycles of the RTU, the controller must verify that:

- The fan is working by checking the air flow sensor in the RTU;
- The alarms conditions are cleared, i.e. smoke detector, fire detector, etc., are not active.

If the above conditions are met, then the controller compares the temperature measured by the room temperature sensor against the setpoint defined in the RTU system:

- If the measured temperature is lower than the heating setpoint, then the controller activates the heat reclaim stage (the heat reclaim unit is part of the RTU, but it is connected to the refrigeration system of the store. It is

considered as a “free heating stage”). If the difference between the zone temperature and the setpoint is still high, and if it is impossible to reach the setpoint value with the heat reclaim stage only, then the controller will gradually activate one or more heating stages (electrical or gas) until the setpoint is reached;

- If the measured temperature is greater than the heating setpoint, then the controller will gradually shutdown the electrical (or gas) heating stages until the setpoint is reached. If the room temperature is still too high, the controller will shutdown the heat reclaim unit.

2.5 Dehumidification Cycle

The humidity in the main area of a supermarket is a major concern. If the humidity in the building is not controlled efficiently, frost will build up on the refrigerated food display cases’ evaporators, thus resulting in an increase of the frequency of the defrost cycles. This leads to disastrous effects:

- Increase of energy consumption;
- Deterioration of food quality in the refrigerated cases.

Before the dehumidifier cycle is activated, the controller must verify that:

- The fan is on by checking the air flow sensor in the RTU;
- All alarms conditions are cleared, i.e. excessively low temperature in the cooling coil, fire detector, etc., are not active.

If the above conditions are met, then the controller compares the humidity measured by the room temperature sensor against the setpoint defined in the RTU system:

- If the measured humidity is higher than the humidity setpoint, then the controller activates the first stage of cooling. If the difference between the measured humidity and the setpoint is still high, and if it is impossible to reach the setpoint value with the first stage of cooling only, then the controller will gradually activate one or more cooling stages until the setpoint is reached. During this cycle, the water contained in the air will condense at the contact of the cooling coils and will be recuperated in a drain pan²;
- If the measured humidity is lower than the humidity setpoint, then the controller will gradually shutdown the cooling stages until the setpoint is reached.

² The dehumidification cycle cools the air in the main area of the supermarket and could cause discomfort to customers. Therefore, as soon as the measured temperature goes below the temperature setpoint, the controller activates the heat reclaim stage to compensate. Other heating stages can be activated as well, as described in section **Error! Reference source not found. Error! Reference source not found.**, on page **Error! Bookmark not defined.**. The dehumidification cycle and the heating cycle are independent from one to the other.

2.6 Air-Conditioning Cycle

The peripheral zones of a supermarket (offices, rest areas, bathrooms, etc.) could be, from time to time, air conditioned for the employees comfort.

Before the cooling cycle is activated, the controller must verify that:

- The fan is on by checking the air flow sensor in the RTU;
- All alarms conditions are cleared, i.e. excessively low temperature in the cooling coil, fire detector, etc., are not active.

If the above conditions are met, then the controller compares the temperature measured by the room temperature sensor against the setpoint defined in the RTU system:

- If the measured temperature is greater than the cooling setpoint, then the controller activates the first stage of cooling. If the difference between the measured temperature and the setpoint is still high, and if it is impossible to reach the setpoint value with the first stage of cooling only, then the controller will gradually activate one or more cooling stages until the setpoint is reached;
- If the measured temperature is lower than the cooling setpoint, then the controller will gradually shutdown the cooling stages until the setpoint is reached.

3 Introduction to the Lighting System

3.1 Description of a Lighting Control System

Figure C.1 illustrates the main components of a supermarket lighting system.

