



Software User Guide

VA 1051000 | Parker Vehicle System Gateway



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Revision History

| Rev # | Description of Change | Date |
|-------|---|--------------|
| 52A | Case 77257 - Updated CAN Log screen. Case 67311 - Added notes on sleep mode now working with J1939 managed buses. | 2022-June-30 |
| 51A | Case 76919 - Added notes to the variants about the RP1210 routing messages on some variants. Case 78580 - Added two new variants: 1051011 and 1051012 | 2022-May-27 |
| 50A | Case 77377 - Added notes on Update Tool Error Codes. - Added note on resetting locked out PVSG. | 2022-Mar-31 |
| 49A | Case 76724 - Updated Storage Administrator diagram. | 2022-Feb-25 |
| 48A | Case 74964 - Added new 2:8 PVSG Error Code. - Added notes on how to verify a successful PVSG Update or Configuration. | 2021-Nov-30 |
| 47A | Case 73579 - Added CAN Message Filters Errors table. | 2021-Sep-30 |
| 46A | Case 72236 - Added operating current ratings. - Added notes about the CAN Filter Import Spreadsheet. | 2021-Jul-22 |
| 45A | Case 70526 - Added Importing and Clearing CAN Filters sections. - Added a caution about J1939 management message and routing. - Added note about how Time and Date shall be used for it to persist. | 2021-Jun-18 |
| 44A | Case 66968 - Added security recommendations section. - Added note about separating safety critical devices on CAN buses. - Added Update Steps section - Updated the Message Filtering Notes section in relation to large message routing. - Added more information to the Sleep Mode tables. - Added note about User Account details. | 2020-Dec-22 |
| 43A | Case 65039 - Added Features section. | 2020-Aug-20 |
| 42A | Case 64793 - Reworded Administrator permissions note to say that it is required. | 2020-Aug-06 |
| 41A | Case 63888 - Added CAN Configuration and Message Filtering section. | 2020-Jun-24 |
| 40A | Case 62210 - Added notes about J1939 management and large message routing. - Updated CAN Logging section. | 2020-Apr-30 |
| 39A | Case 61686 | 2020-Mar-30 |



| | | |
|-----|------------|-------------|
| 38A | Case 59763 | 2019-Dec-17 |
| 37A | Case 59191 | 2019-Nov-22 |
| 36A | Case 58699 | 2019-Oct-25 |
| 35A | Case 58082 | 2019-Sep-30 |
| 34A | Case 56950 | 2019-Aug-02 |
| 33A | Case 56549 | 2019-Jul-02 |
| 32A | Case 55423 | 2019-May-08 |
| 31A | Case 55043 | 2019-Apr-15 |
| 30A | Case 54952 | 2019-Apr-08 |
| 29A | Case 54038 | 2019-Feb-22 |
| 28A | Case 53329 | 2019-Feb-01 |
| 27A | Case 52994 | 2018-Dec-20 |
| 26A | Case 52269 | 2018-Nov-22 |
| 25A | Case 51751 | 2018-Oct-25 |
| 24A | Case 50833 | 2018-Sep-28 |
| 23A | Case 49807 | 2018-Aug-31 |
| 22A | Case 49270 | 2018-Aug-03 |
| 21A | Case 48811 | 2018-Jul-06 |
| 20B | Case 47961 | 2018-Jun-11 |
| 20A | Case 47961 | 2018-Jun-08 |
| 19A | Case 47350 | 2018-May-11 |
| 18A | Case 46879 | 2018-Apr-13 |
| 17A | Case 46176 | 2018-Mar-16 |
| 16A | Case 45444 | 2018-Feb- |



| | | |
|-----|------------|--------------|
| | | 16 |
| 15A | Case 43594 | 2018-Jan-19 |
| 14A | Case 44222 | 2017-Dec-15 |
| 13A | Case 43593 | 2017-Nov-17 |
| 12A | Case 42431 | 2017-Oct-20 |
| 11A | Case 41679 | 2017-Sept-25 |
| 10A | Case 41105 | 2017-Aug-25 |
| 09B | Case 40817 | 2017-Jul-28 |
| 09A | Case 40817 | 2017-Jul-28 |
| 08A | Case 40034 | 2017-Jun-30 |
| 07A | Case 39163 | 2017-Jun-02 |
| 06A | Case 38567 | 2017-May-08 |
| 05A | Case 37804 | 2017-Apr-10 |
| 04A | Case 37055 | 2017-Mar-13 |
| 03A | Case 36610 | 2017-Feb-14 |
| 02C | Case 35723 | 2017-Jan-16 |
| 01A | Case 35553 | 2016-Nov-30 |
| 00A | Case 34734 | 2016-Oct-25 |



1. Overview

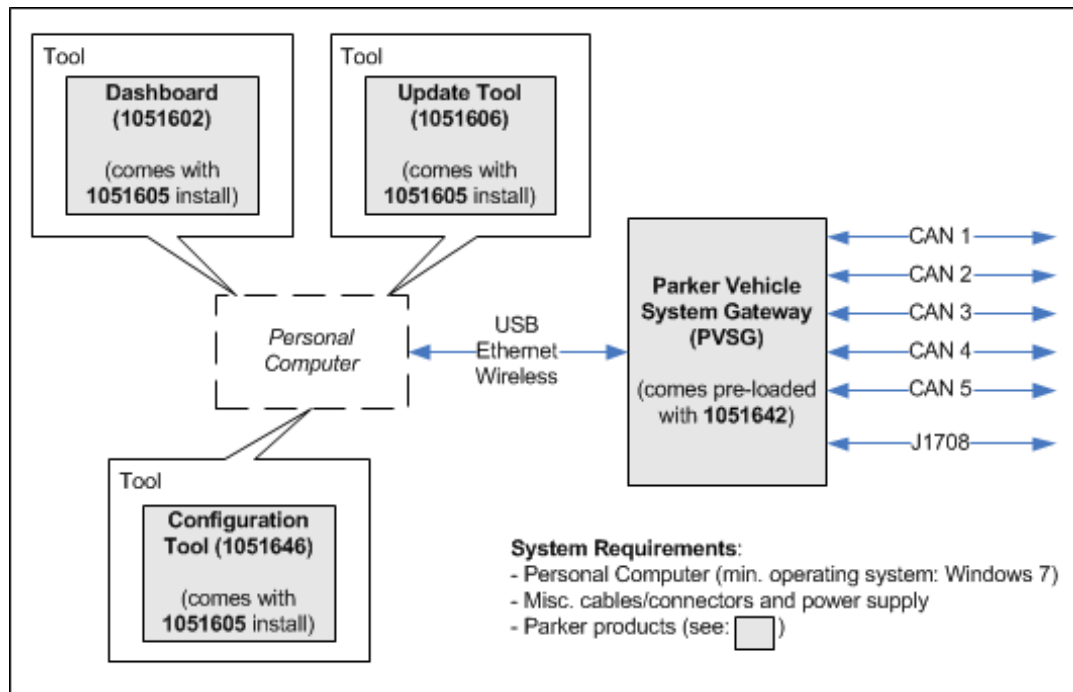
This document provides information relevant to those using the Parker Vehicle System Gateway (PVSG).



Note: this document is subject to change. Contact Parker for more information should you have questions not covered by this document.

1.1. Product Overview

The following diagram shows an overview of the software components and communication interfaces currently supported by the PVSG.



Internally, the PVSG consists of three basic components:

- Router: provides CAN and J1708 interface including all functionality related to CAN message filtering performed to allow CAN messages received on one CAN port to be transmitted on one or more of the other CAN ports.
- Server: provides on board management capabilities including USB / Ethernet / Wireless interface and all functionality associated with them.
- Power Control: performs power management functions including controlling when the product goes to sleep and wakes up.

1.2. Connector Pinout

The pinout for PVSG connectors are as follows:

| J1 Connector | | | |
|---------------------|-----------------|------------|-----------------|
| Pin | Function | Pin | Function |
| J1-1 | GPIO2 | J1-11 | CAN3 Shield |
| J1-2 | GPIO1 | J1-12 | CAN3 High |
| J1-3 | CAN2 Shield | J1-13 | CAN3 Low |
| J1-4 | CAN2 Low | J1-14 | CAN4 Shield |
| J1-5 | CAN2 High | J1-15 | CAN4 High |
| J1-6 | CAN1 Shield | J1-16 | CAN4 Low |
| J1-7 | CAN1 Low | J1-17 | CAN5 Shield |
| J1-8 | CAN1 High | J1-18 | CAN5 High |
| J1-9 | Ground | J1-19 | CAN5 Low |
| J1-10 | Power | J1-20 | Ground |

Note: GPIO1 and GPIO2 are configurable wakeup sources (active high, see "Power Management" section below).

Note: CAN1, CAN2, CAN3, CAN4, CAN5 are configurable wakeup sources (see "Power



Management" section below).

Note: Power (J1-10) requires greater than 8V to wakeup and more than 6V to continue operating.

J2 Connector

| Pin | Function | Pin | Function |
|------------|-----------------|------------|-----------------|
| J2-1 | J1708A | J2-9 | RS232 RTS |
| J2-2 | J1708B | J2-10 | Ground |
| J2-3 | Ground | J2-11 | LIN4 |
| J2-4 | LIN2 | J2-12 | Recovery |
| J2-5 | Ground | J2-13 | RS232 RX |
| J2-6 | LIN1 | J2-14 | RS232 TX |
| J2-7 | RS232 CTS | J2-15 | Ground |
| J2-8 | Output 1 | J2-16 | LIN3 |

Note: All RS232 signals are labelled as DTE (Data Terminal Equipment) signals (TX & RTS are outputs and RX & CTS are inputs).

Note: Access to RS232 signals should be restricted to only those authorized to use them (e.g. place PVSG inside a locked compartment, don't include RS232 connection in production harness).

Note: Access to the Recovery input (J2-12) should be restricted to only those authorized to use it (e.g. place PVSG inside a locked compartment, don't include recovery connection in production harness).

Note: Output 1 may appear to toggle due to the strobing of the open load detection circuitry if the load attached is small.

J12 Connector (USB)

| Pin | Function |
|------------|-----------------|
| J12-1 | USB GND |
| J12-2 | USB PWR |
| J12-3 | USB DP |
| J12-4 | USB DN |
| J12-5 | USB OTG ID |

Note: USB is one of the configurable wakeup sources (see "Power Management" section below).

Note: Access to J12 should be restricted to only those authorized to use it (e.g. place PVSG inside a locked compartment, don't leave mating connector with standard USB connector connected to PVSG).

J11 Connector (Ethernet)

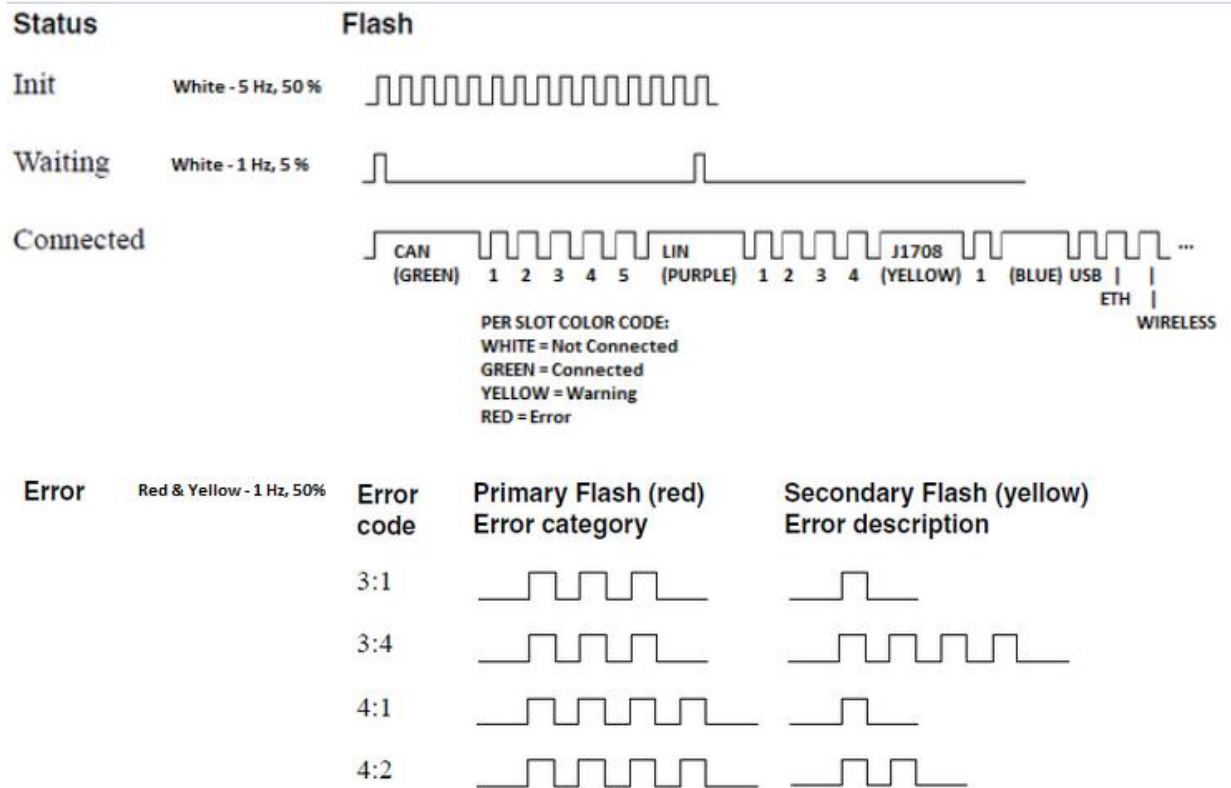
| Pin | Function |
|------------|-----------------|
| J11-1 | Ethernet TXP |
| J11-2 | Ethernet RXP |
| J11-3 | Ethernet TXN |
| J11-4 | Ethernet RXN |

Note: When Ethernet is enabled (see "Network Configuration" section below), access to J11 should be restricted to only those authorized to use it (e.g. place PVSG inside a locked compartment, don't leave mating connector with standard Ethernet connector connected to PVSG).

SMA Connector (External Antenna)

1.3. Status LED

The LED on the PVSG is a multi-color LED that provides diagnostic information as follows (drawing is not to scale):



Where:

- **Init** indicates PVSG is performing some form of initialization (i.e. a portion of the PVSG is still booting up, or performing a configuration/programming step).
- **Waiting** indicates nothing is connected to the PVSG (i.e. no CAN traffic detected, no USB connection, etc.).
- **Connected** indicates something is connected to the PVSG. Use legend to decode connected network status.
 - CAN slot color codes as follows:
 - White: CAN bus inactive (no transmitted or received messages).
 - Green: CAN bus actively transmitting and/or receiving messages.
 - Yellow: Not used.
 - Red: CAN "bus off" or "error passive".



Note: it may be required to successfully transmit and receive a message to clear "error passive" state.

- **Error** indicates an error has been detected.
 - Error codes shown in the diagram are examples.



- The error codes supported by the PVSG are available in the "Error Codes" section below.

1.4. Error Codes

The following table is a list of error codes supported by the PVSG.

| Error Code | Description | Detectable via | Disabled Function(s) | Recovery |
|------------|--|---------------------|--|--|
| 1:1 | Server offline (not detected at all since startup). | LED | Server disabled. | Reset PVSG. |
| 1:2 | Server offline (detected at startup, but then later not detected). | LED | Server disabled. | Reset PVSG. |
| 1:3 | Configuration missing or invalid. Note: CAN bit rate defaulted to 250 kbps. | LED | CAN transmission disabled. | Configure PVSG. |
| 1:4 | Invalid hardware. Note: CAN bit rate defaulted to 250 kbps. | LED | CAN transmission disabled. | Verify version of 1051642 in use supports the hardware in use. |
| 2:1 | USB communications failure. | LED | USB disabled. | Reset PVSG. |
| 2:2 | Server failed to load configuration. | LED, Dashboard | Default configuration. | Configure PVSG. |
| 2:3 | Server failed to mount internal storage. | LED, Dashboard | Server disabled. | Reset PVSG. |
| 2:4 | Power control offline. | LED, Dashboard | Power management disabled (PVSG will not sleep regardless of configured wakeup sources). | Reset PVSG. |
| 2:5 | Server internal service has stopped responding. | LED, Dashboard, DM1 | Server disabled. | Reset PVSG. |
| 2:6 | Router offline. | LED, Dashboard | CAN receive/transmit not available. | Reset PVSG. |
| 2:7 | Shutdown not possible. | LED, Dashboard | Server shutdown is not possible due to an internal error. | Reset PVSG. |
| 2:8 | XMC failed to | LED, | PVSG XMC | Perform |

| Error Code | Description | Detectable via | Disabled Function(s) | Recovery |
|------------|---|----------------|---|--|
| | reprogram. | Dashboard | software or configuration is not updated. | update/configuration again. |
| 20:1 | Missing modules. | Dashboard, DM1 | Expected modules are missing from the system. | Connect the missing modules. |
| 20:2 | Unknown modules detected. | Dashboard, DM1 | Unexpected modules are connected to the system. | Remove the unknown modules from the system. |
| 21:1 | Custom logic: incompatible SDK. | Dashboard, DM1 | Custom logic halted. | Update PVSG and/or custom logic SDK in use. Consult document 1051G05, <i>Custom Logic User Guide</i> for more details. |
| 21:2 | Custom logic: resource utilization limits exceeded. | Dashboard, DM1 | Custom logic halted. | Debug/rework custom logic. Consult document 1051G05, <i>Custom Logic User Guide</i> for more details. |
| 21:3 | Custom logic: failed to load. | Dashboard, DM1 | Custom logic halted. | Check PVSG configuration. |
| 21:4 | Custom logic: terminated. | Dashboard, DM1 | Custom logic halted. | Debug custom logic. Consult document 1051G05, <i>Custom Logic User Guide</i> for more details. |
| 21:5 | Custom logic: stalled. | Dashboard, DM1 | Custom logic halted. | Debug custom logic. Consult document 1051G05, <i>Custom Logic User Guide</i> for more details. |

Where possible, error information is also available in the **PVSG Dashboard**. See the "Dashboard" section of this document for more details.

Error information is available in a periodic DM1 message broadcast by the PVSG on J1939 interfaces that have management enabled (see "J1939 Configuration" section below). Each active Diagnostic Trouble Code (DTC) included in the DM1 message uses proprietary SPN 52xxyy, where x and y are taken from the error code in the table above. E.g. SPN 520205 is error 2:5, and SPN 521510 is error 15:10. Each active DTC uses Failure Mode Identifier (FMI) 31, where 31 is defined by J1939-73 JAN2016 to mean "Condition Exists ... the reported SPN name spells out the component and a non-standard failure mode". Each active DTC sets Amber Warning Lamp (AWL) to flash slow and Red Stop Lamp (RSL) to off.



Note: LED off indicates the PVSG is not operating due to power off, or powered without an activated unmasked wakeup source.



2. Licensing

Licensing is covered in several contexts with respect to the PVSG. The following is a summary of the contexts and specific license related references in this document:

1. Section "Software Licensing & Copyright" below deals with the GPL code used in the PVSG that is licensed under the GNU General Public License (refer to section "GNU GENERAL PUBLIC LICENSE" at the end of this document).
2. Section "Licences" under "Dashboard" describes how the dashboard provides an interface to install a tool license or a PVSG feature license.
3. Section "Variants" under "Configuration Tool" > "Creating/Editing Configurations" describes how PVSG feature licenses can be used to enable functionality on certain variants of the PVSG.
4. Document 1051G05, *Custom Logic User Guide* describes additional licenses for the development of custom applications and programming plugins.



Note: License and licence is used interchangeably in this document and in the software.

2.1. Software Licensing & Copyright

The software running on the PVSG makes use of code built around the GNU General Public License, version 2.

All Parker-modified GPL code continues to be licensed under the GNU General Public License. This license is available in its entirety at the end of this document. You may obtain the complete Corresponding Source code from us for a period of three years after our last shipment of this product, which will be no earlier than 2021-01-01, by a request to:

Parker Hannifin Canada
Electronic Controls Division
1305 Clarence Avenue
Winnipeg, MB R3T 1T4 Canada

Please include the following with your request: "Request for source code corresponding to Parker-modified GPL code licensed under GNU General Public License in product PVSG 1051000". This offer is valid to anyone in receipt of this information.

All Parker-generated code is copyright Parker-Hannifin Corporation, all rights reserved. No part of this Parker code may be reproduced, published, or distributed in any form or by any means (electronically, mechanically, photocopying, recording or otherwise), or stored in a database or retrieval system, without the prior written permission of Parker-Hannifin Corporation in each instance.

3. Security

The following security related risk reductions factors are included in the PVSG to reduce the risk associated with security threats (including cybersecurity related threats):

- Configuration file includes optional password-based protection to restrict view and/or edit access. Configuration files are encrypted to prevent unauthorised access and modification. See "Configuration Security" section below for details. This can be used to:
 - Prevent unauthorised users from modifying the installed configuration.
 - Prevent unauthorised users from reading an installed configuration and gaining unapproved knowledge of the system.
- Wireless configuration includes optional support for connection-oriented security modes to restrict access when wireless is enabled. See "Network Configuration" section below for details.
 - The configuration warns the user if an acceptable level of security has not been configured.
- User access control provides optional support for restricting access to certain PVSG features. See "User Accounts" and "User Access Control" sections below for details.
 - The configuration tools warns the user if the specified user account password does not meet specific security criteria.
- Critical data exchange with the PVSG (e.g. configuration, authentication) uses a secure session to prevent eavesdropping and man-in-the-middle attacks. This uses industry standard transport layer security (TLS) mechanisms to protect the system and its users.
- Data signing techniques are employed where necessary to validate the authenticity of specific data and its sender.
- Open TCP/IP ports limited to only required ports in use.
- Some critical functions are protected by hardware separation.
- Internal access to the PVSG is protected via a layered security approach to prevent unauthorised access.

When incorporating the PVSG into a system with security requirements, ensure that security related PVSG features are configured appropriately and that any system level security related risk reduction factors are also considered to reduce the risk associated with security threats (including cybersecurity related threats).

Contact Parker for more information should you have questions not covered by this document.

3.1. Security Recommendations

At least one user account with read and write access should be configured to lock out any unauthorised configuration of a PVSG. If Wifi is used, a Password should be also be used.



4. Features

This sections describes some of the PVSG features in more detail.