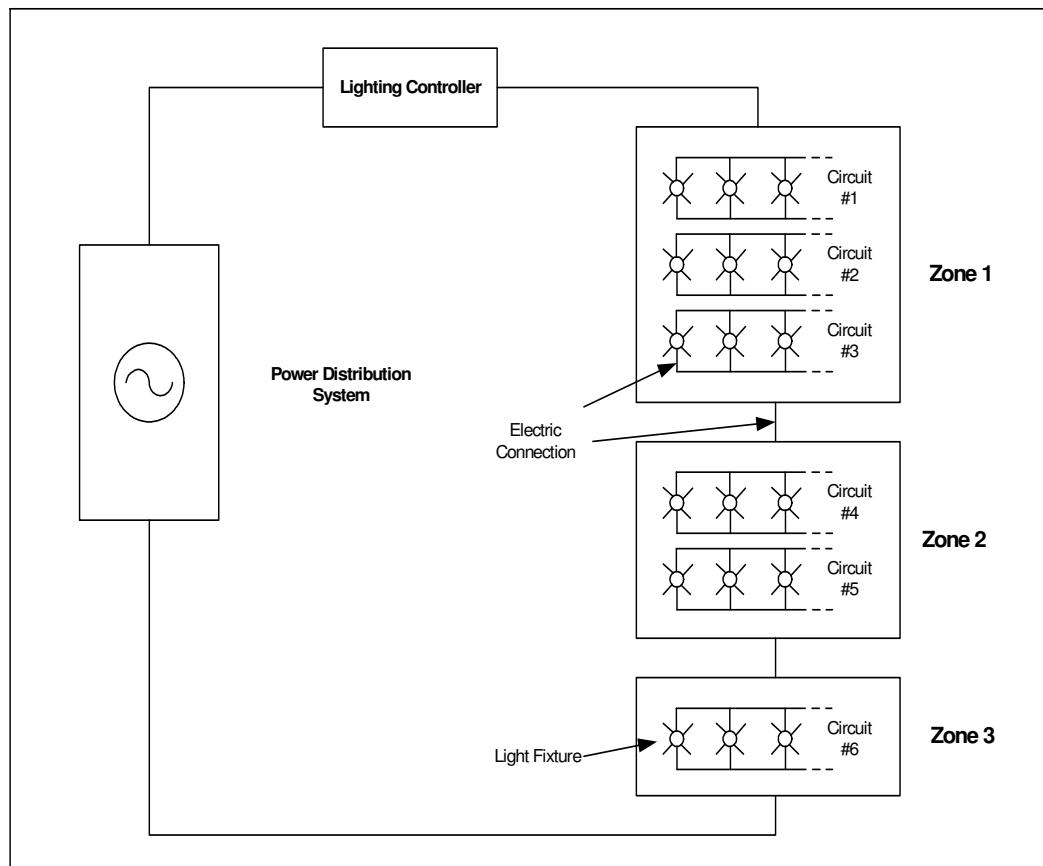


Figure C.1 – Lighting System of a Supermarket

In a supermarket, the lighting system is made up of light fixtures organized into lighting zones. All lighting circuits are connected to a lighting controller. The following sections provide more detail about the lighting zones and lighting system components of a supermarket.

C.2 – Lighting Zones

The outdoor and indoor areas of a supermarket are divided into lighting zones. A zone can be delimited by an environment or physical area or even by a logical group (decorative lighting). A lighting zone can be manually or automatically controlled.

The table below describes the different zones that are found in a supermarket. Certain zones can be subdivided into sub-zones (last column), thus providing management and system setting flexibility.

Location	Lighting Zone	Sub-Zone
Outdoor	Parking lot	Yes
	Signs	
	Traffic lanes	
	Unloading zone	
Indoor	Sales area	Yes: aisles, entranceway, cashier area
	Refrigerated cases	Yes: Based on different products
	Decorative lighting	Yes: Based on product groups
	Service area	Yes: Based on peripheral services
	Emergency lighting	
	Office area	Yes
	Mechanical room	
	Storage area	

Table C.2 – Lighting Zones of a Supermarket

A compromise must be made between the size of a lighting zone and the cost of a lighting system. Small lighting zones are more expensive (equipment and installation costs), but offer more flexibility and greater potential for reducing system operating costs.

C.3 – Components of the Lighting System

The main component of a lighting system is *the light fixture*. A light fixture is a lighting unit made up of a light source and parts for distributing light, physically supporting the light source and electrically connecting the light source. A light fixture is made up of the following parts:

- **Light source:** Produces the light
- **Socket tube:** Holds the light source in the housing and electrically connects the light source
- **Ballast:** Device to operate a fluorescent light or high intensity discharge (HID) light. It provides starting voltage while stabilizing the current during operation. There are two types of offloads: magnetic ballasts and electronic ballasts
- **Reflector:** Reflects the light
- **Lens:** Made of a transparent material and used to converge the light
- **Housing:** Mechanical support that holds together all parts of the light fixture

C.3.1 – Lights

Different types of lights are available, each having their own specific characteristics. The following characteristics are used for describing a light:

Mean Life: A measurement used to compare the average life of a light source. It is expressed in hours.