4.1. Data Link Adapter (DLA)

The PVSG along with PVSG PC software is able to provide DLA functionality. The PVSG software is fully compliant with the RP1210 standard and provides CAN, J1939 data traffic on all five CAN ports at 250, 500 or 1000 Kb/s, as well as J1708 traffic on the single J1708 port. The PVSG connects to your PC via USB and via ethernet or wifi on select models (See configuration section below to configure the PVSG to be used via ethernet or wifi).

4.2. CAN Routing

The PVSG is able to route CAN messages from one CAN port to other ports. See the "Message Filter" section below for more details on how to configure the PVSG for CAN routing.

PVSG's running software V1.07 or higher will route DLA CAN messages sent from the PVSG CAN ports based on the CAN routing configuration on the PVSG.



Note: CAN routing will be interrupted during sleep or wakeup therefore it is good practice to keep safety critical devices on the same CAN bus.

4.3. Current Ratings

The operating current ratings are the following:

- 12V - 122 to 137 mA with wifi enabled.
- 24V - 61 to 74 mA with wifi enabled.
- Output adds an additional 250 mA when enabled.

5. Embedded Software

Embedded software for the PVSG is distributed as a deployment package, software part number 1051642. 1051642 is pre-programmed in the PVSG, and upgradable using the update tool (1051606).

5.1. J1939

J1939 Controller Applications (J1939 CAs) are configurable for each physical CAN interface via the configuration tool (1051646).

5.1.1. Version Information

Version information is available on each configured J1939 CA via the J1939 Software Identification (SOFT) and Component Identification (CI) messages. The information can be requested from the CA using the J1939 Request (RQST) message. Note that the information returned by each CA will be identical. The response for both SOFT and CI is compliant with 983F17.01A (internal Parker ECD Standard). In the case of the SOFT message, the fields present are as shown in the following table.

| Field Name | Use |
|------------|--|
| APP | The version of the 1051642 embedded deployment package. |
| PAR | Information pertaining to the installed configuration. This includes the configuration version, label and file name information. |
| MODE | The current operating mode of the product. Valid values are "Run" and "Test". |
| FMT | The specification with which the J1939 SOFT output is compliant. Currently, this is 983F17.01A. |

For the Component Identification message, the final SAP number and final serial number are published for the "Model" and "Serial Number" fields respectively. The format is governed by J1939DA August 2015.

Example:

Below is an example trace from CANsniff:

Timestamp | Len. | PGN | P SA DA | Data

```

-----
12:57:40.260 | 3 | 00EA00 | 6 F9 00 | DA FE 00 |
12:57:40.307 | 94 | 00FEDA | 6 00 FF | 04 41 50 50 2C 31 30 35 31 36 34 32 2C 56 30 2E 35
42 32 37 2A 50 41 52 2C 2C 56 30 2E 30 42 31 2C 31 30 35 31 4D 30 36 20 54 31 31 38 2C
31 30 35 31 4D 30 36 5F 30 34 41 5F 54 31 31 38 2E 70 76 73 67 63 2A 4D 4F 44 45 2C 52
75 6E 2A 46 4D 54 2C 39 38 33 46 31 37 2C 52 30 31 41 2A |
APP,1051642,V0.5B27*PAR,,V0.0B1,1051M06
T118,1051M06_04A_T118.pvsgc*MODE,Run*FMT,983F17,R01A*
13:05:19.997 | 3 | 00EA00 | 6 F9 00 | EB FE 00 |
13:05:20.031 | 25 | 00FEEB | 6 00 FF | 2A 31 36 32 37 35 30 2A 50 52 4F 31 30 35 31 30 30
31 52 30 30 3F 3F 2A 2A | *162750*PRO1051001R00??**

```



The following information was returned upon request of the SOFT message:

APP,1051642,V0.3B18*PAR,,V0.0B1,1051M06

T118,1051M06_04A_T118.pvsgc*MODE,Run*FMT,983F17,R01A*

The following information was returned upon request of the CI message:

*162750*PRO1051001R00??**

where the final SAP number was set to "162750" and the final serial number was set to "PRO1051001R00??".

5.2. Configuration

A PVSG is to be configured using a compatible version of the Configuration Tool. To verify compatibility, compare the Config Format version used by the embedded software installed on your PVSG with the Config Format versions supported by the PC Software installed on your computer. If the Config Format version does not fall within the range of supported versions, downgrade or upgrade the PVSG PC Software on your computer to a suitable version.

6. PC Software

6.1. Overview

PC software for the PVSG is distributed via a single installer (1051605). This installer currently installs the following components:

| Component Name | Software Number |
|--------------------|-----------------|
| Core Driver (*) | 1051602 |
| Update Tool | 1051606 |
| Configuration Tool | 1051646 |

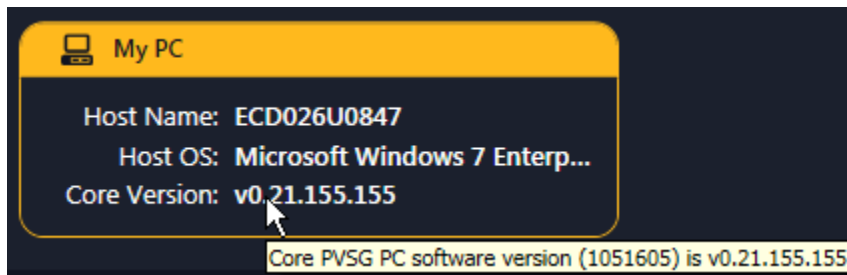
* - The core driver is made up of more than just 1051602, but 1051602 includes the dashboard which is the only user-visible piece.



Note: To determine the correct version of 1051605 PC software to use with the version of 1051642 embedded software used in the PVSG, refer to the release notes accompanying each software package.



Note: The current installed version of the PC software (1051605) can be determined from the dashboard:



The current installed version of the PC software (1051605) can also be determined by going to **Control Panel > All Control Panel Items > Programs and Features** and examining the version reported by **Parker Vehicle System Gateway Suite**. For example:

| | | | | |
|-------------------------------------|-----------------------|------------|---------|---------|
| Parker Vehicle System Gateway Suite | Parker Hannifin Corp. | 30/11/2016 | 59.9 MB | 0.2.9.9 |
|-------------------------------------|-----------------------|------------|---------|---------|



Note: An administrator login is required to successfully install the PVSG PC software.

6.1.1. System Requirements

The PVSG PC Software currently requires Windows 7 / 10 (32-bit or 64-bit), a minimum screen resolution of 1024 x 768, and USB 2.0 or higher.

6.1.2. File Types

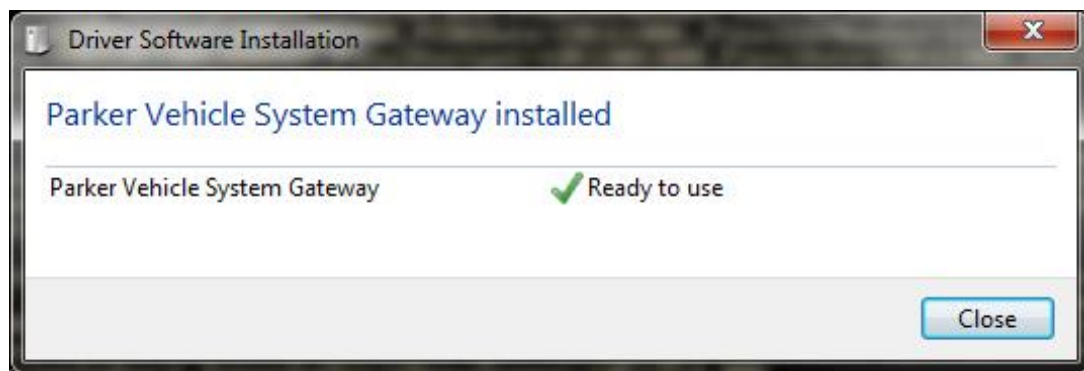
The following file types are used by the PVSG PC software.



| File Extension | Type | Used By | Description |
|----------------|--------------------|------------------------------|--|
| .pvsgs | PVSG Software | Update Tool (1051606) | PVSG embedded software package. Created by Parker Engineering. |
| .pvsgc | PVSG Configuration | Configuration Tool (1051646) | PVSG configuration source file. Configuration can also be distributed in this format. |
| .pvsgapp | PVSG Custom Logic | Configuration Tool (1051646) | PVSG custom logic file (custom application or custom programming plugin). Contact Parker for more details. |

6.1.3. USB Driver Software Installation

The first time a PVSG is connected to a PC via USB, Windows will initiate a PVSG USB Driver Software installation. The PVSG PC Software should not be used until the PVSG USB Driver Software installation has completed:



6.1.4. Management Connectivity

It is possible to connect to the PVSG for management purposes via 3 interfaces:

- USB
- Ethernet
- Wireless

The PVSG PC drivers can handle all 3 types of communication link. From an architectural perspective, Ethernet and Wireless are the same mechanism and are categorised herein simply as "Network" since the underlying layer (TCP/IP) is the same for each. The active communication mechanism can be selected from the **Dashboard** application within the **Connection** tab.

6.2. Dashboard

The dashboard is the user-visible portion of the core driver (1051602) that is the single endpoint for PVSG communication with the PC. Any PC tool(s) needing to communicate with the PVSG does so via this service.

6.2.1. Accessing the Dashboard

The dashboard will start automatically when you log in to Windows as a tray application. Connection change notifications will be shown near the system tray area, for example:



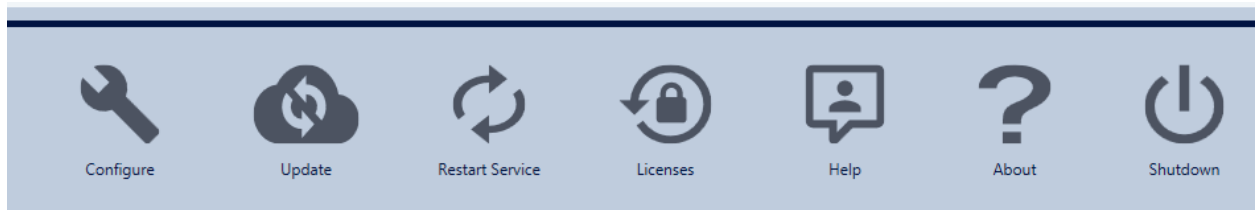
The dashboard tray application can be opened by double-clicking the 'Parker' icon in the system tray area:



When closed, the dashboard will be hidden and continue to run in the background. The dashboard tray application can be permanently shutdown using the **Shutdown** option on the dashboard dock. The dashboard dock can be accessed by clicking the dock button in the top right corner:



Or pressing **Ctrl + D** when the dashboard is in focus. The dock appears at the bottom of the dashboard window:



The dock provides quick access to other PVSG tools as well as access to the help files and version information.

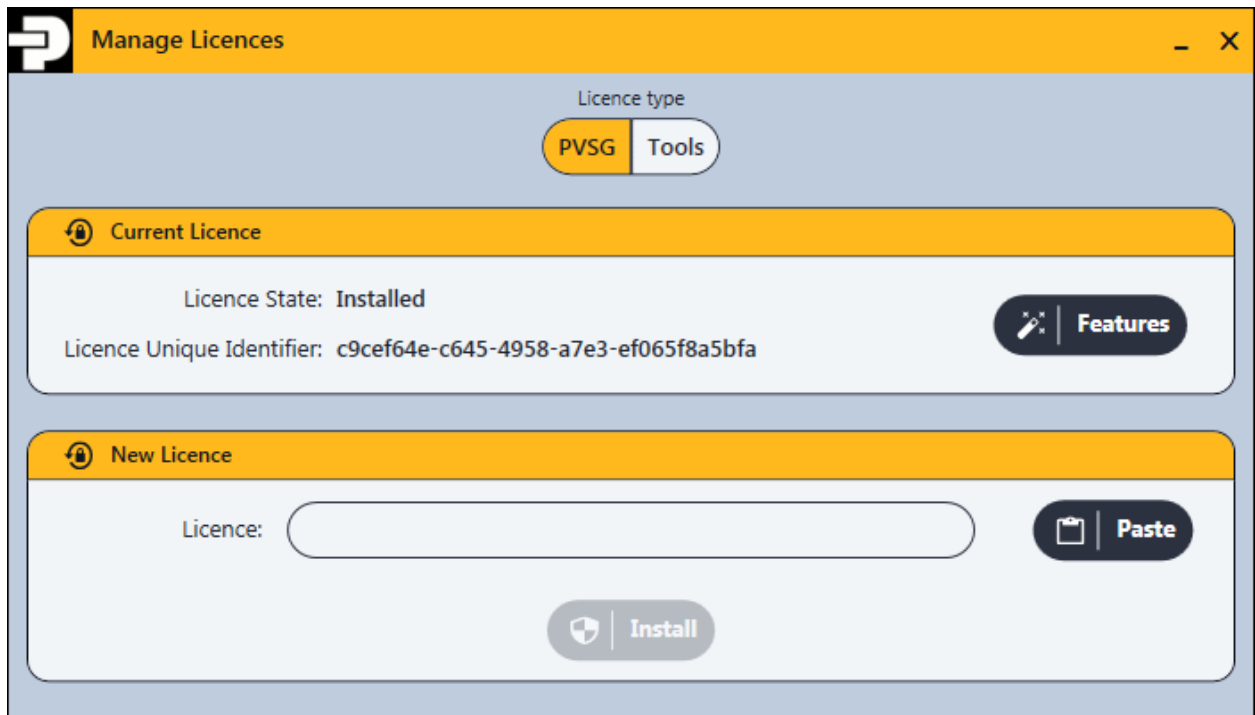
If needed to be relaunched after a permanent shutdown, run **PVSG Dashboard** (shortcut added to Windows start menu by default as part of the installer (1051605) under **Parker > ECD > PVSG**).



Note: Shutting down the dashboard does not shut down the portion of the core driver (1051602) that runs as a Windows service. If you need to restart the core driver, select **Restart Service** from the dashboard dock. Alternatively, from the Windows start menu select **Run**, enter **services.msc** and click **OK**. This should launch a **Services** screen listing Windows services. In the list of services, find **PVSG Driver Core Manager**, right-click on it and select **Restart**. The security principal of an administrator may be required to restart the **PVSG Driver Core Manager** service. If you can't restart the service, restart Windows.

6.2.2. Licences

PVSG feature licences and tool licences can be installed via the licence manager.



6.2.2.1. PVSG

PVSG feature licences can be obtained from Parker Hannifin Corporation, or are pre-installed on a PVSG unit. To install a licence, copy the licence data provided by Parker to the Windows clipboard, and click the **Paste** button under **New Licence**. The PVSG must be restarted (per the prompt) in order for the new licence to take effect. The state of any installed licence is reported under **Current Licence** along with a summary of the enabled feature state via the **Features** button.



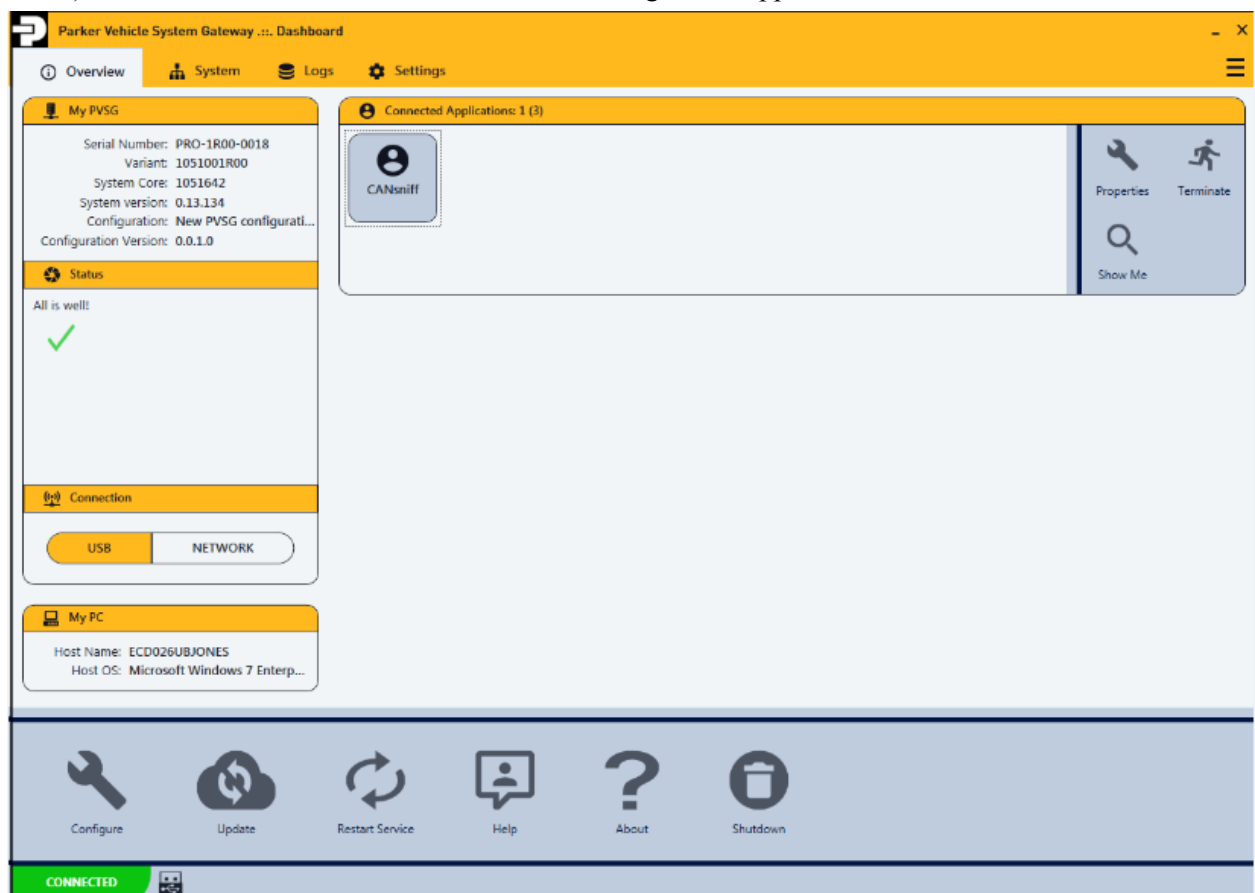
Note: the state of any installed licence is only available when the PVSG has a valid configuration installed.

6.2.2.2. Tools

This section provides easy access to licence data for installed PVSG tools. Refer to the specific tool help for more details on the licence in relation to that particular tool.

6.2.3. Overview

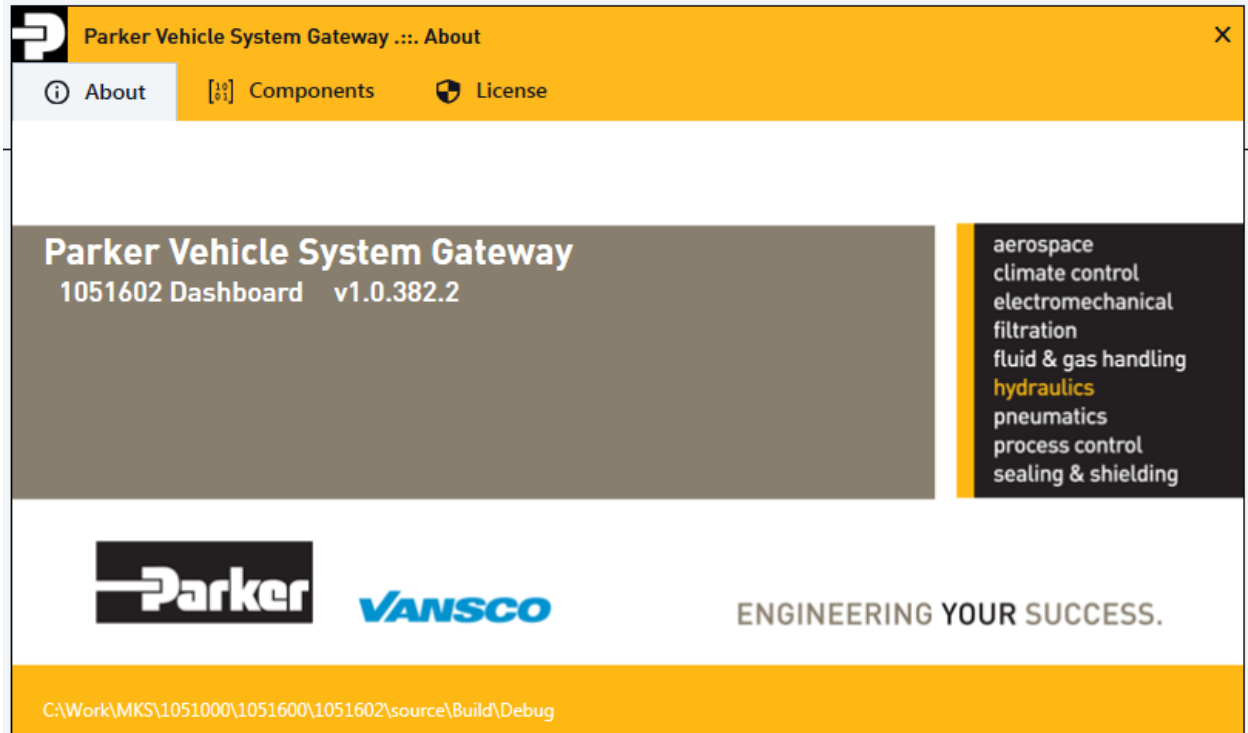
The **Overview** tab provides a quick view of the current state of the connected PVSG (if one exists) and the current state of the PC drivers, including which applications are connected.







Note: The **Configuration Version** number is composed as follows: the first three numbers match the major version, minor version, and build number entry in the configuration tool, and the fourth number (is known as the 'runtime configuration version') is a number updated by PVSG whenever configuration is modified internally (incremented per change at shutdown) or a new configuration is installed (set to 0).


Driver version information can be obtained by selecting the **About** option on the dashboard dock:




The **Components** tab provides detailed information on all major driver components:



Parker Vehicle System Gateway ... About

 About


Components

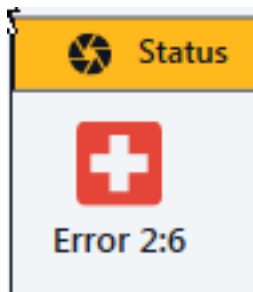
 License

| Component Name | Version |
|--------------------|------------|
| cantypes.dll | 0.1.9.0 |
| cldp.dll | 0.1.10.1 |
| j1939stack.dll | 0.10.69.2 |
| j1939types.dll | 0.8.23.1 |
| libnetdisco.dll | 0.5.9.1 |
| logprocabinet.dll | 0.2.3.1 |
| libvsgcontrols.dll | 1.0.44.2 |
| PH105132.dll | 0.5.15.5 |
| pvsgconfig.dll | 0.11.43.6 |
| pvsgdcs.dll | 0.1.4.0 |
| pvsgsuppkg.dll | 0.27.283.4 |
| nvsgsvc.exe | 0.16.22.6 |

 **Copy Info**

Note that the **Copy Info** button can be used to help provide diagnostic information to Parker; this will copy all of the component version information to the Windows clipboard which can then be pasted into an email, for example.