Efficiency: A measurement used to compare the relationship between the light flux issued and energy consumed. It is expressed in lumens per watt.

Color Index: A scale that measures the color produced on an object by a reference light source. This scale is measured in percentage. A low color index means the color of objects is not natural.

Visual Comfort Probability: Visual comfort probability specifies the percentage of people who are comfortable with the lighting in a given space. A comfort probability of at least 70% is recommended for inside commercial environments.

Supermarkets use three types of light sources: incandescent, fluorescent and HID. Table C.3.1 describes the main characteristics of each of these types of light sources.

Types	Sub-Types	Characteristics
Incandescent	Standard	<ul style="list-style-type: none">• Low efficiency: 6 to 24 lumens• Short life: 750 –2500 hours• Applications: General
	Tungsten-Halogen	<ul style="list-style-type: none">• More efficient than standard light sources• Longer life than standard light sources• Light beam is more concentrated or focused• Less degradation in efficiency per time unit than the incandescent light sources• Light more natural than standard light sources• Applications: Display, strong lighting
Fluorescent		<ul style="list-style-type: none">• High efficiency• Good lighting distribution and diffusion• Long life• Applications: Commonly used commercially

Types	Sub-Types	Characteristics
High intensity discharge (HID) light	Mercury vapor	<ul style="list-style-type: none"> • The least effective of all HID lights • Quick degradation in efficiency • Very weak color index • Long life: 24,000+ hours • Blue-green light • Applications: Landscaping lighting
	Halide lights	<ul style="list-style-type: none"> • Wide range of wattage ratings: 32 –2000 watts • Efficiency: 50 to 115 lumens per watt • Good color index • Life: <ul style="list-style-type: none"> • Low power: 7,500 hours • High power: 15,000 – 20,000 hours • Applications : <ul style="list-style-type: none"> • Indoor: Arena, stadium, auditorium, etc. • Outdoor: Parking
	High-pressure sodium	<ul style="list-style-type: none"> • More efficient than halide lights • Low color index • Gold colored light • Applications: Industrial and outdoors
	Low-pressure sodium	<ul style="list-style-type: none"> • Best efficiency of all HID light sources • Low color index • Monochrome color • Applications: <ul style="list-style-type: none"> • Outdoor: Security and street lighting • Indoor: When color is not important

In general, these three types of light sources are used in supermarkets:

- Incandescent lights are used in specific zones, such as cases for meat and bread, to create warm colors
- Halogen lights are limited to decorative lighting
- Fluorescent lights are especially used for general lighting: sales areas, offices, passageways. They are also used for specific applications: freezer cases, fruits and vegetables cases.
- HID lights are used for large surfaces: sales areas, parking areas, unloading areas, etc.

The type and number of light fixtures in a supermarket are selected at the corporate level and the selection criteria are based on architectural appearance and marketing to showcase products in order to increase sales. In practice, saving energy is not a priority.

3.2 Configuring Lighting Controls

A typical lighting control includes a lighting controller, which controls lighting based on a typical strategy. The inputs receive signals from the occupation sensors and those of photocell sensors to detect daylight. The controller activates low-voltage relays, which are used to activate the electric load. Relays can be directly connected to the light fixtures or even connected to the lighting contact switches. The contact switches are used to activate major lighting loads. The panel breaker isolates the control circuits of the lighting circuits in order to protect against overloads and electric surges.

There are two types of lighting system configurations, which are chosen based on the lighting zones:

- Lighting control system with relays and contactors
- Lighting control system with low-voltage relays

Figures C.4.1 and C.4.2 illustrate each configuration based on the small lighting system comprising six lighting circuits divided between three zones.

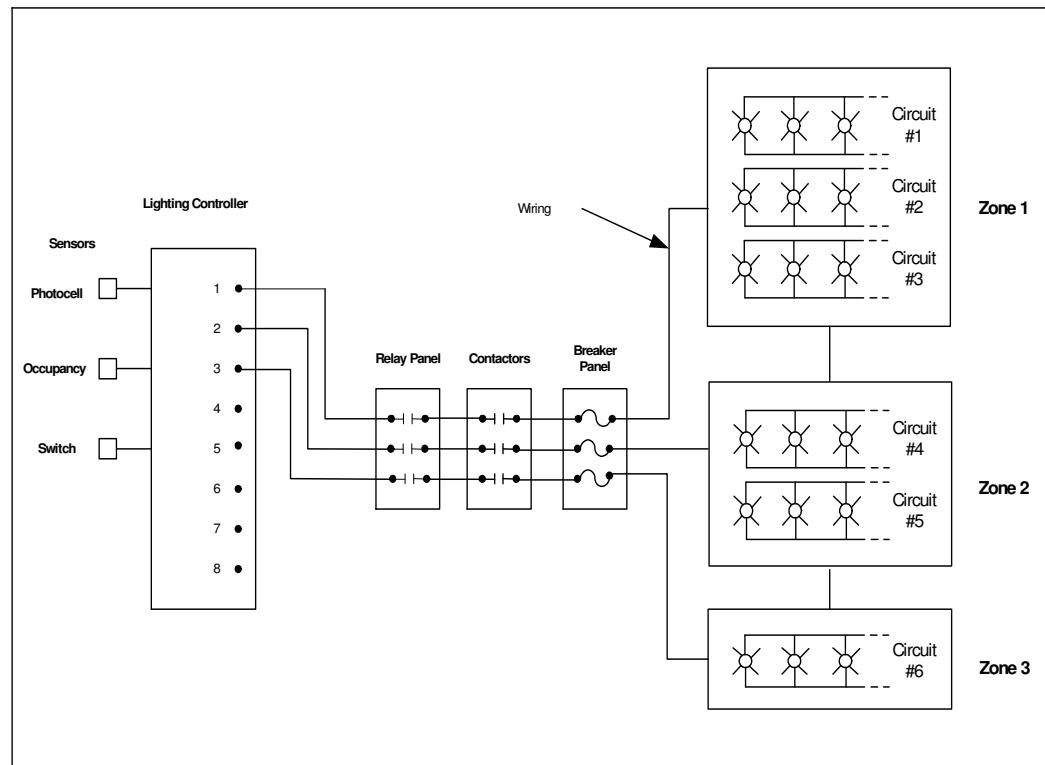


Figure C.4.1 – Lighting Control system With Relays and Contactors

In the lighting control system with and relays and contactors , each zone is defined by connecting all circuits of a zone to a contactor switch. Each contactor is controlled by a relay. The advantage of this configuration is the reduction of the number of outlets in the lighting controller and the number of relays. However, this type of control system is not flexible since each zone is determined based on the connection of the electrical lighting circuits. Moreover, this type of configuration requires more cabling.

In the lighting control system with low-voltage relays (Figure C.4.2), each circuit is connected to a low-voltage relay, which is connected to the outlet of the lighting controller. Lighting zones are defined logically in the lighting controller by activating the relays associated with a given zone. This configuration offers far more flexibility since each zone can be easily redefined and requires less cabling than the lighting control system with relays and contactors. However, the large number of relays required increases installation costs.