Active target errors are shown within the **Status** panel. The error codes match those shown on the PVSG's status LED and the "Error Codes" section within this document can be used to lookup the meaning.






6.2.4. Connection Information

The bottom right corner of the Dashboard provides connection information summary.



The connection status indicator on the left reports the connection state as CONNECTED or

NOT CONNECTED. When connected, the connection method will be shown as USB ()

or network (). In addition, when connected, a lock symbol () will appear when a secure session has been established with the PVSG.



Note: A secure session is required to perform critical data exchange with the PVSG (e.g. configuration, authentication).

The **Connection** panel provides an interface to select between available target connection methods (USB or Network (including Ethernet and wireless)).

6.2.4.1. USB

USB is the primary management connection mechanism. If another management connectivity mechanism is in use and the USB connection becomes connected, communication will transition to the USB link once a connection is established.

6.2.4.2. Network

The default network connection mechanism is Ethernet. If Ethernet and/or wireless is enabled in the configuration and depending on whether Ethernet is physically connected to the target or not, one or the other will become active whenever the USB link is determined to be disconnected. If wireless is enabled in the configuration, the radio will power up and down as necessary when the network connection mechanism is available.

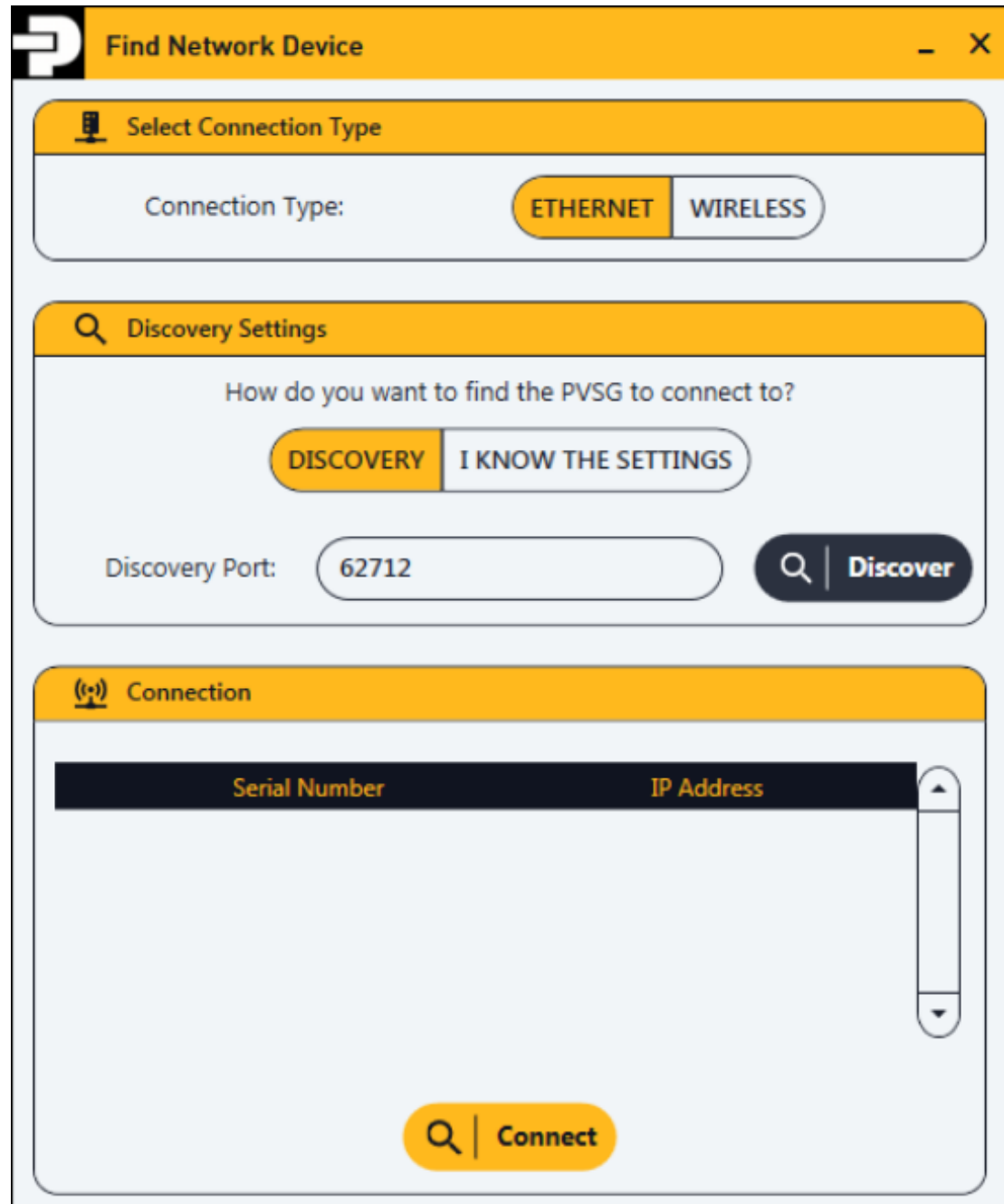
All network configuration can be done via the configuration tool (1051646) from the **Network Configuration** menu option.

Discovery

The network communication mechanism provides a discovery feature which allows one or more PVSGs to be discovered on the network. This allows such devices to be connected to without knowing their address details. For this to work, discovery must be enabled in the configuration and the discovery port must be known. The discovery mechanism uses broadcast UDP transmissions, and so PVSGs can ONLY be discovered within the broadcast domain of the network to which they are connected. The broadcast domain is controlled by

both the physical topology of the network and the addressing scheme in use. Importantly, note that broadcast transmissions are never forwarded by network routers. The PVSG(s) which you wish to discover and the PC performing the discovery operation must be on the same network segment and be visible to one another.

The discovery interface can be accessed from the dashboard by going to the **Connection** panel and clicking on **Network**. This will bring up the following screen.



The interface is titled "Find Network Device" and is divided into three main sections:

- Select Connection Type:** Features a "Connection Type:" label and two buttons: "ETHERNET" (selected) and "WIRELESS".
- Discovery Settings:** Includes a search icon and the text "How do you want to find the PVSG to connect to?". It has two buttons: "DISCOVERY" (selected) and "I KNOW THE SETTINGS". Below this is a "Discovery Port:" label, a text input field containing "62712", and a "Discover" button with a search icon.
- Connection:** Features a connection icon and a table with two columns: "Serial Number" and "IP Address". The table is currently empty. At the bottom of this section is a "Connect" button with a search icon.

Click **Discover** to discover available PVSGs. Available PVSGs will appear in the *Connection* area of the screen. Select the desired PVSG and then click **Connect** to establish a connection with it.



Ports

As is good practice with services which use TCP/IP communication, the ports used are configurable. Note that the default values have been carefully chosen to avoid collision with known standard ports, and so should not be changed by the user without very good reason.

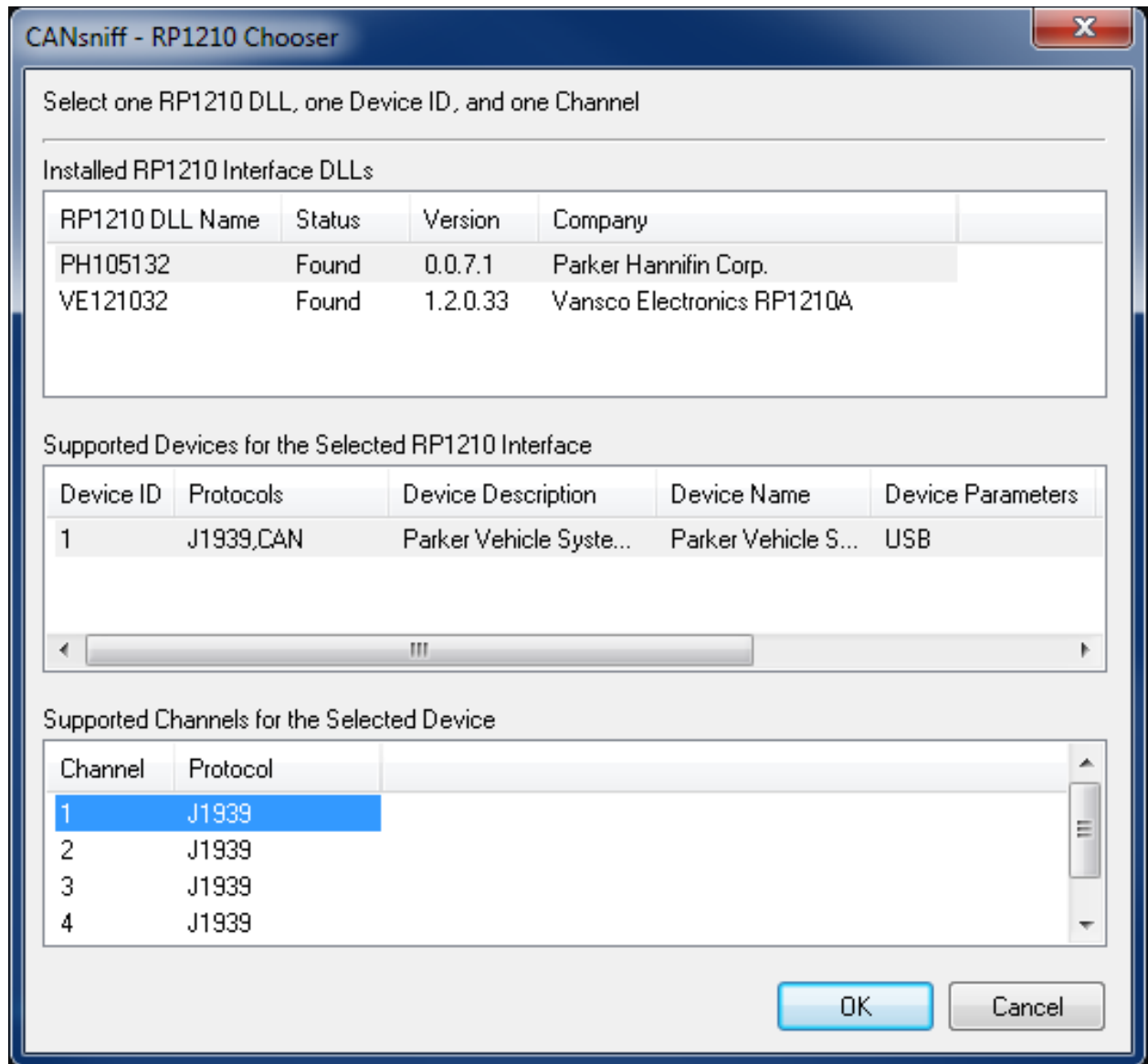
6.2.5. Client Information

The dashboard provides information on the clients connected to the target. The **Connected Applications** panel provides an interface to select between connected applications.

6.2.5.1. Connecting an RP1210 Client

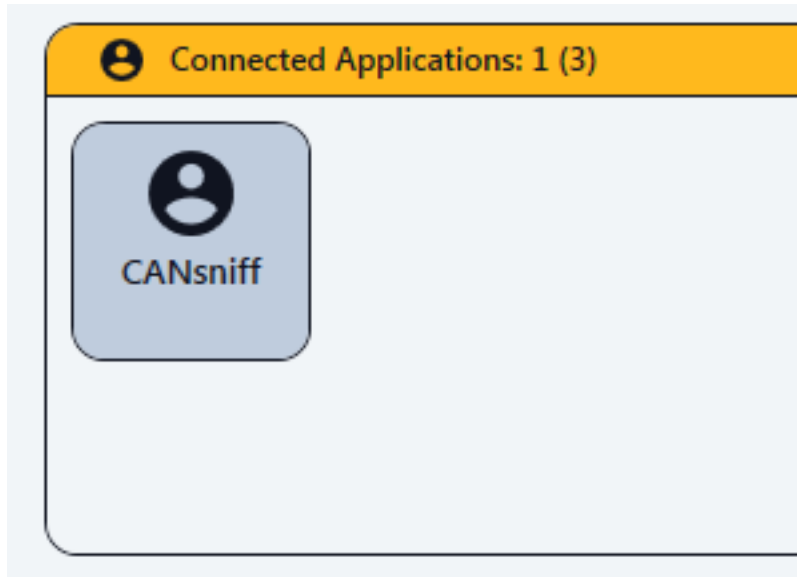
The PVSG supports a subset of RP1210C (reference *TMC RP 1210C - Windows Application Program Interface*) to provide diagnostic tool access to all of the PVSG CAN, J1939 and J1708 interfaces.

In order to connect a RP1210-based tool to the PVSG (e.g. CANsniff), the PVSG DLL (i.e., PH105132) must be specified as the RP1210 Vehicle Datalink Adapter (VDA) to use. For example, CANsniff supports a built-in RP1210 chooser that allows you to choose the RP1210 VDA to use. Note other tools may require other steps to be taken to specify the PVSG DLL.

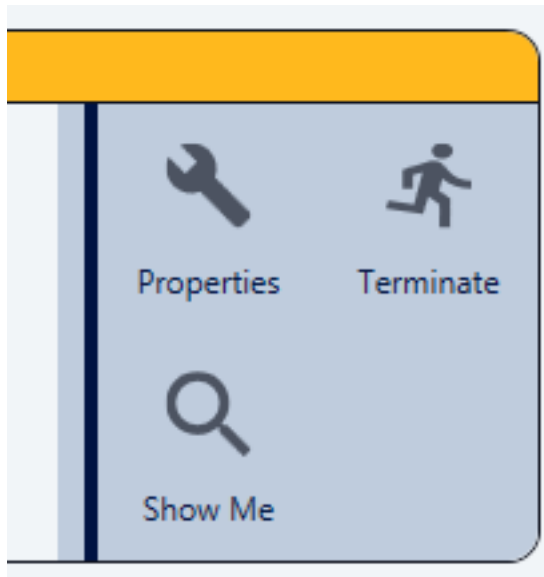


Note: The physical CAN bus with which an RP1210 client is associated is set by channel selected for the supported device when specifying PH105132 (third section of the screen above *Supported Channels for the Selected Device*). The channel number is the physical CAN bus number (i.e. Channel 1 is CAN 1, Channel 2 is CAN 2, etc.).

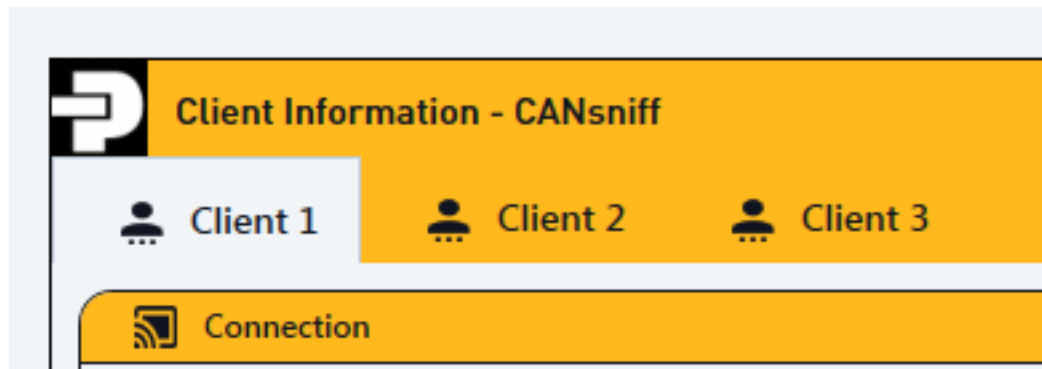
Once connected, the client can be seen from the dashboard tray application, **Connected Applications** panel.



Clicking on any client application will bring up a menu with actions that can be performed upon the application attached to the PVSG.

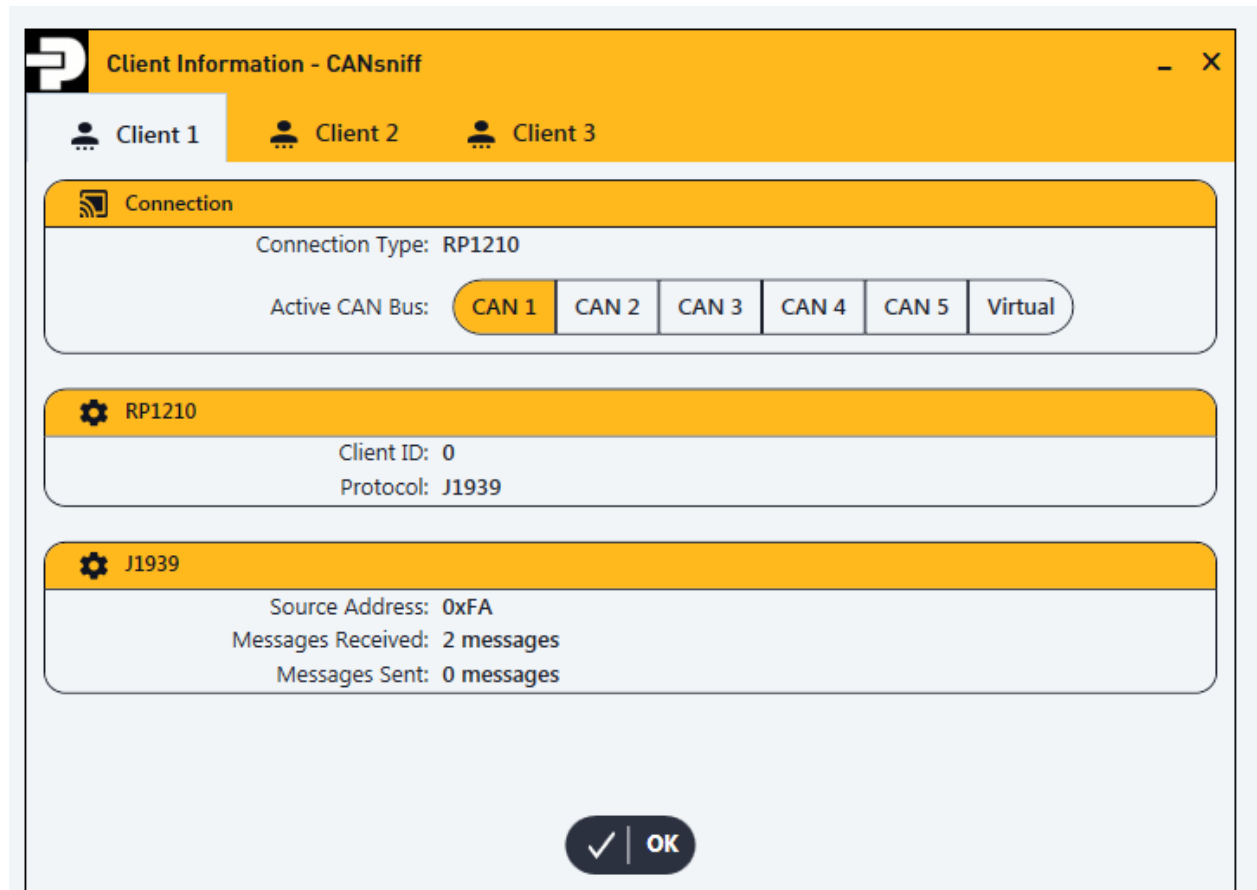


Note: A single application may contain multiple "clients". In terms of RP1210 clients, for example, a single application instance may open more than one RP1210 client connection. Each logical connection which a connected application owns is shown as a tab in the properties window:



6.2.5.2. Properties

The **Properties** window shows various metric information about a particular client connection. For CAN (or J1939) type connections, it also allows the active CAN bus to be changed:



Notes:

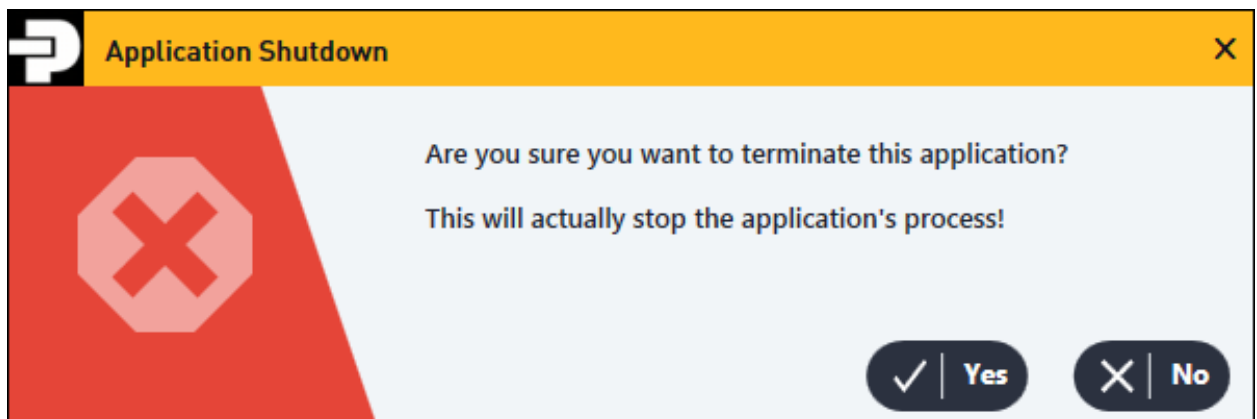
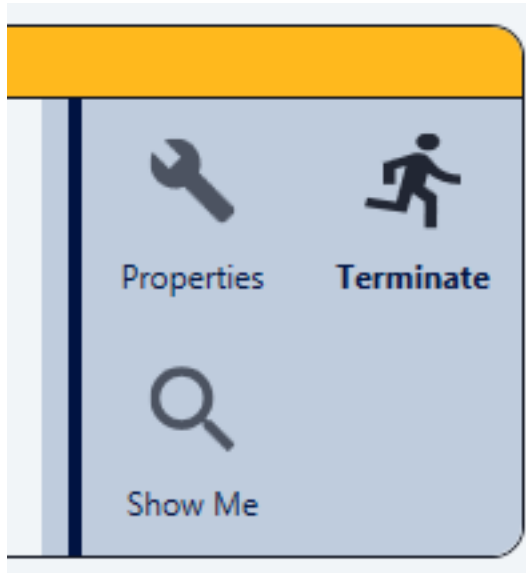
- The virtual CAN bus connection (the *Virtual* tab seen above) is currently a stub (non-existent).
- Some applications (e.g. CANsniff) may make more than one RP1210 client connection and all of the RP1210 client connections associated with a particular instance of an



application may need to be updated to the same CAN bus in order for the application to function properly.