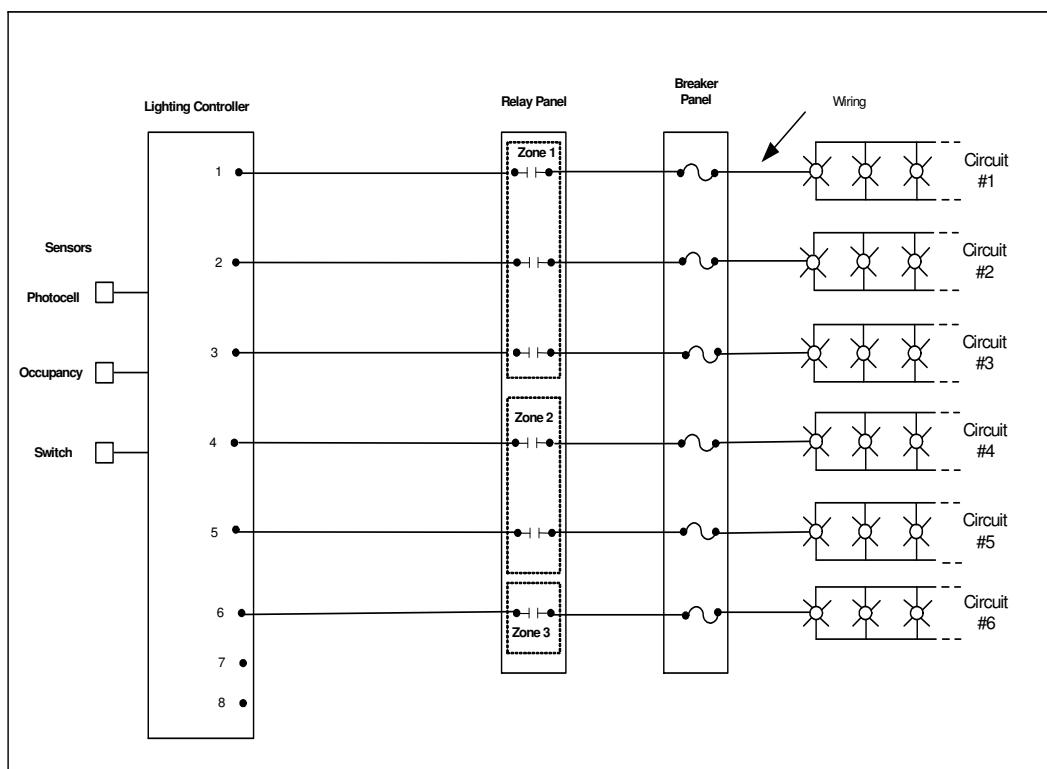


Figure C.4.2 – Lighting Control System With Low-Voltage Relays

The control system may be a combination of both configurations, with some of the circuits having a fixed connection to the contactors and the other circuits being individually connected to the low-voltage relays. This allows more flexibility than the contact switch with relay configuration and reduces the number of relays required.

The lighting control systems in a building may be centralized or distributed or a combination of the two. Figure C.4.3 illustrates the two architectures.

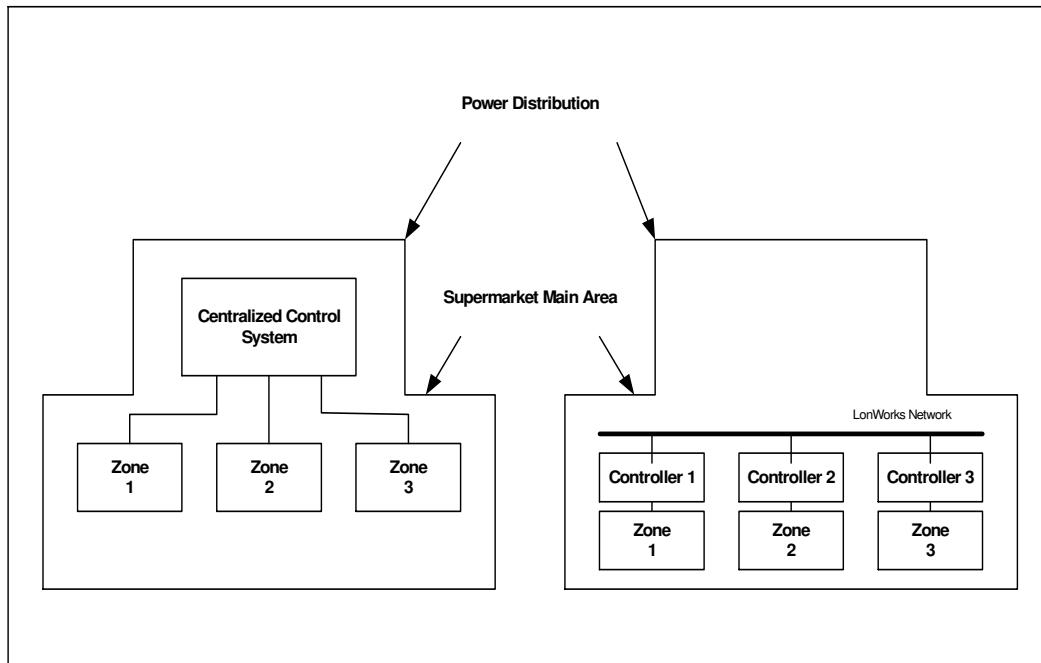


Figure C.4.3 – Centralized Control System Versus Distributed Control System

In a centralized control system, the central controller controls several lighting zones. It receives signals from the sensors, analyzes data and activates the relays to control all the zones in the building. The central controller is normally located in the electrical distribution room. This approach controls all zones, but requires a large controller. Moreover, all electric lighting circuits are connected to the central controller in the electrical distribution room.