6.2.5.3. Terminate

The **Terminate** option can be used to stop the connected application's process:



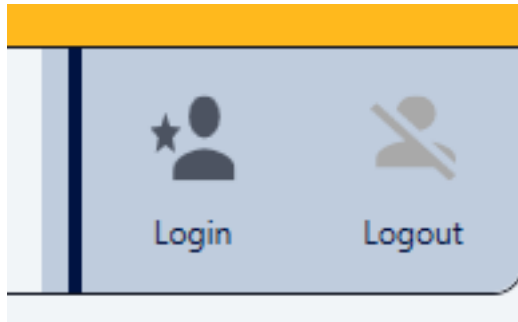
This terminates any logical client connections and then shuts down the application's process.

6.2.5.4. Show Me

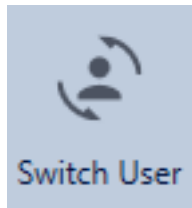
The **Show Me** option can be used to give visual focus to the selected application's process.

6.2.6. User Access Control

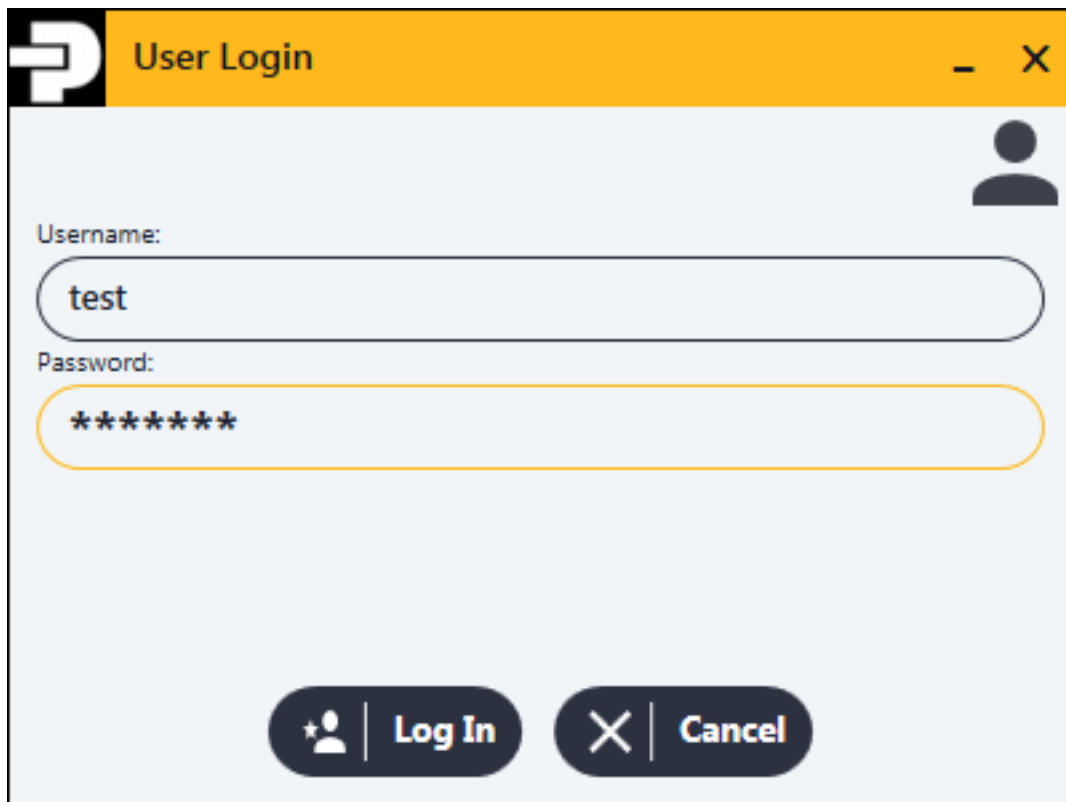
The dashboard provides the ability to log in to the PVSG. By default, the anonymous user is logged in. The current user will be logged out whenever an attached management device is disconnected, or the PVSG is rebooted. The **Login** and **Logout** buttons may be used to log in as a new user, or log out as the current user respectively:



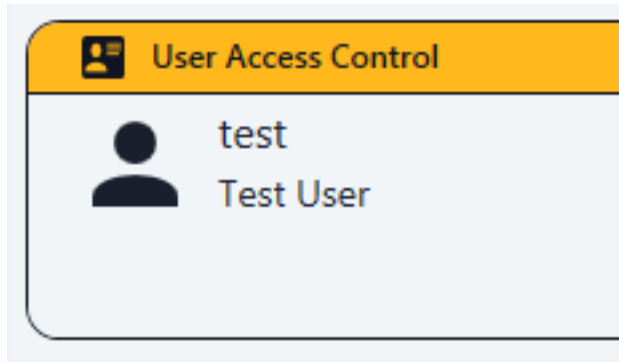
If a user is already logged in, the **Switch User** option appears:



When logging in (or switching user), the **User Login** window is displayed:

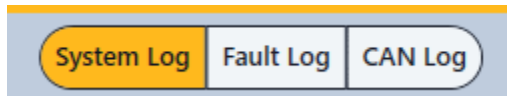
A screenshot of the 'User Login' window. It has a title bar with the Parker logo and the text 'User Login'. Inside, there is a 'Username:' label followed by a text input field containing 'test'. Below that is a 'Password:' label followed by a password input field containing seven asterisks. At the bottom, there are two buttons: 'Log In' with a person icon and 'Cancel' with an 'X' icon.

Entering the correct username and password will log the respective user in. Entering an incorrect username and password will log in the anonymous user.



6.2.7. Logs

The **Logs** tab provides an interface to retrieve logs, including system logs, fault logs, and CAN logs. The log type can be selected using the toolbar buttons:



Refresh the logs by clicking the **Request** button in the top right corner.

| Level | Source | Time | Username | Detail |
|-------------|---------------|----------------------|----------|---|
| Information | Configuration | 23-Apr-2019 10:46 AM | KN10751 | Configuration was updated. |
| Information | Configuration | 23-Apr-2019 10:10 AM | KN10751 | Configuration was updated. |
| Information | Configuration | 23-Apr-2019 10:07 AM | KN10751 | Configuration was updated. |
| Information | Configuration | 23-Apr-2019 10:03 AM | KN10751 | Configuration was updated. |
| Information | Configuration | 22-Apr-2019 3:58 PM | KN10751 | Configuration was updated. |
| Information | Configuration | 18-Apr-2019 9:52 AM | kn10751 | Configuration was updated. |
| Information | Configuration | 01-Jan-1970 12:01 AM | kn10751 | Configuration was updated. |
| Information | System | 01-Jan-1970 12:00 AM | system | The system has been successfully upgraded to 1051642, version 0.27.362. |
| Information | Configuration | 15-Apr-2019 2:44 PM | kn10751 | Configuration was updated. |
| Warning | System | 02-Apr-2019 3:43 PM | system | XMC reset was detected. |
| Critical | System | 02-Apr-2019 3:43 PM | system | The XMC has gone missing and will be reset to attempt recovery. |
| Warning | System | 02-Apr-2019 10:34 AM | system | XMC reset was detected. |
| Critical | System | 02-Apr-2019 10:34 AM | system | The XMC has gone missing and will be reset to attempt recovery. |
| Information | Configuration | 01-Apr-2019 1:47 PM | KN10751 | Configuration was updated. |
| Information | Configuration | 16-Feb-2000 12:52 AM | KN10751 | Configuration was updated. |
| Information | Configuration | 10-Feb-2000 11:14 PM | KN10751 | Configuration was updated. |
| Warning | System | 01-Jan-1970 12:02 AM | system | XMC reset was detected. |
| Critical | System | 01-Jan-1970 12:02 AM | system | The XMC has gone missing and will be reset to attempt recovery. |
| Warning | System | 01-Jan-1970 12:02 AM | system | XMC reset was detected. |

The listing of logs are displayed in reverse chronological order.

To export logs to a .csv file, select **Export** button in the top right corner.

For system logs, the following events are logged:

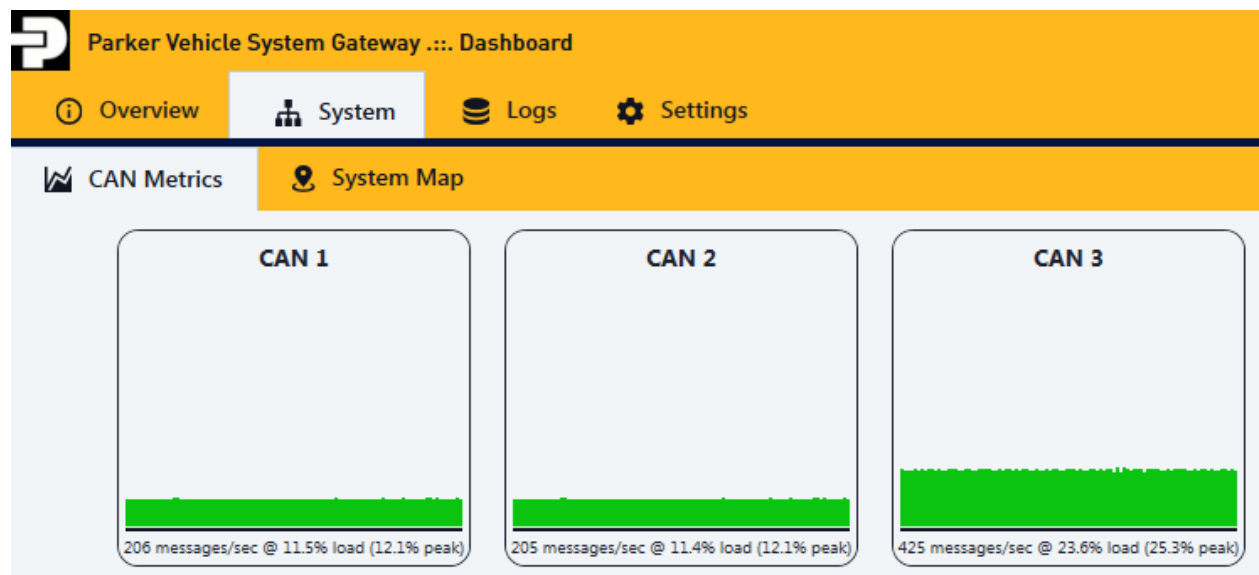
- Configuration failed to load
- eMMC failed to mount
- Softdog related events (server services/router (XMC)/power control (M0) gone missing)
- Configuration updated (including username of user who performed the update)
- System update events
- Shutdown provider stopped
- USB service stopped
- Custom application errors

For details on the data logged within a fault log, see the **Fault Logging** section under **Configuration Tool**. Likewise, see the **CAN Logging** section under **Configuration Tool** for more details on CAN logging.

6.2.8. System

The **System** tab provides access to CAN metric information and the system map.

6.2.8.1. CAN Metrics



This shows the number of CAN messages being received by the PVSG per second, for each available CAN bus. The approximate bus load is also shown as a percentage, given the configured baud rate. The traffic graph uses the following colours:

- Green. 0% <= CAN bus load < 40%
- Yellow. 40% <= CAN bus load < 70%
- Red. 70% <= CAN bus load <= 100%



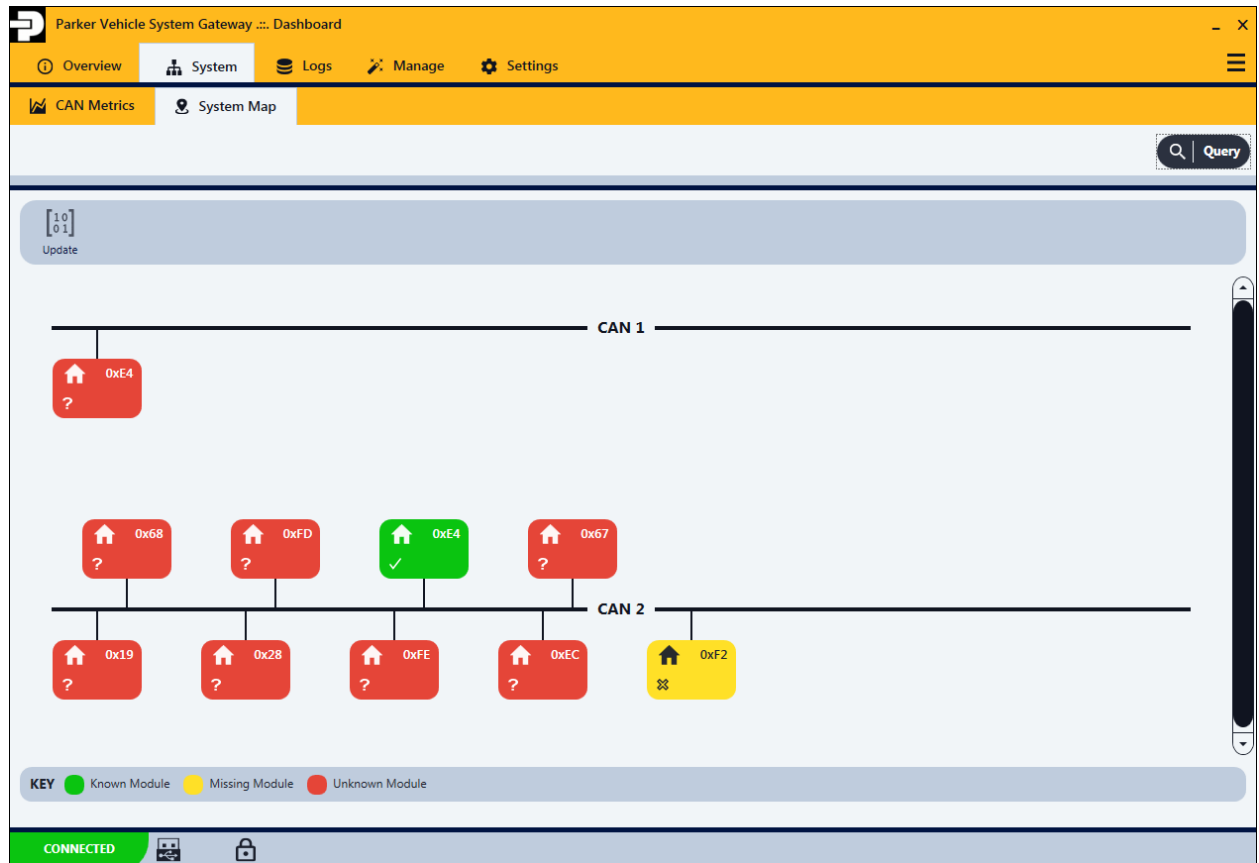
Note: The CAN bus metric colour scheme is merely used to provide a visual aid. It does not provide any indication as to the state of the system and should not be used as such.



6.2.8.2. System Map

The **System Map** tab shows a visual representation of the modules connected to the system in which the currently attached PVSG resides. Clicking **Request** retrieves the module data currently stored by the PVSG. Clicking **Probe** forces the PVSG to detect new modules first.


Modules are detected by the PVSG making a "J1939 global request for address claim" on all configured CAN buses (see the "Configuration Tool" section for details on how to configure module detection). Additional information is retrieved from modules which respond, where possible.




The icons shown within a module card differ depending upon the state of the module:

| Icon | Description |
|------|--|
| | Module is known, and is expected on the system. |
| | Module is not known, and is not expected on the system. |
| | Module is missing from the system. |
| | The configuration holds software for this module, and it can be updated. |


Clicking on a particular module shows additional information, where available:


Module Information




0x2E on CAN 2


Bus: CAN 2
Address: 0x2E


Component Identification

Model: 161561
Serial Number: 81985529216486895

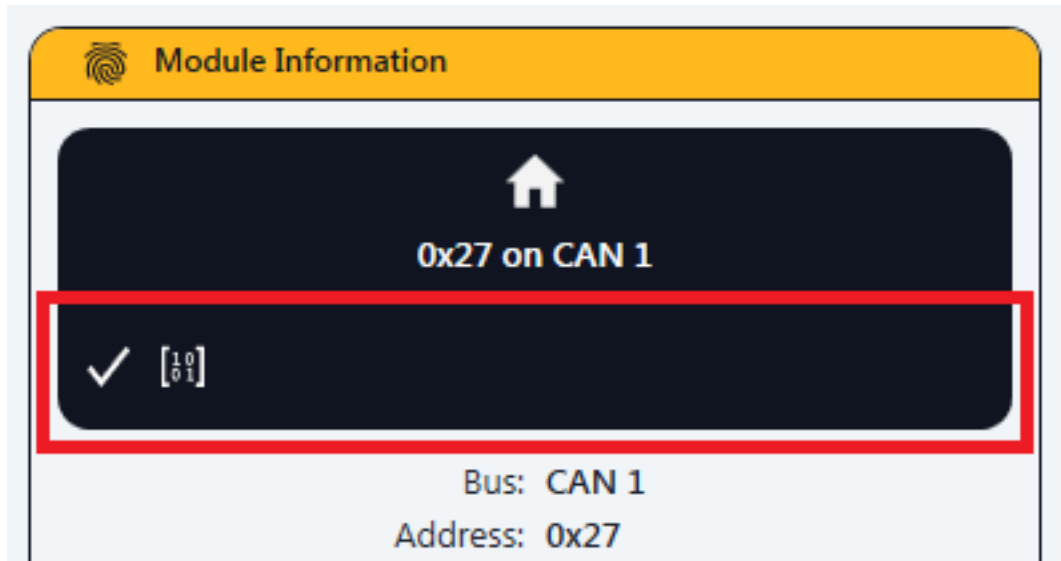

Software Identification

Active: Application 1
Application 1: DPS-C Construction X,Y,Z
Application 1 Software: 971611
Application 1 Version: 1.18 Build 34
Application 2: DPS-C Agriculture
Application 2 Software: 971688
Application 2 Version: 1.00 Build 12
Boot Block Software: 971602
Boot Block Version: 1.02 Build 17
Images Software: 971620




J1939 NAME

Arb Address Capable 0
Industry Group 3
Vehicle System 0
Vehicle System Instance 0
Function 34
Function Instance 0
ECU Instance 0

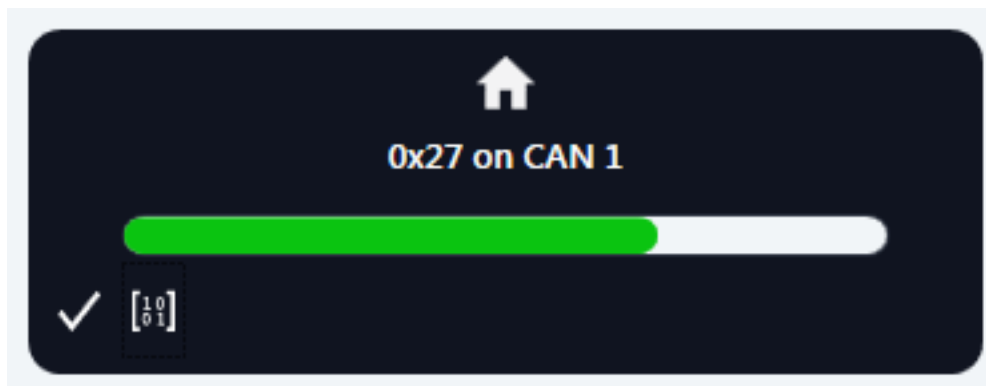
If a module is "known" to the system (i.e. it is present in the configuration), an extra section appears under the module header, known as the **Module Toolbox**:



Several icons/buttons are available (note that the module toolbox contents are dynamic and different icons/buttons will appear depending on the state of the module and the installed configuration):

| Icon/Button | Function (click) | Description |
|---|-------------------------|---|
|  | None | Indicates that the identity of the detected module matches that set in the configuration. |
|  | Updates module software | Only appears if the module ID matches and the module is configured for software updates (i.e. the configuration contains software for this module). When selected, the module will be updated with the software contained within the configuration. |

If an operation is currently in progress on a module, a progress bar is also shown within the module toolbox:



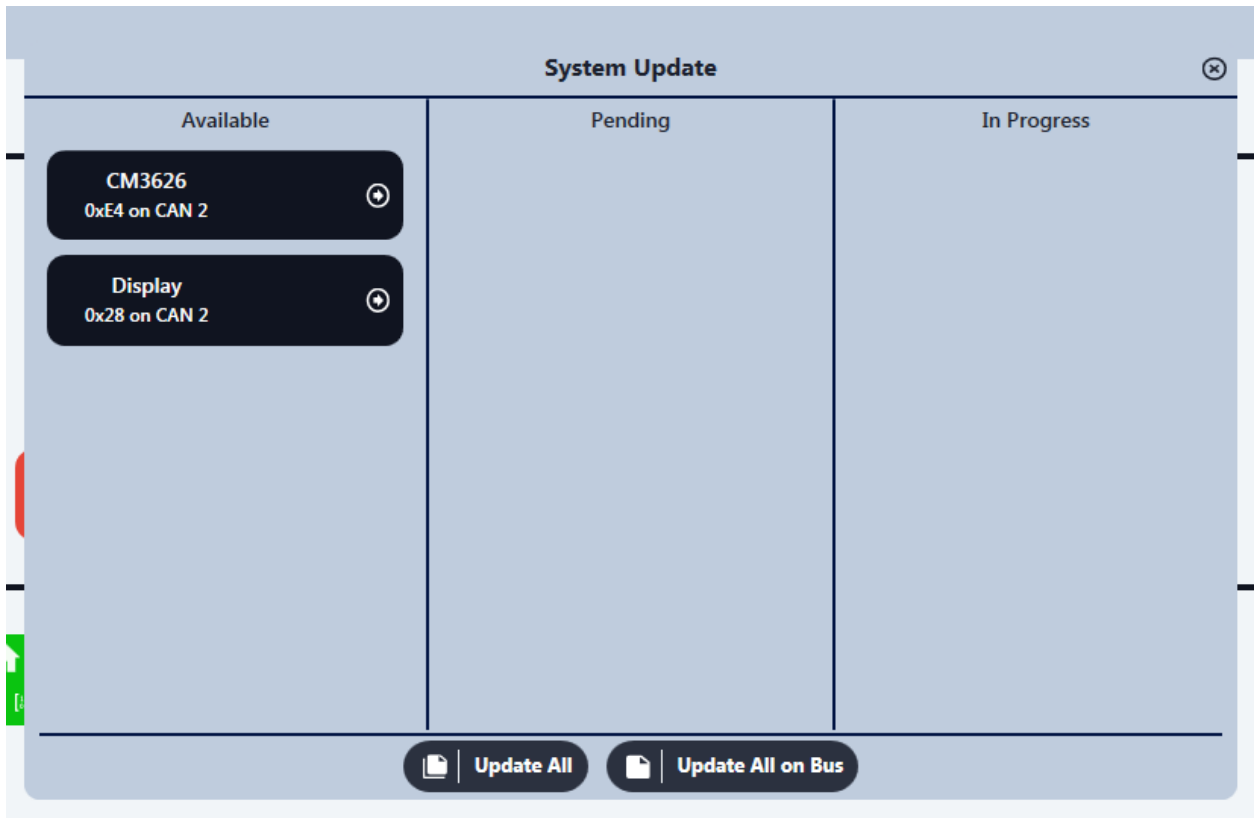
The **System Toolbox** is shown at the top of the system map:



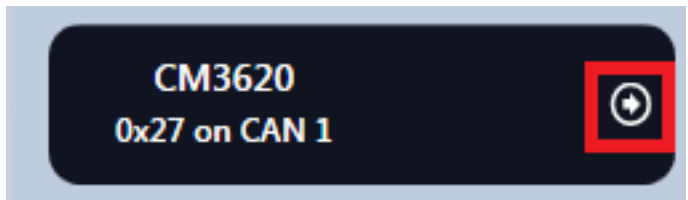
This contains available "global" (to the system) actions.

6.2.8.3. Update

Opens a popup giving access to system software update options:



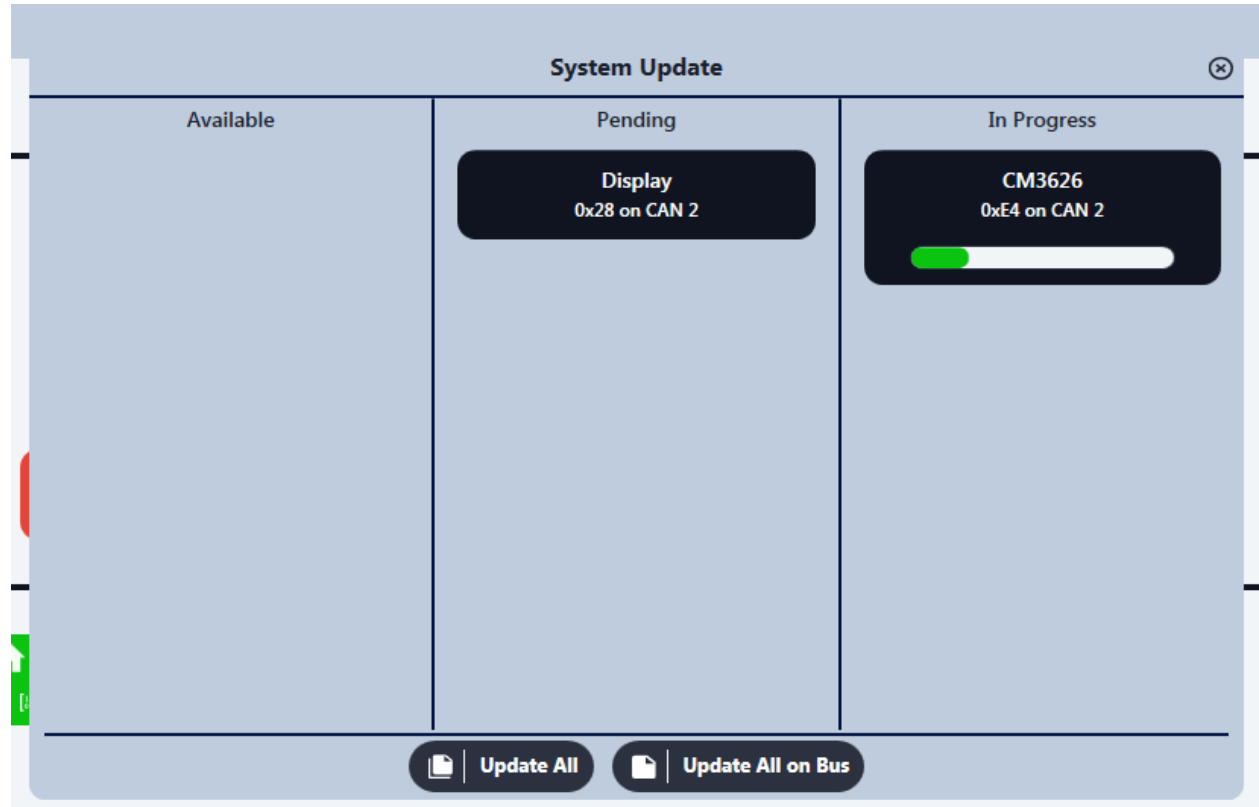
Modules which are available for software update are shown in the **Available** column. Individual modules can be updated by clicking the arrow on the module info within the **Available** column:





Using the **Update All** and **Update All on Bus** buttons at the bottom of the popup, all eligible modules and all eligible modules on a chosen CAN bus can be updated respectively.

Operations currently in progress are shown under the **In Progress** column. Operations which cannot start yet are shown within the **Pending** column.



Concurrent operation policies are controlled via the configuration tool.

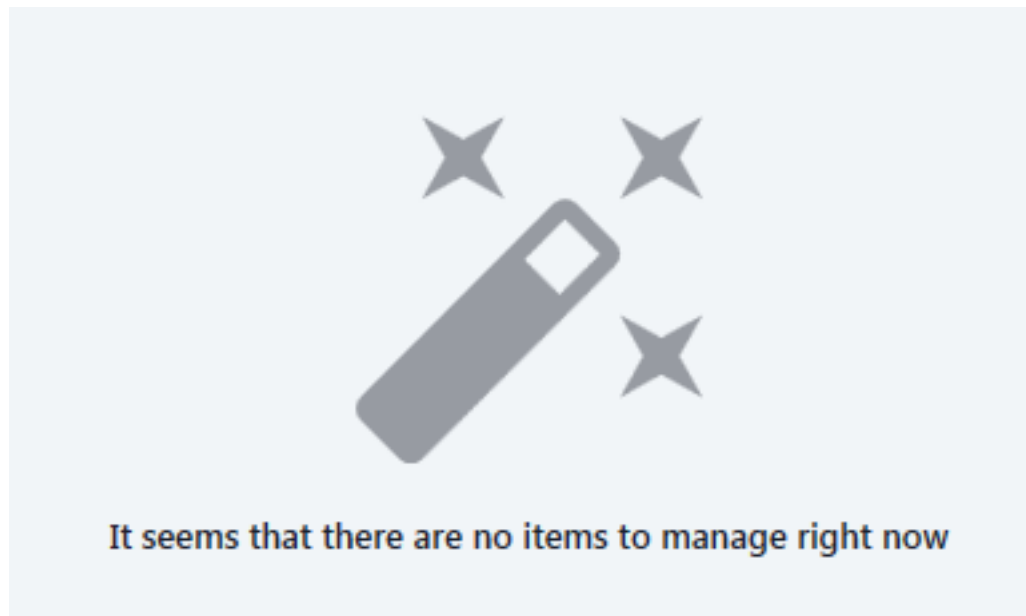
System module update operations are logged in the system log (refer to **Logs** section above). In the case of failure, the meaning of the returned status codes are dependent upon the protocol in use.

6.2.8.4. Vansco Flashload-over-CAN

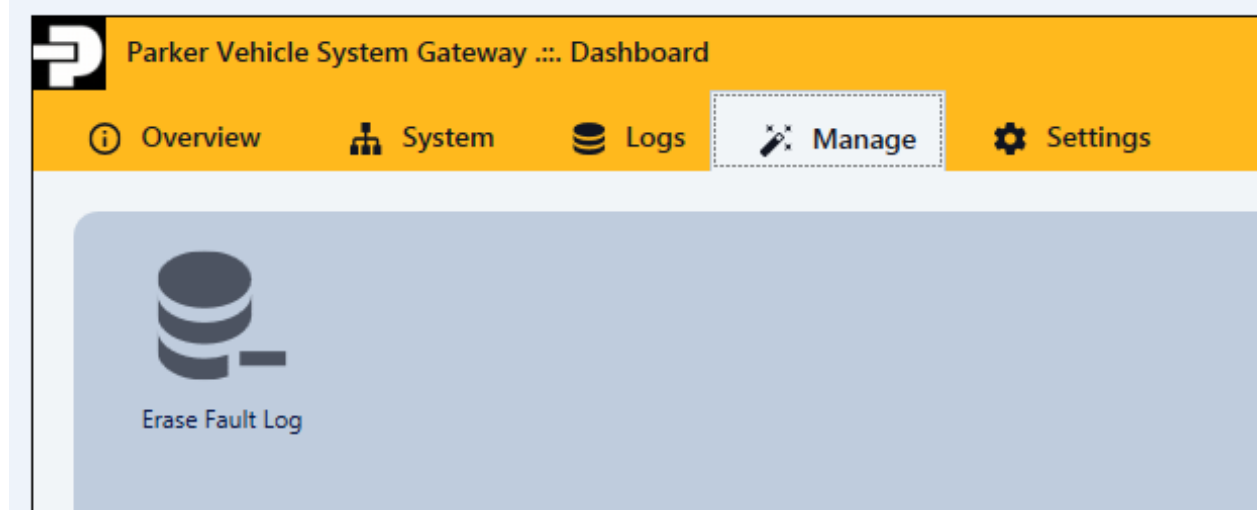
| Code | Description |
|------|---|
| -9 | The system module software file header was malformed. |
| -61 | There was insufficient memory available to perform the operation. |
| -61 | The system module software file was empty. |
| -125 | Operation cancelled. |
| -131 | A general error occurred which could not be recovered from. |

6.2.9. Manage

Management options are available under the **Manage** tab. If no management options are available for the currently logged in user, the following is seen:



To access management options, log in as a user (if user management is not configured, all possible management options are displayed without a user being logged in).

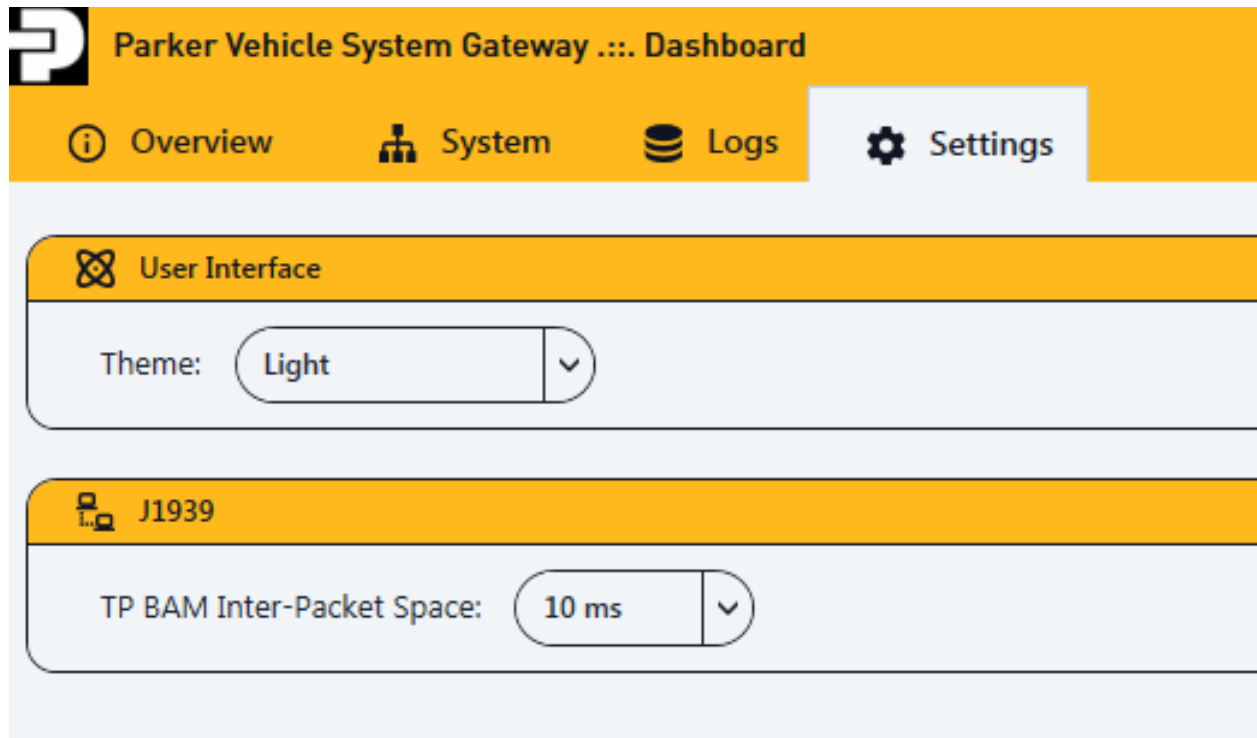


Possible management options are listed below.

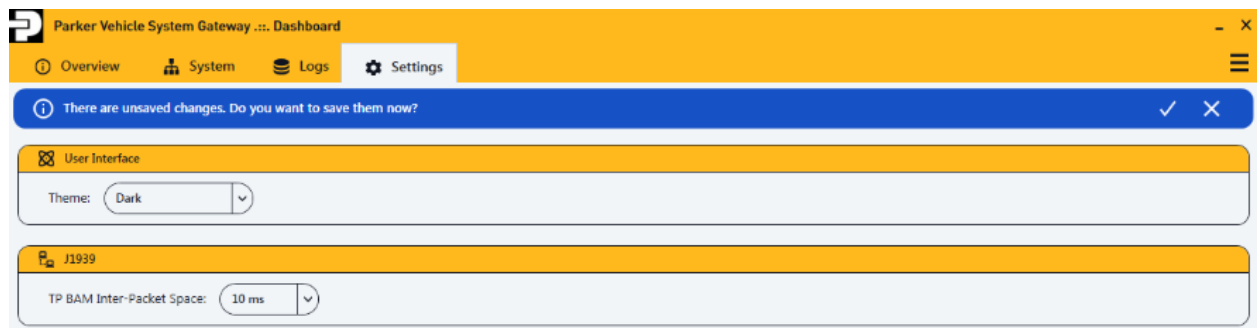
| Option | Description |
|-----------------|---|
| Erase Fault Log | Erases all logs currently stored in the fault log database. This action cannot be undone. |

6.2.10. Settings

The **Settings** tab gives access to available user settings:



When settings are changed, the user is prompted to save them:



The following settings are available:

- User Interface: Theme. This sets the current visual theme from two available options:
 - Light
 - Dark
- J1939: TP BAM Inter-Packet Space: Sets the time interval between consecutive data packets on a J1939 Transport Protocol Broadcast Announce Message transmission. The J1939 standard states that this should be set between 50ms and 200ms. 10ms is also provided as an optional performance enhancement at the user's discretion.



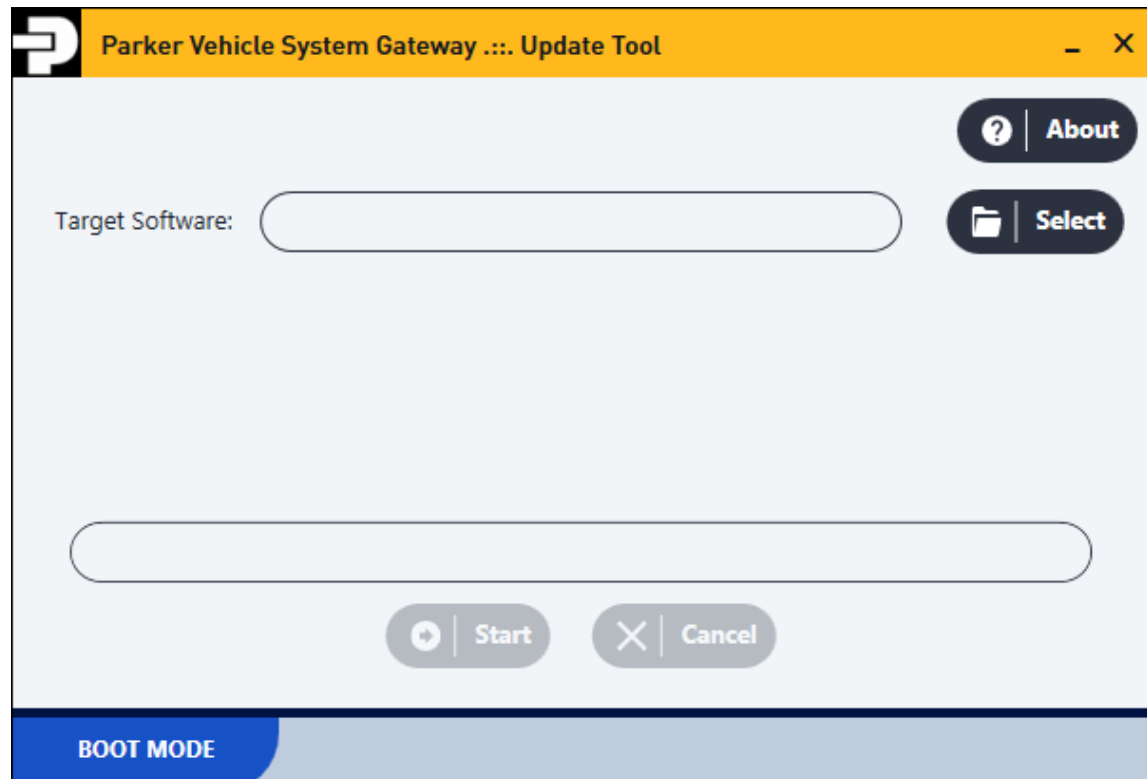
Note: Once changes are saved, they are not applied until the relevant PC software component is restarted.

6.3. Update Tool

The update tool may be used to update the version of the software (1051642) installed on the PVSG. The update tool requires a USB connection to the PVSG to update.

6.3.1. Accessing the Update Tool

The update tool can be accessed by using the **PVSG Update** shortcut added to the Windows start menu by default as part of the installer (1051605) under **Parker > ECD > PVSG**.



In order to update a PVSG, with the PVSG connected, run the update tool, select the appropriate file and click Start. Then follow the on screen instructions to complete the update process.



Note: The update tool also provides a command line interface. Locate pvsgupd.exe (installed as part of the installer 1051605), and run "pvsgupd.exe -h" to get a listing of all of the available commands.

6.3.2. Update Steps

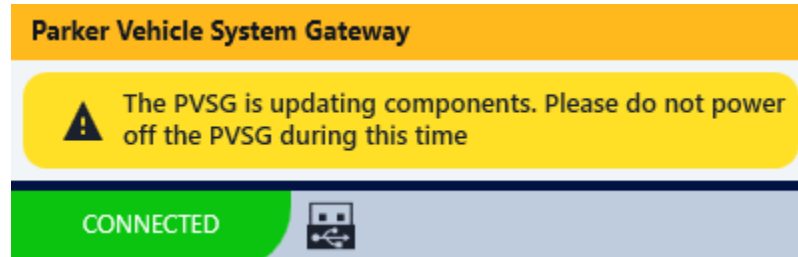
The following upgrade procedure can be used to update PVSG software alongside PVSG PC software.

1. Read configuration from PVSG with currently installed PVSG PC software and save configuration. This configuration can be used on PCs with the same PVSG PC software versions installed and can also be used on laptops with newer versions of PVSG PC software.
2. Install newer version of 1051605 PC Software.

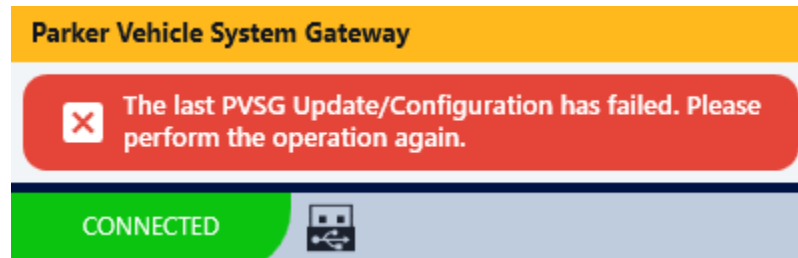


3. Read configuration from PVSG and save configuration. Save this config as precautionary or if step 1 was missed.
4. Update PVSG.
5. Send configuration from Step 1 to PVSG.

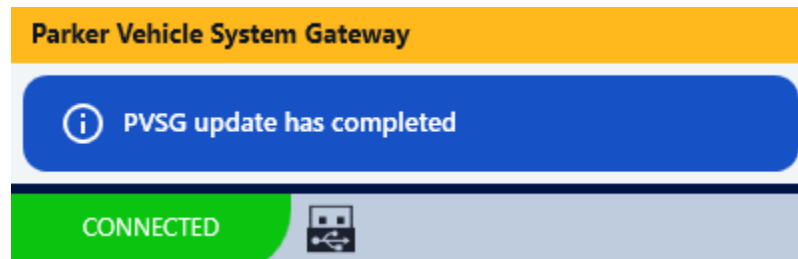
Depending on which PVSG software version the PVSG is being updated to, the following pop may appear at the bottom right of the screen:



If the reprogram fails, a 2:8 error code will appear along with the following pop up:



If the reprogram succeeds, the following pop up will be shown:



To confirm that your reprogram was successful, verify that the "PVSG update has completed" pop up appears and that no new errors appear in the dashboard.

6.3.3. Update Tool Error Codes

Under some conditions, the PVSG update tool generates numeric error codes. A brief description of the general fault area is given to the user, but the exact meaning of the error is intentionally hidden since providing the error details would likely expose information surrounding our update procedure which should ideally remain confidential to Parker.

The error codes are dynamically formed from a base code, and a specific error. The base codes currently in use are:

| Base Error Code | Description |
|-----------------|-------------------------------------|
| 0x1000 | Error downloading bootloader. |
| 0x2000 | Error downloading device tree blob. |
| 0x3000 | Error downloading RAM filesystem. |

| Base Error Code | Description |
|-----------------|------------------------------|
| 0x4000 | Error downloading kernel. |
| 0x5000 | Error jumping to address. |
| 0x6000 | Error missing security keys. |
| 0x7000 | Error missing files. |
| 0x8000 | General bootstrap error. |

The specific error codes currently in use are:

| Specific Error Code | Description |
|---------------------|---|
| 1 | Operation not permitted. |
| 2 | No such file or directory, or the expected data is missing. |
| 5 | General I/O error. |
| 0x13 (19) | No device. |
| 0x16 (22) | Invalid argument. |
| 0x3D (61) | No data. |
| 0x46 (70) | General communication error. |

Error codes can be decoded as per the following examples.