In a distributed control system, the control system is subdivided into several local controllers installed near each lighting zone of the supermarket. The sensors are directly connected to the local controller instead of a central controller. Each local controller is independent and connected to the network. This approach involves smaller controllers and requires less cabling. The reliability of this approach depends on the solidness of the network.

This architecture has the following advantages:

- If a controller is defective, only one zone will be affected.
- If a change has to be made, only one of the controllers will be changed.

However, using this approach, the lighting schedules for each zone must be redistributed to each controller.

3.3 Lighting Control Strategy in the Supermarket

The lighting control strategy is based on two priorities: operations and sales. This means that the objectives are:

- To maintain the appropriate operating conditions: employee safety, product quality
- To provide lighting that showcases products in order to increase sales

Flexibility is an important component for the following reasons:

- A supermarket's opening and closing hours may vary, and stores are open for increasingly longer periods of time. This impacts a supermarket's activities: they are more spread out throughout the day. Lighting must be adjusted based on occupation hours and the type of activity (e.g. occupation by customers during the day versus occupation by support staff at night).
- Supermarkets are becoming larger and larger and are offering more and more services through independent retailers. This impacts the lighting system by creating new zones that must be controlled independently.

In general, the time switching control strategy is highly used in supermarkets since it is less costly to implement. To obtain gradual or partial lighting control, the lighting circuits are grouped alternatively so that a percentage of the lighting fixtures (generally 50%) is turned off while another is on. This strategy is known as the 50/50 strategy (Figure C.5.1). It balances the time the lights are on and facilitates maintenance while providing adequate lighting

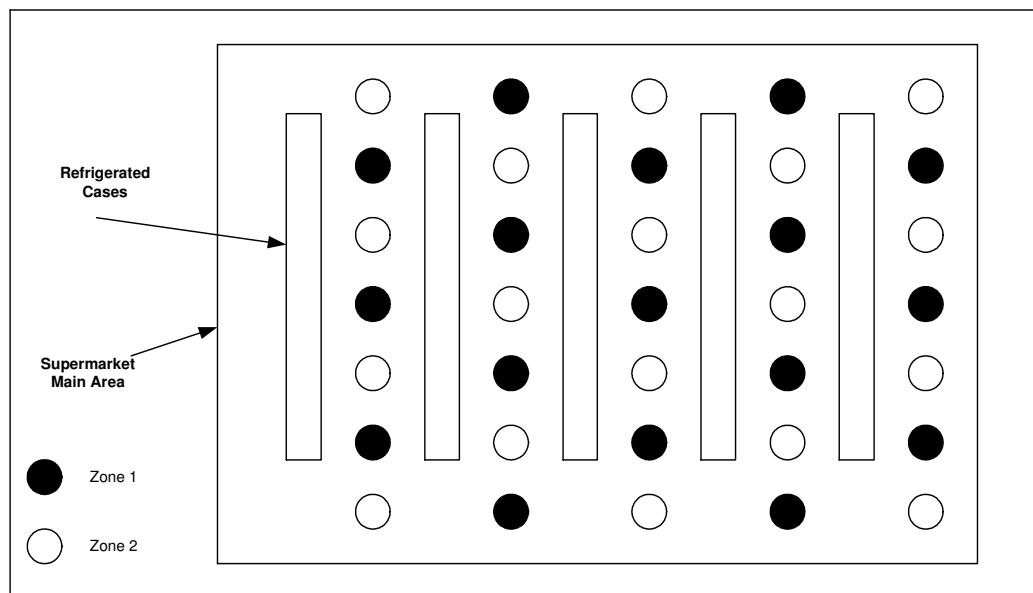


Table C.5.1 shows the different lighting control techniques: automatic or manual control.