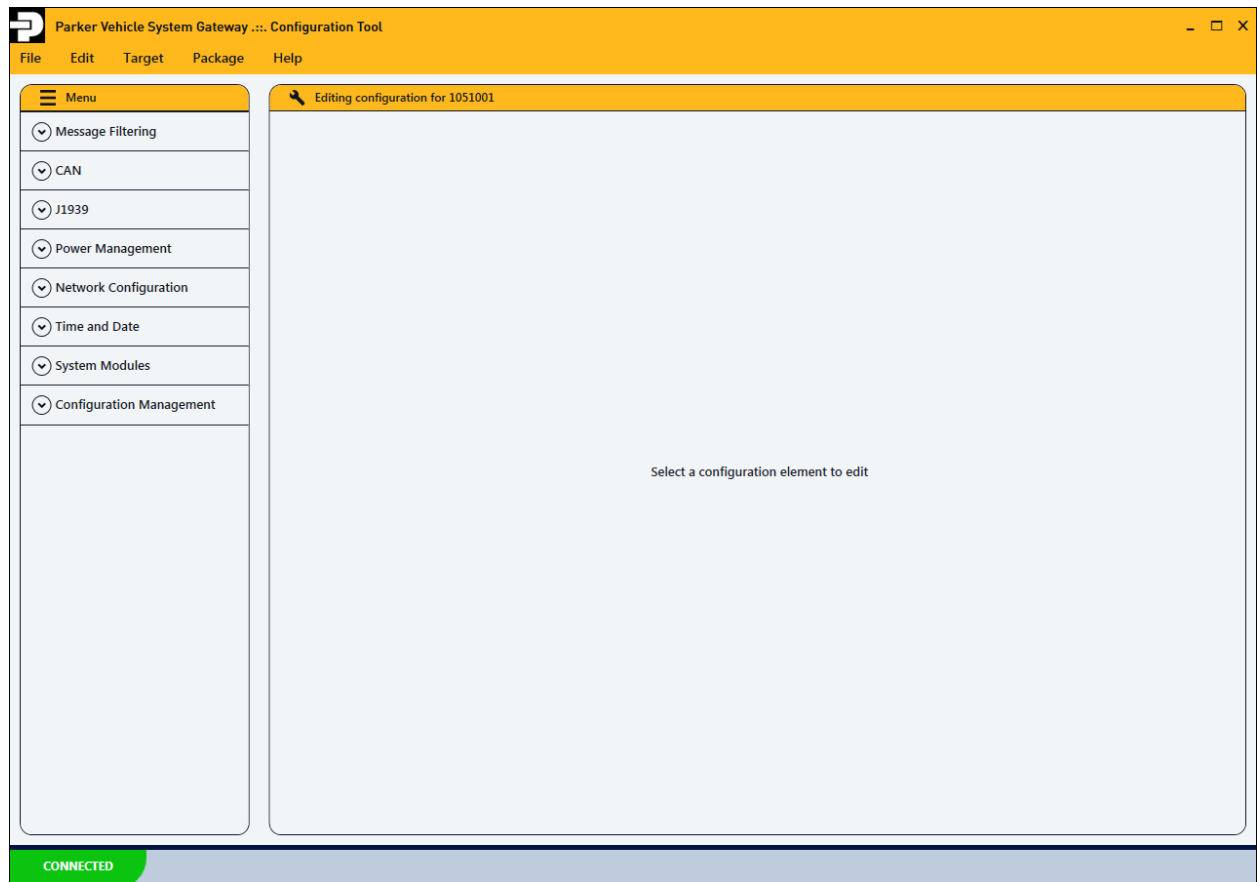
1. Error 4166. $4166 = 0x1046$, therefore base code is $0x1000$, specific code is $0x46 = 70$. Hence, error 4166 is a general communication error which occurred when downloading the bootloader.
2. Error 16454. $16454 = 0x4046$, therefore base code is $0x4000$, specific code is $0x46 = 70$. Hence, error 16454 is a general communication error which occurred when downloading the kernel.

6.4. Configuration Tool

The PVSG is configured using the configuration tool.

6.4.1. Accessing the Configuration Tool

The configuration tool can be accessed by using the **PVSG Configuration** shortcut added to the Windows start menu by default as part of the installer (1051605) under **Parker > ECD > PVSG**. Configurable elements are accessible via the menu system on the left side of the tool and are organized by area.




Note: The configuration tool also provides a command line interface. Locate pvsgcfg.exe (installed as part of the installer 1051605), and run "pvsgcfg.exe -h" to get a listing of all of the available commands.



Note: The configuration tool will show/popup (wherever applicable) a symbol on its interface to bring attention to:

- an error (with a red color scheme),
- a warning (with a yellow color scheme), or
- information (with a blue color scheme)

Further information can often be found on the symbol tooltip (place the mouse cursor over the symbol to access). Some examples:



Edit Message Filter

One or more validation errors are present in the entry

Message Identifier

Message Identifier: 0xFFFF00

J1939 Priority: 0

J1939 PGN: 0xFFFFff ▲

Enter a value in the range 0x0 - 0x3FFFF

J1939 Source Address: 0x0

Wireless Configuration

The use of WEP-based security is strongly discouraged and should only be used if absolutely necessary. If possible, you should consider switching to another security mode.

Antenna: **INTERNAL** EXTERNAL AUTO

Security Key: abcde

6.4.2. Creating/Editing Configurations

A blank configuration is created by default every time the tool is started. To destroy any unsaved changes and start a new configuration, select **File -> New**.

6.4.2.1. Variants

The configuration tool supports multiple variants of the PVSG product. The configuration tool allows all options and features to be configured irrespective of which variant of PVSG is connected or selected in the Variant Manager. If a feature or option is configured which is not supported on the variant on which the configuration is deployed, the particular feature or option will be disabled and the configuration will fall back to a default state.

In order to assist with understanding the particular features available on a particular variant, the **Variant Manager** is available. Open the **Variant Manager** by selecting **Variant** from the menu bar and then the **Summary** option. This can also be accessed using the icon in the bottom right-hand corner of the tool.

Variant Manager

Selected variant

1051001
1051002
1051003
1051004
1051005
1051006

Overview

Conflicts

✓
5 CAN ports

✗
0 LIN ports

✗
0 J1708 ports

✓
4 GiB storage

i
'Wireless Core' is available on this variant with an extra licence

✓
'Fault Logging' is available on this variant




✓
'Module Management' is available on this variant

✓
'System Module Update' is available on this variant

✓
'CAN Router' is available on this variant








✓
'DLA' is available on this variant



















































































The **Overview** view shows the features which are available on the selected variant. A feature can be configured in one of 3 states, per the table below.

| Feature State | Description |
|---|---|
| Enabled  | The feature is available by default on the selected variant. |
| Enabled with License  | The feature is not available by default on the selected variant, but can be enabled with the addition of a license. |
| Disabled  | The feature is not available on the selected variant. |

The **Conflicts** view shows any features which have been configured in the configuration but are not available on the selected variant.

The following is a table of supported variants, and features supported:

| Features / Variant | 1051001 | 1051002 | 1051003 | 1051004 | 1051005, 1051011 and 1051012 | 1051006 | 1051007 |
|--------------------|---|---|---|---|---|---|---|
| 5 - CAN |  |  |  |  |  |  |  |

| Features / Variant | 1051001 | 1051002 | 1051003 | 1051004 | 1051005, 1051011 and 1051012 | 1051006 | 1051007 |
|---|---|---|---|---|---|---|---|
| 1 - J1708 |  |  |  |  |  |  |  |
| Internal Storage | 4 GiB | 4 GiB | 4 GiB | 4 GiB | 4 GiB | 4 GiB | 4 GiB |
| Wireless Core |  |  |  |  |  |  |  |
| - External Antenna |  |  |  |  |  |  |  |
| Fault Logging |  |  |  |  |  |  |  |
| Module Management |  |  |  |  |  |  |  |
| - System Module Update |  |  |  |  |  |  |  |
| CAN Router |  |  |  |  |  |  |  |
| - The CAN router configuration also applies to messages that originate from RP1210. |  |  |  |  |  |  |  |
| DLA |  |  |  |  |  |  |  |
| Custom Applications |  |  |  |  |  |  |  |
| Custom Programming Plugins |  |  |  |  |  |  |  |
| Sleep Mode 2 Supported |  |  |  |  |  |  |  |
| CAN Logging | | | | | | | |



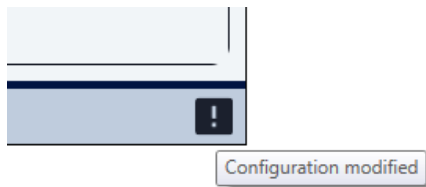
Note: The CAN Logging feature is still under development and is not yet available.

6.4.2.2. Opening and Saving Configurations

Configurations can be opened/saved using the **File -> Open** and **File -> Save** menus respectively. The .pvsgc format is used for configuration files (See File Types table above); this format is a proprietary format belonging to Parker. Note that these files cannot be edited manually and should only be modified using the configuration tool.



Unsaved changes to the current configuration are indicated by an icon in the status bar (bottom right corner):



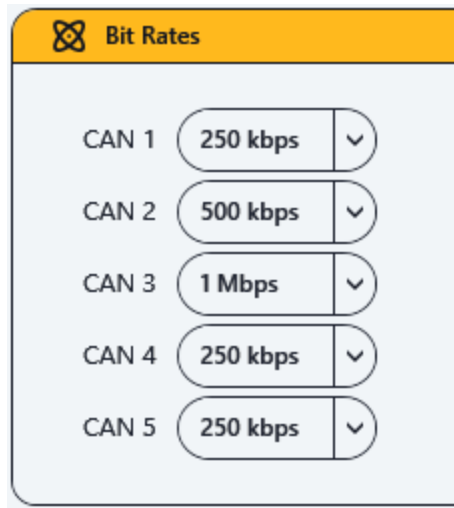
6.4.3. Keyboard Shortcuts

The following 'special' keyboard shortcuts can be used:

| Keyboard Shortcut | Area Active | Function |
|-----------------------------------|----------------------------|---|
| Ctrl + S | Global (all areas) | Saves the current configuration (equivalent to a File > Save). |
| Ctrl + C | Message filter list editor | Copies the currently selected message filter entry/entries. Note that groups of entries may be selected by selecting the first entry, holding the SHIFT key and then selecting the last entry. |
| Ctrl + V | Message filter list editor | Pastes any message filter entries on the clipboard into the current list. |
| Del | Message filter list editor | Deletes the currently selected message filter entry/entries. Note that groups of entries may be selected by selecting the first entry, holding the SHIFT key and then selecting the last entry. |
| Ctrl + A | Message filter list editor | Selects all message filter entries in the current view. |
| Ctrl + left mouse click(s) | Message filter list editor | Allows multiple non-contiguous message filter entries to be selected/deselected for further operation (copy, delete, etc.). |
| Shift + left mouse click | Message filter list editor | Allows multiple contiguous message filter entries to be selected/deselected for further operation (copy, delete, etc.). |

6.4.4. CAN Configuration

The **CAN configuration** menu allows you to change the CAN bus speeds on all five CAN ports. The PVSG supports 250, 500, and 1000 kbps CAN bit rates.



Bit Rates

| | | |
|-------|----------|---|
| CAN 1 | 250 kbps | ▼ |
| CAN 2 | 500 kbps | ▼ |
| CAN 3 | 1 Mbps | ▼ |
| CAN 4 | 250 kbps | ▼ |
| CAN 5 | 250 kbps | ▼ |

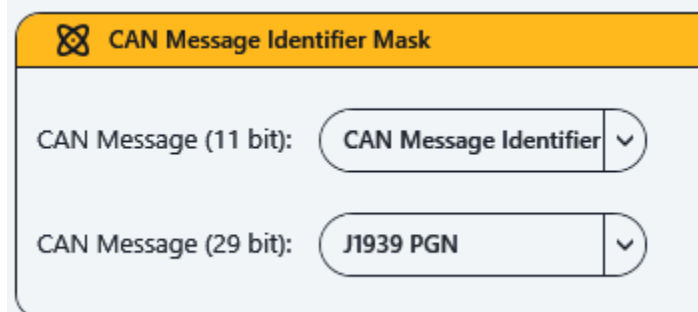
6.4.5. Message Filtering

The PVSG can route messages from one CAN port to any other CAN port based on message filters. These filters are configured in the **Message Filtering** menu.

6.4.5.1. Options

The **Message Filtering Options** section allows you to set **CAN Message Identifier mask** (criteria), and choose **Filter Types** for the message filters.

CAN Message Identifier Mask options allow users to specify which parts of a CAN Message ID is used when the PVSG is determining which messages to route. There is one mask type for Standard 11-bit and four mask types for Extended 29-bit CAN messages.



CAN Message Identifier Mask

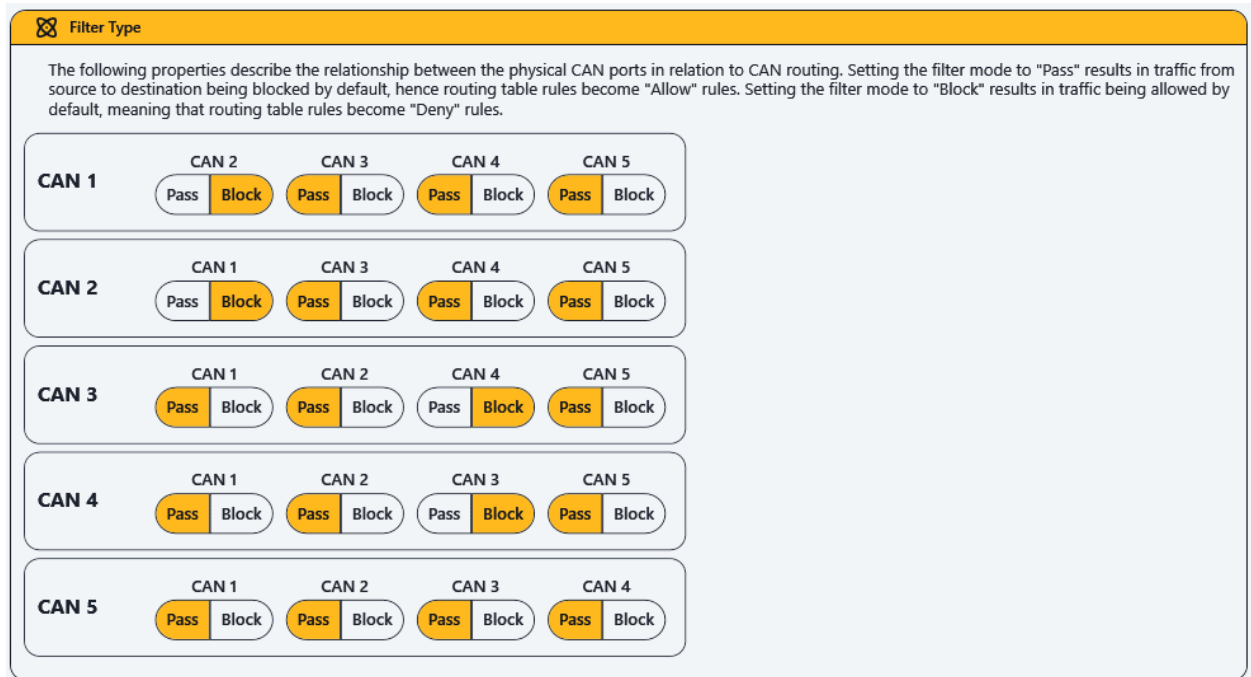
| | | |
|-----------------------|------------------------|---|
| CAN Message (11 bit): | CAN Message Identifier | ▼ |
| CAN Message (29 bit): | J1939 PGN | ▼ |

| CAN Message ID Mask Types | Match Description (All definitions as specified in SAE J1939-21) |
|--|--|
| J1939 PGN | Only the J1939 PGN portion of the CAN message ID is used for matching. |
| J1939 PGN and Source Address | Only J1939 PGN and source address of the CAN message ID is used for matching. |
| J1939 PGN, Source Address and Priority | Only J1939 PGN, source address, and priority of the CAN message ID is used for matching. |
| CAN Message Identifier | All parts of the CAN Message ID is used for matching. |

There are two ways to define the messages filters between two CAN ports. This is done via **Filter Types: Pass filters** and **Block filters**.

| Filter Types | Description |
|---------------|--|
| Pass Filters | If pass filter type is used, only CAN messages that match one of the message filters will be routed from CAN A to CAN B. No other messages will be routed. |
| Block Filters | If block filter type is used, CAN messages that match one of the message filters for CAN A to CAN B will not be routed (blocked) from CAN A to CAN B. All other messages will be routed. |

For example, in the image below, it shows that CAN 1 is set to block filter type between itself to CAN2, but pass filter type between itself to CAN 3, 4, and 5. All messages seen on CAN 1 are sent to CAN 2 so long as the messages don't match a message filter entry set between CAN 1 to CAN 2. Messages seen on CAN 1 are not sent to CAN 3, 4 or 5 unless they there is a message filter entry set between CAN 1 to the corresponding CAN.



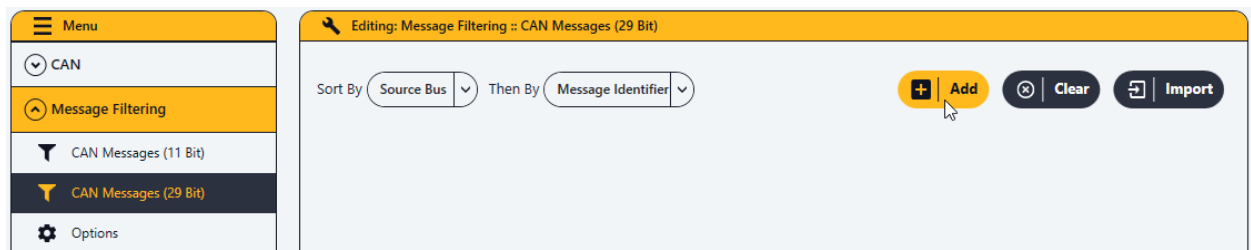
6.4.5.2. Message Filters

Filters for CAN routing are added to the configuration via the menus **CAN messages (11 Bit)** for standard CAN messages and **CAN messages (29 Bit)** for extended CAN messages.

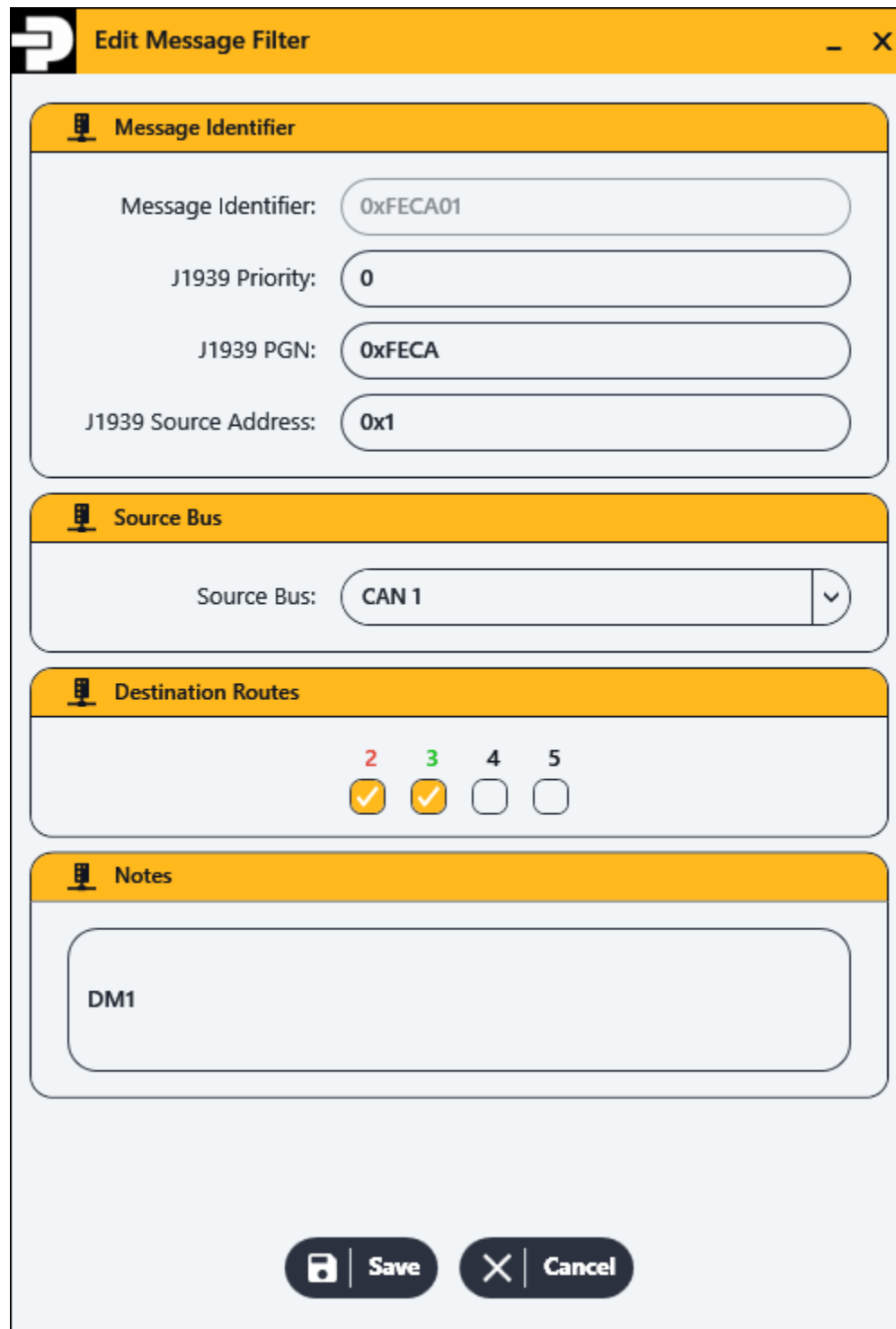
6.4.5.3. CAN Messages (11 Bit) and CAN Messages (29 Bit) Filters


To add a new message filter click on the **Add** button while in either CAN Message screen.


To edit or delete a message filter click on the **Edit** or **Delete** button on the entry.



The Edit window is broken up four sections. The *Message Identifier* section allows you to edit the filters message ID data based on the CAN Message Identifier Mask selected in the Options screen. The *Source Bus* section allows you to choose the source bus for the messages filter. The *Destination Routes* section allows you to choose the destination bus for this message filter. And the *Notes* section allows you to enter any notes for the message filter.




Edit Message Filter
- X



Message Identifier

Message Identifier:

J1939 Priority:

J1939 PGN:


J1939 Source Address:


Source Bus

Source Bus:

CAN 1

▼


Destination Routes

2

3

4


5

☒


☒


☐

☐


Notes

DM1

 Save

 Cancel



In the example above, J1939 PGN and J1939 Source Address are the only fields in the *Message Identifier* section that are modifiable since the CAN Message Identifier Mask is set to J1939 PGN and Source Address only. This message filter is for messages appearing on CAN 1 and will route messages that match this filter to CAN 3 but will block them to CAN 2.

6.4.5.4. Message Filtering Notes

- J1939 large messages (data greater than 8 bytes) are transmitted via a connection between two devices using multiple sequence packets and multiple data packets using J1939 messages defined in the SAE J1939-21 specification (see spec for more details). The PVSG will handle routing of these large messages for you so long as the large message message ID matches the filters and filters types for the CAN port.
- Tracking of active J1939 large messages is required to successfully route them between the source and destination CAN port. Once these large messages connections are completed or aborted, tracking of the large message is no longer required. Tracking is done internally to the PVSG and only active large message connections are tracked. Routing of future large messages will be impacted if the message filtering configuration is too "loose" for the system. Meaning if any large messages are allowed to be routed to another CAN bus that does not contain the corresponding destination device and therefore never properly completed or terminated.
- To setup the PVSG to be a "repeater" between two CAN ports (no blocking or tracking), set the filter type to Block type in both directions and do not specify any block message filters between the two CAN ports in either direction.
- It is possible to route messages from one CAN port bus speed to a different one, so long as the port being routed to can handle the extra bus utilization.

Any message filter errors will be displayed at the top, and the offending entries are highlighted in red.

Editing: Message Filtering :: CAN Messages (29 Bit)

Sort By Source Bus Then By Message Identifier + Add ✕ Clear ⇄ Import

Errors

Invalid entries:
Id 0x0 does not have a destination route

| | | | | | | | | | |
|--|---|--|------------|--------------------------|--------------------------|--------------------------|--------------------------|-------|----------------|
| | CAN Identifier | | Source Bus | Destination Routes | | | | Notes | Edit Delete |
| | 0x00000000 | | CAN 1 | 2 | 3 | 4 | 5 | | |
| | J1939 Priority PGN Source Address 0x0 0x0000 0x00 | | | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | | |

6.4.5.5. CAN Message Filter Errors

| Error Title | Error Text | Solution |
|-------------------|---|--|
| Duplicate Entries | PGN 0x#### | Locate each erroneous entry and provide a unique entry for each duplicate parameter. |
| Duplicate Entries | PGN 0x####, source address 0x## | Locate each erroneous entry and provide a unique entry for each duplicate parameter. |
| Duplicate Entries | PGN 0x####, source address 0x##, priority 0xA | Locate each erroneous entry and provide a unique entry for each duplicate parameter. |
| Duplicate Entries | Message Id 0x##### | Locate each erroneous entry and provide a unique entry for each duplicate parameter. |
| Invalid Entries | Id 0x##### does not have a destination route | Add a destination route to the message. |
| Invalid Entries | Invalid message with Id 0x##### | 11-Bit CAN: Ensure the message ID is less than 0x00007FF. |
| Invalid Entries | Invalid message with Id 0x##### | 29-Bit CAN: Ensure the message ID is less than 0x1FFFFFFF. |
| Invalid Entries | Message ID 0x##### has priority set when it should not be | <ol style="list-style-type: none"> 1. Confirm that you have the appropriate CAN Message Identifier Mask set for your message filters. 2. Switch the CAN Message Identifier Mask to "J1939 PGN, Source Address and Priority" and remove priority from the offending entry and switch the mask back to "J1939 PGN and Source Address". <ul style="list-style-type: none"> – Alternatively, switch the CAN Message Identifier to "J1939 PGN, Source Address, and Priority" and switch it back to "J1939 PGN and Source Address" then confirm the automatic deletion of the priority bits. |
| Invalid Entries | Message ID 0x##### has priority and/or source address set when they should not be | <ol style="list-style-type: none"> 1. Confirm that you have the appropriate CAN Message Identifier Mask set for your message filters. 2. Switch the CAN Message Identifier Mask to "J1939 PGN, Source Address and Priority and Source Address" and remove source address and/or priority from the offending entry and switch the mask back to "J1939 PGN". <ul style="list-style-type: none"> – Alternatively, switch the CAN Message Identifier to "J1939 PGN, Source Address, and Priority" and switch it back to "J1939 PGN" then confirm the automatic deletion of the source address and priority bits. |



6.4.5.6. Importing CAN Messages (11 Bit) and CAN Messages (29 Bit) Filters

Another option for adding and configuring CAN Messages (11 Bit) and CAN Messages (29 Bit) filters is by creating excel spreadsheets (.xlsx) that follow the requirements below and importing it.

For 11-Bit CAN filters, a workbook tab could look similar to the template shown below.

| | A | B | C | D | E | F | G | H |
|---|-------|------------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------|
| 1 | ID | Source Bus | Destination CAN 1 | Destination CAN 2 | Destination CAN 3 | Destination CAN 4 | Destination CAN 5 | Notes |
| 2 | 0x123 | 1 | | Yes | Yes | | | Hello World |
| 3 | 0x124 | 2 | Yes | | | | | |
| 4 | 0x125 | 3 | | Yes | | | | |
| 5 | 0x126 | 4 | | | Yes | | | |
| 6 | 295 | 5 | | | | Yes | | Test |
| 7 | | | | | | | | |

For 29-Bit CAN filters, a workbook tab could look similar to the template shown below.

| | A | B | C | D | E | F | G | H | I | J | K |
|---|----|----------|----------|----------------|------------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------|
| 1 | ID | Priority | PGN | Source Address | Source Bus | Destination CAN 1 | Destination CAN 2 | Destination CAN 3 | Destination CAN 4 | Destination CAN 5 | Notes |
| 2 | | | 0 0x1200 | 0x20 | 1 | | Yes | | | | Hello World |
| 3 | | | 1 0x1200 | 0xFD | 2 | Yes | | | | | |
| 4 | | | 2 0xDD00 | 0x00 | 3 | | Yes | | | | |
| 5 | | | 3 0xDC00 | | 16 | | | Yes | | | |
| 6 | | | 4 0xFEFA | | 32 | | | | Yes | | |
| 7 | | | 5 0xFEED | | 100 | | Yes | | | | |
| 8 | | | 6 0xE000 | 0xF9 | 2 | Yes | | | | | |
| 9 | | | 7 0xFDC6 | 0xfa | 3 | | | | Yes | Yes | |

In order to utilize this feature, you must first create a properly configured excel spreadsheet (.xlsx) that follow the workbook requirements:

General Workbook Requirements:

- All column headers shown in the templates above must be included into your filter tab.
- If you are importing 11-Bit filters, the workbook must contain a tab named "**11-Bit CAN Filters.**"
- If you are importing 29-Bit filters, the workbook must contain a tab named "**29-Bit CAN Filters.**"
- Numeric values can be entered as decimal or hexadecimal (0x####).
- Valid **Source Buses** are 1, 2, 3, 4 and 5.
- To set a **Destination Bus**, enter the keyword "Yes" under the correct cell.

11-Bit Filter Row Requirements:

- Each data row must have at least one **Destination Bus** set in the 11-Bit tab.
- Each data row in the 11-Bit tab must contain **ID** and **Source Bus** data.
- **ID** must be between 0 and 2047 inclusive.
- "**Notes**" information is optional.

29-Bit Filter Row Requirements:

- Each data row must have at least one **Destination Bus** set in the 29-Bit tab.
- Each data row in the 29-Bit tab must contain **Source Bus**.
- If "**J1939 PGN**" 29-Bit routing mode/mask is used, each data row in the 29-Bit tab must contain **PGN** data.

- If "**J1939 PGN and Source Address**" 29-Bit routing mode/mask is used, each data row in the 29-Bit tab must contain **PGN** and **Source Address** data.
- if "**J1939 PGN, Source Address**" 29-Bit routing mode/mask is used, each data row in the 29-Bit tab must contain **PGN**, **Source Address**, and **PGN** data.
- **PGN** must be between 0 and 262143 inclusive.
- "**Notes**" information is optional.

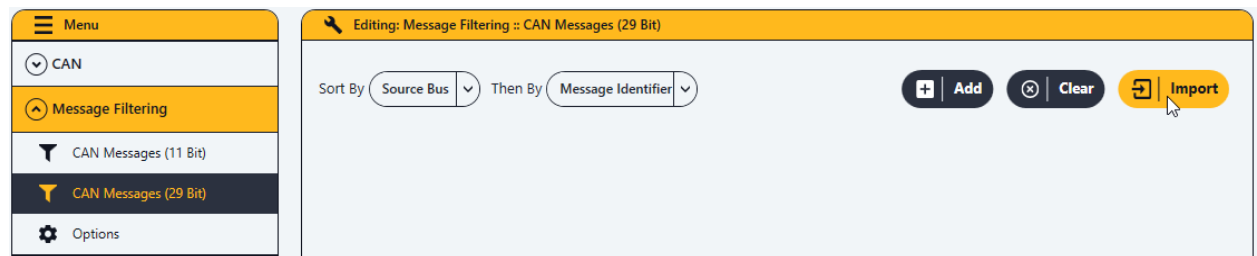
Some Things to Consider:

- Tab or column order does not matter.
- Tab or column names are not case sensitive.
- If any required filter data is missing, the row is considered invalid.
- If any columns are missing, the import is aborted.
- If any rows are found to be invalid, no filters are imported and the corresponding error information is displayed.
- Invalid data/rows are to be revised using the error information displayed before attempting to import again (see error types below).

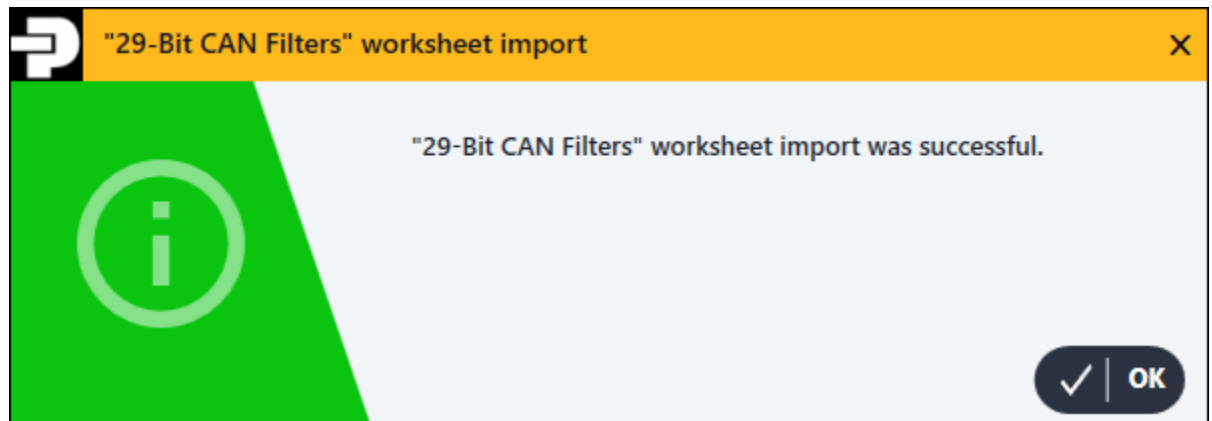
An example CAN filter import spreadsheet can be found in:

- C:\Program Files (x86)\Parker\ECD\PVSG\doc for 64-bit operating systems.
- C:\Program Files\Parker\PVSG\ECD\doc for 32-bit operating systems.

To import a message filter configuration file, navigate to the **Message Filtering** menu. Select **CAN Messages (11 Bit)** or **CAN Messages (29 Bit)**. Finally, click on the **Import** button and select the excel file (.xlsx) you created.

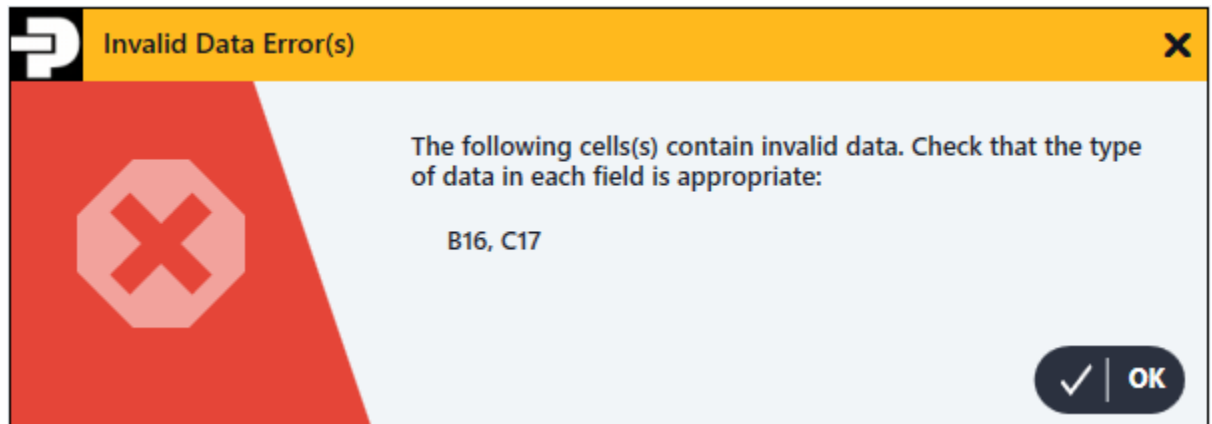


If your excel file (.xlsx) was configured properly, a window will pop up indicating your filters were imported successfully.





If your excel file (.xlsx) was not configured properly, a window will pop up indicating the error(s). Information on this window will direct you to where to find the error(s).



Below is a list of possible errors that can appear when importing.

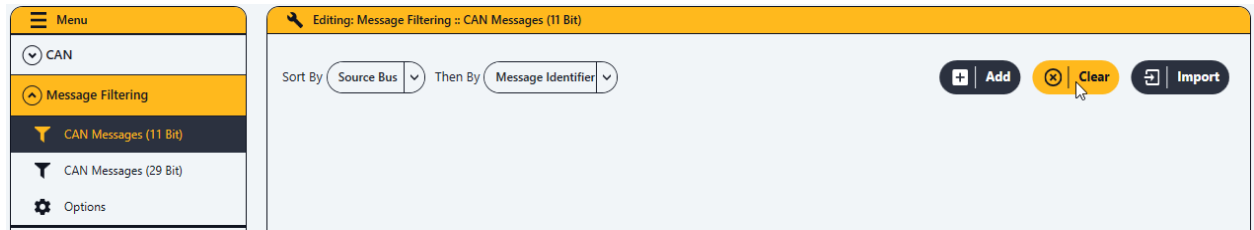
6.4.5.7. CAN Message Filter Importing Error Types

| Error Title | Solution |
|---|--|
| No Destination Bus Error(s) | Navigate to the row(s) mentioned and ensure that the data row has at least one Destination Bus . |
| Destination Matches Source Bus Error(s) | Navigate to the row(s) mentioned and ensure their Destination Bus(es) do not match their Source Bus . |
| Invalid Data Error(s) | Navigate to the cell(s) mentioned and ensure that a valid entry is entered. |
| Missing Information Error(s) | Navigate the the cell(s) mentioned and ensure that a valid entry is entered. |
| Out of Range Error(s) | Navigate the the cell(s) mentioned and ensure that a valid entry is entered. |
| Incorrect Spreadsheet Tab Label | Verify that you are on the correct menu option, i.e., CAN Messages (11 Bit) or CAN Messages (29 Bit) and that your workbook has the corresponding tab named properly ("11-Bit CAN Filters "or "29-Bit CAN Filters"). |
| 11-Bit CAN Filter Import Failed | Correct the error(s) within the "11-Bit CAN Filters" tab in your workbook and try importing again. |
| 29-Bit CAN Filter Import Failed | Correct the error(s) within the "29-Bit CAN Filters" tab in your workbook and try importing again. |

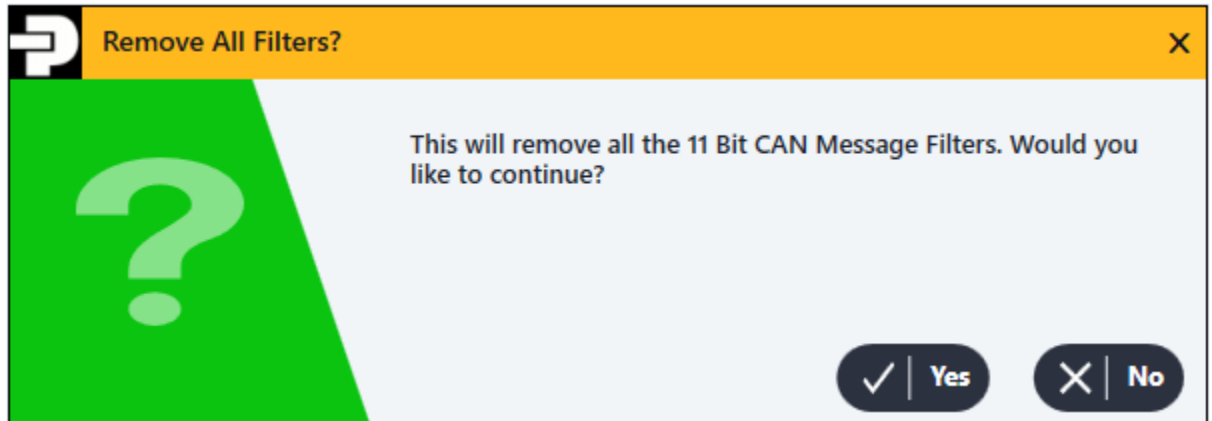
6.4.5.8. Clearing Message Filters

You can remove all filters at once using the **Clear** button.

To clear the filters, navigate to the **Message Filtering** menu. Select **CAN Messages (11 bit)** or **CAN Messages (29 Bit)**. Finally, click on the **Clear** button.



If there are filters to be cleared, a confirmation window will pop up confirming you want to remove all filters.



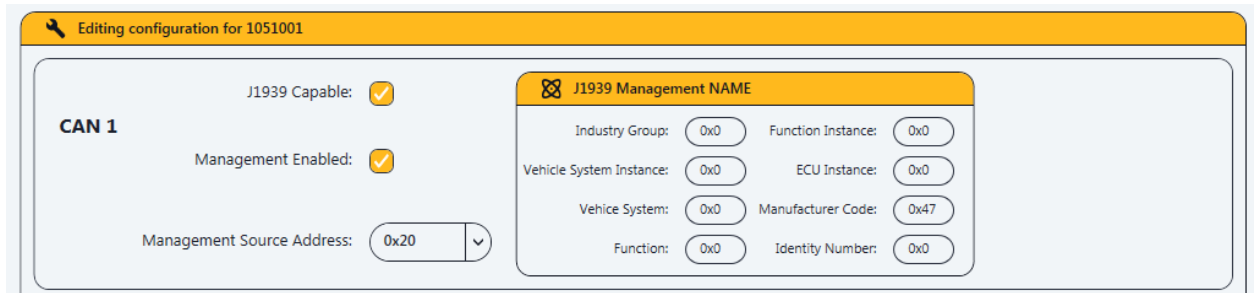
Once you click **Yes**, your message filters will be cleared and your filtering table will be blank.



Note: Clearing CAN Messages (11 Bit) filters will not clear CAN Messages (29 Bit) filters and vice versa.

6.4.6. J1939 Configuration

The PVSG contains 5 physical CAN interfaces, each of which is capable of supporting J1939 communication. J1939 configuration can be adjusted using the **J1939 Management** section under the **J1939** menu.



To support J1939, an interface must have its **J1939 Capable** property set. This denotes that the interface is connected to a J1939 capable network but does not necessarily create any Controller Applications (CAs) on it. To create a CA which can be used for management purposes (for SOFT and CI retrieval, for example), the **Management Enabled** property must also be checked. When both **J1939 Capable** and **Management Enabled** are checked, the management configuration fields become visible which allows the management source address and NAME field to be configured.



Note: A periodic DM1 message is broadcast on J1939 interfaces that have management enabled. See "Status LED" section above for details on how error information is made available in a DM1 message.



Note: If J1939 management is enabled on a bus, J1939 Request (RQST) messages for J1939 Software Identification (SOFT) and Component Identification (CI) are sent out to each J1939 module(s) on that bus.



Caution: Pay close attention to your CAN routing configuration, as J1939 management messages are routed if allowed to. This may cause J1939 address conflicts.



Caution: J1939 Software Identification (SOFT) and Component Identification (CI) responses mentioned above will be J1939 large messages directed at the PVSG. Use caution when using "block" filters in the PVSG CAN routing configuration as these large messages will be routed, using entries in the internal CAN router buffers. These entries in the buffer will never be cleared, and there are a limited amount of entries in the buffer.


6.4.7. Power Management


Power management features of the PVSG can be controlled via sub-menus of the **Power Management** menu. Currently, this allows the wakeup sources to be selected, via the *Wakeup Options* section.

When one or more enabled wakeup sources become active, the PVSG will wake up. When all enabled wakeup sources are no longer active, the PVSG will initiate a proper shutdown and go to sleep.



Note: There is a risk of corrupting the PVSG filesystem if power is removed from a PVSG prior to allowing a PVSG to go to sleep. Therefore it is recommended to always use Wakeup control to put the PVSG to sleep if power needs to be removed.


 Editing: Power Management :: Sleep/Wake Configuration

 Wakeup Control

The following options enable or disable the sources which may wake the PVSG. When one or more wakeup sources become active, the PVSG will wake up. When all enabled wakeup sources are no longer active, the PVSG will go to sleep after the timeout period has elapsed.

Input 1 ☐
 Input 2 ☐
 CAN 1 ☐
 CAN 2 ☐
 CAN 3 ☐
 CAN 4 ☐
 CAN 5 ☐
 USB ☐

Wakeup timeout: seconds

 Sleep Mode

The following options control the behaviour of the PVSG when it goes to sleep. *Sleep Mode 1* provides the lowest sleep mode current consumption possible, but with a longer time to resume on wake. *Sleep Mode 2* has a higher sleep mode current consumption, but with the benefit of resuming much more quickly. For a full description of the sleep mode options, please refer to the user manual.