Control Type	Control Technique	Description and Considerations
Automatic	Time switching	<p>Light fixtures are switched to On/Off state based on the programmed schedule. In this control technique, different types of timers are used:</p> <ul style="list-style-type: none"> • Mechanical timer • Electronic timer • Programmable software timer <p>This type of control must include a manual control with time-out to override the schedule or lighting timer. After the time-out period, the lighting system must automatically go back to time switching mode.</p> <p><i>Supermarket Applications:</i> Electronic or mechanical timers are used in the zones with set schedules. Programmable software timers are used in occupation zones with variable schedules.</p>
	Time Switching / modulation based on ambient lighting	<p>Light fixtures are switched or modulated in intensity based on the ambient lighting levels when there is daylight.</p> <p>A photocell sensor is used to convert visible rays:</p> <ul style="list-style-type: none"> • Into a digital electronic signal to switch one or more controller lighting relays (circuit). • Into an analog electronic signal to modulate the lighting controller's analog outlet. This modulates the lighting intensity based on the level of ambient light. <p>The electric photocell sensors used for outdoor applications normally face north in the northern hemisphere to ensure constant illumination on the sensor. This eliminates any contribution from the sun.</p> <p>In general, outdoor photocell sensors must not be used for indoor applications because of the low sensitivity and their limited adjustment level.</p> <p><i>Supermarket Applications:</i> The switching mode is used for outdoor applications. Modulation mode is used for indoor applications when there are skylights.</p>

Control Type	Control Technique	Description and Considerations
	Occupation/motion sensor	<p>Occupation and motion sensors are digital devices that switch the light fixtures depending on whether people are in a given physical space or not.</p> <p>The light fixtures are activated when a person enters and remains in a room. The light fixtures are turned off after a programmable time when the person has left the room. Occupation may be detected by an audio signal, ultrasound, infrared or optical means.</p> <p><i>Supermarket Applications:</i> In general, limited to spaces with a limited occupation rate (office, mechanical room, electrical distribution room, storage room) or even outside business hours.</p>
Manual	Forced Control with Time-out	<p>The forced control with time-out activates lighting from a local switch. The lighting turns off after a programmable time is reached.</p> <p><i>Supermarket Applications:</i> For the spaces or occupation rates is limited or occupied outside of business hours.</p>

Table C.5.1 – Lighting Control Techniques

A lighting control strategy is the application of one or more control techniques. For example, in the office areas in a supermarket, a software timer can be used during opening hours and a forced control with time-out outside of opening hours. Table C.5.2 presents the lighting control strategies and their different control devices for the different lighting zones of a supermarket.

Lighting Zone	Control Strategy	Control Devices
Parking and Signs	<ul style="list-style-type: none"> • Time switching on a schedule in conjunction with switching based on ambient lighting. • Light fixtures activated in the dark, on all night and off at daylight. 	Timers, programmable lighting schedules and photocell sensors
Traffic Lanes and Unloading Area	<ul style="list-style-type: none"> • Time switching along with switching based on ambient lighting. • Light fixtures activated in the dark and on all night for security 	Timers, programmable lighting schedules and photocell sensors
Peripheral Area Services and Sales Area: Aisles, Entranceway and Cashier Area	<ul style="list-style-type: none"> • Time switching • Light fixtures are on during the business areas and turned off 50/50 in unoccupied mode. 	Programmable lighting schedules
Sales Area With Energy Optimization	<ul style="list-style-type: none"> • Time switching along with modulation based on ambient lighting. • Light fixtures turned off outside of opening hours and intensity modulated based on ambient lighting based on opening hours. 	Programmable lighting schedules and photocell sensors
Refrigerated and Freezer Cases	<ul style="list-style-type: none"> • Time switching • Activated during business hours and several hours outside of business hours so that cases can be filled. Turned off the rest of the time. 	Programmable lighting schedules
Decorative Lighting	<ul style="list-style-type: none"> • Time switching • Activated during business hours, turned off during unoccupied periods 	Programmable lighting schedules
Office, Mechanical Room, Storage Room	<ul style="list-style-type: none"> • Time switching along with occupation detection and forced control with time-out • Activated during business hours and activated by the occupation sensor or manually forced command 	Programmable lighting schedule, occupation detector, switch with time-out
Emergency lighting	<ul style="list-style-type: none"> • Controlled by a separate control system connected to an emergency generator. 	

Table C.5.2 – Control Strategy for Lighting Zones of a Supermarket

Revision History

REV	Description	Revised by	Date
1.0	Creation and formatting of the document, based on 71-GEN-0010 (French version)	Rosson	12-sep-03
1.1	Document Revision and corrections	JMT, JG, CBC	18-sep-03
2.0	Document Release	JG	29-sep-03