Sleep Mode: ▼



Note: The **Wakeup timeout** defines the duration that all enabled wakeup sources must be idle for before being considered inactive, allowing the PVSG to go to sleep.



Note: When wakeup is enabled (any **GPIO 1 .. USB** checkbox (as seen above) is checked), upon waking (regardless of the wakeup source), the PVSG will require the **Wakeup timeout** to expire before going to sleep.



Note: If wake on CAN X is used and J1939 Management is enabled on CAN X, the PVSG will turn off DM1 messages after 5-10 seconds of inactivity on CAN X. DM1 messages will resume upon receiving messages on CAN X. Due to the delay of shutting off DM1 messages, the entrance into sleep mode (Wakeup Timeout) may increase by 5 - 10 seconds.

6.4.7.1. Sleep Mode

The **Sleep Mode** setting controls what the PVSG does when it goes to sleep. This happens when all of the unmasked wakeup sources become inactive. Available options are documented in the tables below. Note that the available sleep modes depend upon the variant used.

| Sleep Mode | Description | Time to Sleep | Router on Wakeup | Server on Wakeup | Supported Variants |
|--------------|---|---------------|------------------|------------------|--------------------|
| Sleep Mode 1 | Sleep mode with the lowest current consumption possible. Slower to fully wake from sleep than sleep mode 2. | 16 seconds | Restart | Restart | All |
| Sleep | Wakes from sleep much | 16 | Restart | Resume | 1051004, |



| Sleep Mode | Description | Time to Sleep | Router on Wakeup | Server on Wakeup | Supported Variants |
|------------|--|---------------|------------------|------------------|--------------------|
| Mode 2 | faster than sleep mode 1, but at the expense of slightly higher current consumption. | seconds | | | 005, 006 and 007. |

Example Start-up Times

| Function | On Power Up | Sleep Mode 1 | Sleep Mode 2 |
|---|-------------|--------------|--------------|
| Critical Tasks (CAN routing) | 456 ms | 432 ms | 97.2 ms |
| Non-Critical Tasks (ex. DLA functionality, product reprogramming, custom application/programming plugins) | 9.92 secs | 7.89 sec | 468 ms |

Example Current Draw

| Sleep Mode | 12V | 24V |
|--------------|---------|--------|
| Sleep Mode 1 | 3.2 mA | 1.7 mA |
| Sleep Mode 2 | 11.4 mA | 5.9 mA |

6.4.8. Input Output Management

The single output of the PVSG can be configured via the **Input Output Management** menu. Output Control can be used to toggle the output based on whether or not the PVSG is awake and/or there is a programming in progress.

Wireless is enabled and disabled as described in the "Connection Information" section, but can also be configured to be enabled or disabled via Inputs 1 and 2 using the **Input Output Management** menu. Note: Wireless configuration is still required via the **Network Configuration** menu.

6.4.9. Network Configuration

PVSG network configuration is controlled by the **Network Configuration** menu. This menu can be used to configure a PVSG to use Ethernet and/or wireless as a management connection interface. For a description of each network configuration option please refer to the tool-tip that appears when hovering over an option in the configuration tool.

Editing configuration for 1051001

Basic Configuration

Ethernet Enabled: YES NO Ethernet Management Enabled: YES NO Wireless Enabled: YES NO

Ethernet Address Configuration

Address Mode: DHCP SERVER DHCP CLIENT STATIC

Server Address: 10.62.7.1

Network Mask: 255.255.255.240

Start Address: 10.62.7.10

End Address: 10.62.7.14

Wireless Address Configuration

Address Mode: DHCP SERVER DHCP CLIENT STATIC

Server Address: 10.7.62.1

Network Mask: 255.255.255.240

Start Address: 10.7.62.10

End Address: 10.7.62.14

Wireless Configuration

Wireless Mode: ACCESS POINT CONNECT TO EXISTING

Security Mode: OPEN WEP-64 WEP-128 WEP-152 WPA WPA 2

Antenna: INTERNAL EXTERNAL AUTO

Band: 2.4 GHz Channel: 11

SSID: PVSG

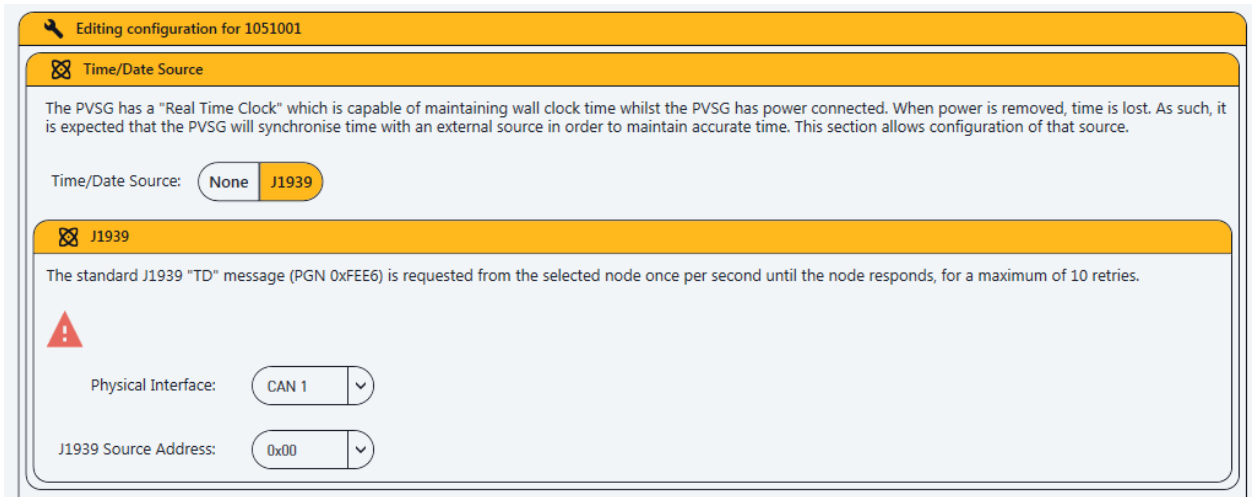
SSID Suffix: None

Management Settings

Discovery Enabled: YES NO Discovery Port: 62712 Communication Port: 62714

6.4.10. Time and Date

PVSG Time and Date configuration is controlled by the **Time/Date Configuration** menu. This menu allows the user to specify the time/date source (either **None** or **J1939**) for setting the PVSG Real Time Clock (RTC) time and date values. For a description of each **Time/Date Source** option, please refer to the tooltip that appears when hovering over a non-selected time/date source option in the configuration tool.



Editing configuration for 1051001


Time/Date Source

The PVSG has a "Real Time Clock" which is capable of maintaining wall clock time whilst the PVSG has power connected. When power is removed, time is lost. As such, it is expected that the PVSG will synchronise time with an external source in order to maintain accurate time. This section allows configuration of that source.

Time/Date Source: None **J1939**

J1939

The standard J1939 "TD" message (PGN 0xFEE6) is requested from the selected node once per second until the node responds, for a maximum of 10 retries.



Physical Interface: CAN 1

J1939 Source Address: 0x00

If the **J1939** option is selected, the physical CAN bus where the external source resides as well as its source address need to also be specified. Note that the user is required to enable and configure (via the **J1939 Management** menu) the J1939 management settings for the chosen **Physical Interface** (which houses the time/date source, a J1939-based node). The time and date configuration takes effect as soon as the configuration becomes active. The RTC will only be set via J1939 once per power session; once the first received message has been processed, all future time/date messages received by the PVSG will be ignored until the PVSG is power cycled.

Regardless of the **Time/Date Source** option selected, the RTC will contain a random time and date every time the PVSG is power cycled (until the time/date is set, if applicable). The use of one of the Sleep Modes and permanent battery shall be supplied to the PVSG if valid Time and Date data is to persist.

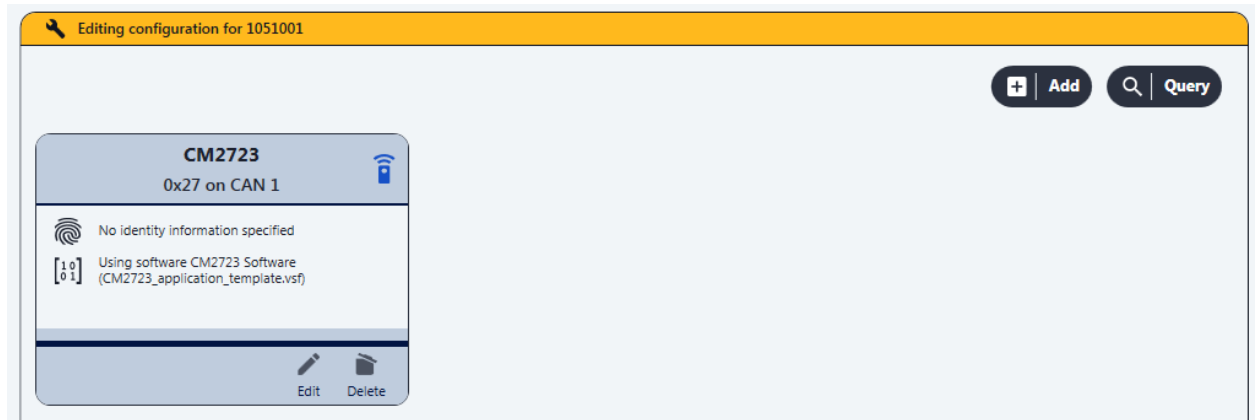
6.4.11. System Modules

This section relates to other modules within the system to which the PVSG is connected.

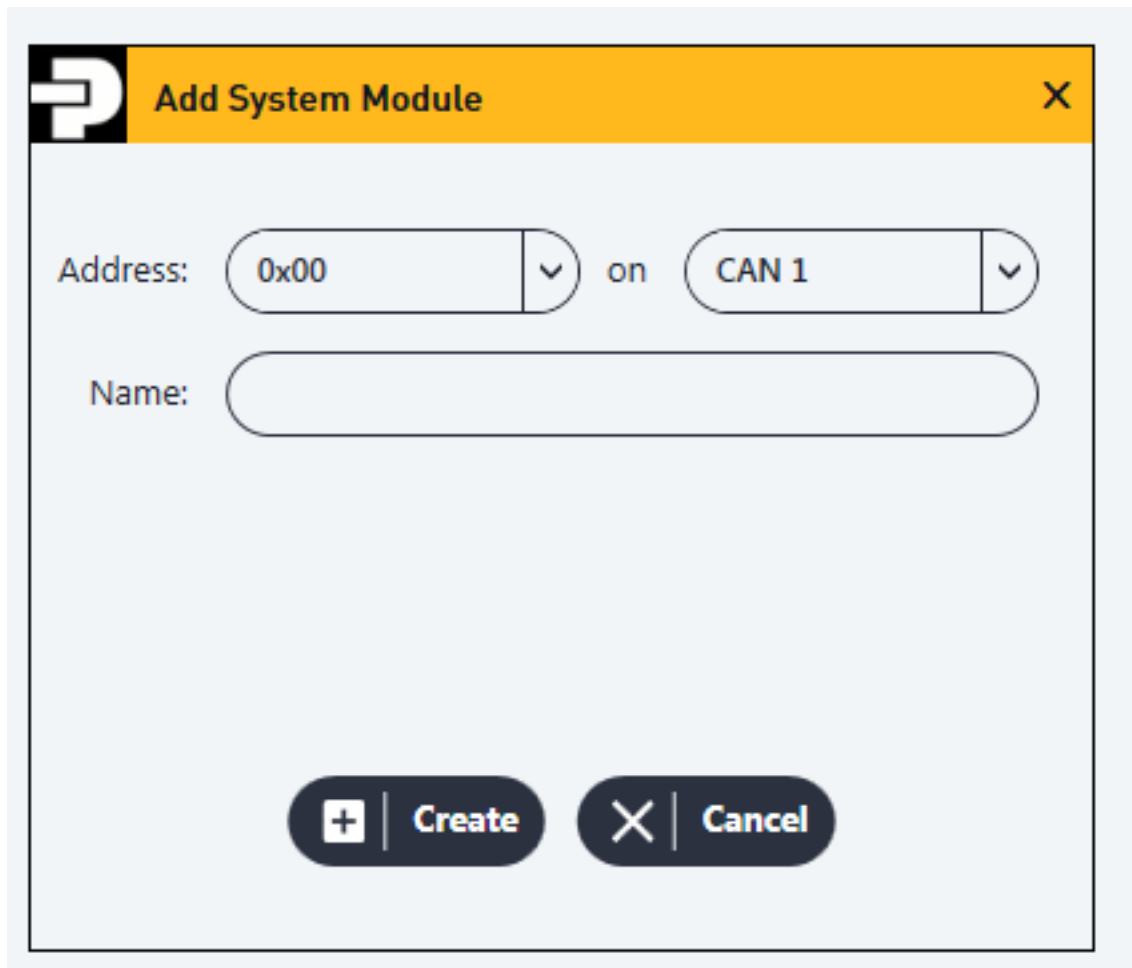
6.4.11.1. Module Management

"Modules of interest" in the target system can be identified within the module management interface. A module's core identity is comprised of its J1939 source address and the physical CAN bus on which it resides. It is possible to further refine a module's identity by using the following pieces of information:

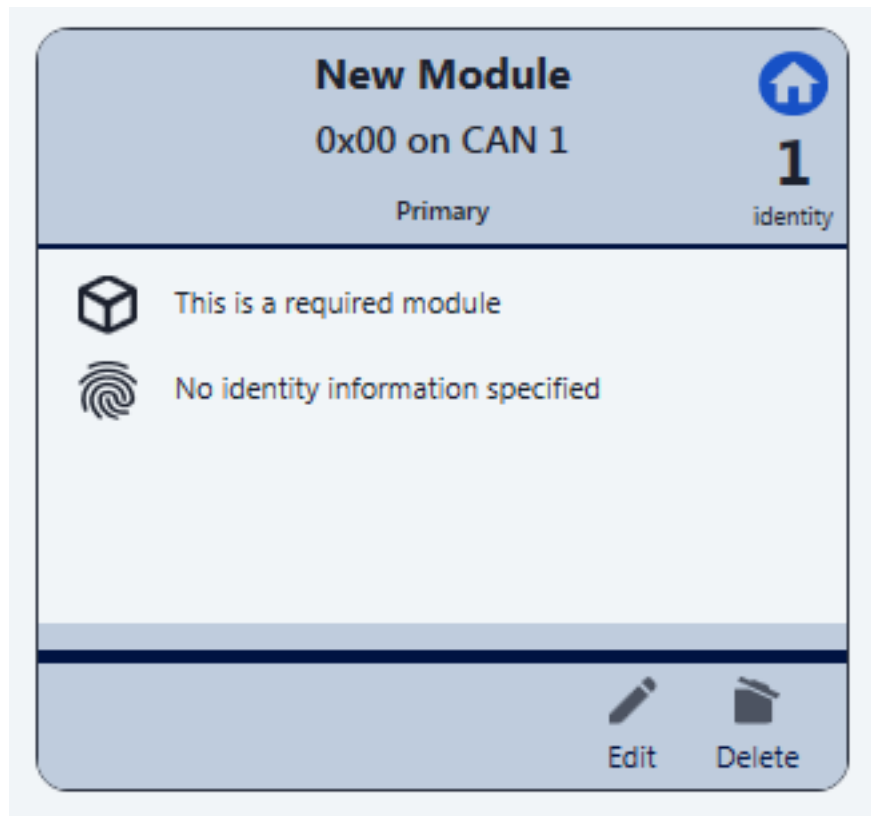
- J1939 NAME Field
- J1939 Software Identification message (PGN 0xFEDA) data
- J1939 Component Identification message (PGN 0xFEED) data



Selecting the **Add** button under the **Module Management** configuration applet allows a new module to be created:



The J1939 source address and physical CAN bus should be set, along with a descriptive name for the module. Clicking **Create** adds the module to the current configuration and shows a new **Module Card**:




The module card data changes depending upon the configuration:

CM3626


0xE4 on CAN 2

Primary




1

identity




This is a required module




No identity information specified

10
01

Using software 3626 Software
(991619_V0_02_build2.vsf)



Edit




Delete

Display


0x28 on CAN 2

Primary




1

identity




This is an optional module




Identity is formed from J1939 NAME, Software
Identity

10
01

Using software Display Software
(1007677_JCB_Loadall_P493_DECU_v0_02.vsf)



Edit



Delete

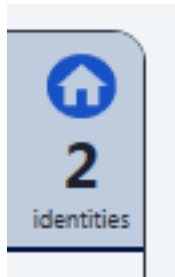


Each module offers options of **Edit** (covered in the following section) and **Delete** which, as the name suggests, allows the module to be removed from the configuration.

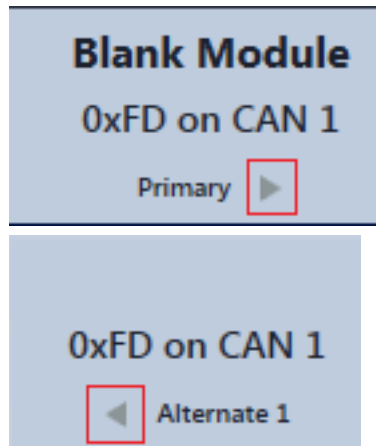
If the PC is connected to a PVSG, the **Query** button queries the information from the modules connected to the system in which the currently connected PVSG resides. The icon in the top right corner of the module information control shows the status of the module in the current system, if the PC is connected to a PVSG. It can show one of four states:

- Not queried. It isn't currently known whether this module exists or not. Icon is blue. Click **Query** to begin.
- Not connected. The module is not present in the current system. Icon is red.
- Connected, but the identity does not match. The module source address was found on the particular CAN bus, but the identity was different than configured. Icon is yellow.
- Connected, and the identity matches. The module source address was found on the particular CAN bus, and the identity matches that which was configured. Icon is green.

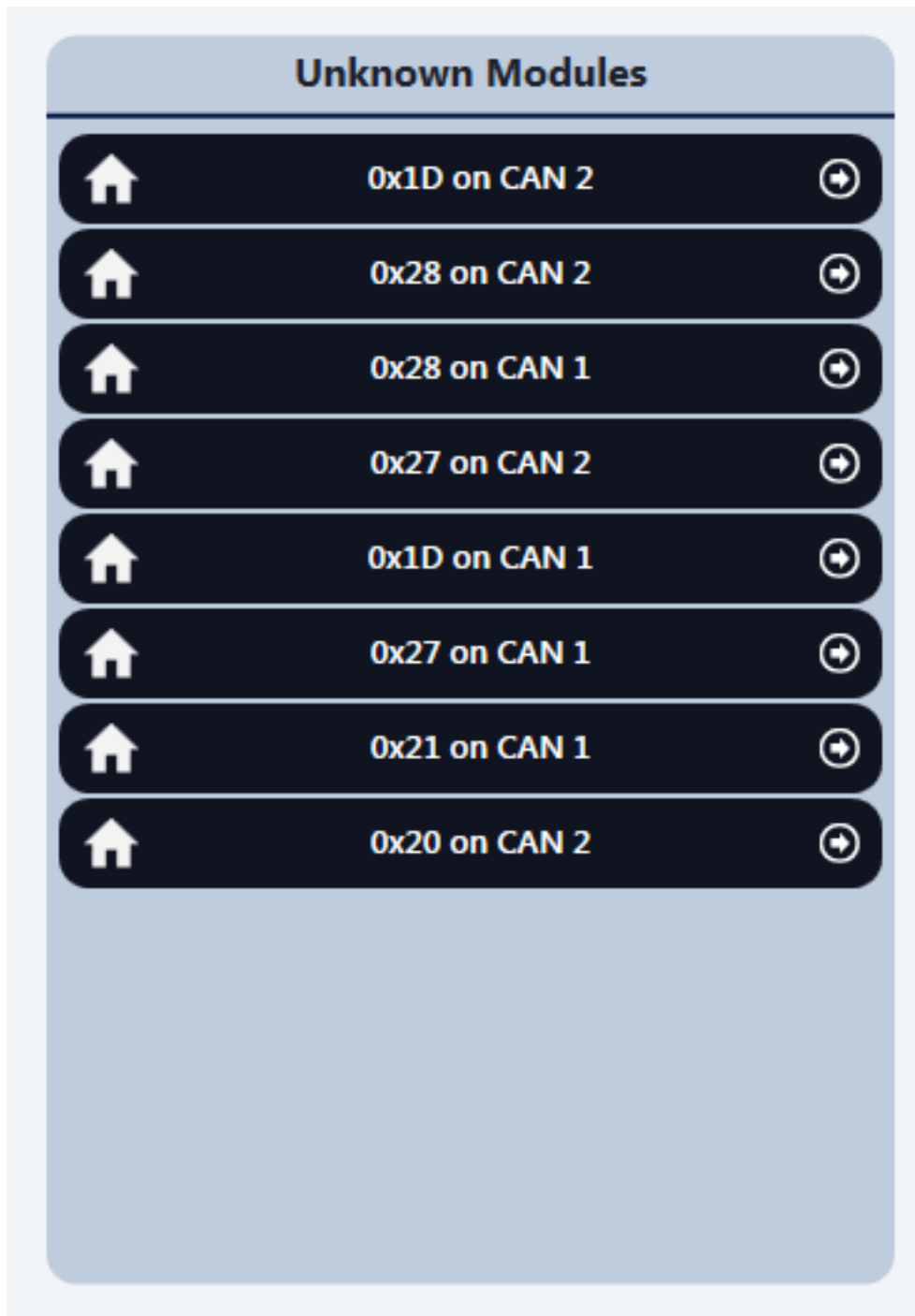
Each module may contain multiple identities; a module's core identity is formed from the J1939 source address and CAN bus though it is possible under certain conditions for a particular source address and CAN bus combination to change meaning, or be used for multiple purposes within a single system. An example of this is a blank module, containing no application software; such modules often use 0xFD as their J1939 source address until they have been programmed with a valid application. Alternate identities can be used to handle such cases, by using extra identity information to identify a unique instance of a module and then apply a different behaviour, such as installing different module software. A module must contain a primary identity, and may contain multiple alternate identities. The number of available identities is indicated in the module card header:



The module card can show information about alternate identities by cycling through the available identities:



If modules are detected on the system which are not listed in the configuration, an **Unknown** button appears. Clicking this shows the **Unknown Modules Popup**:



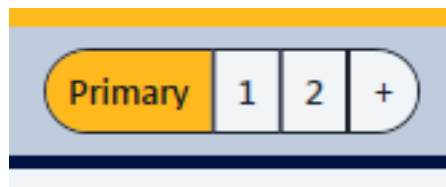
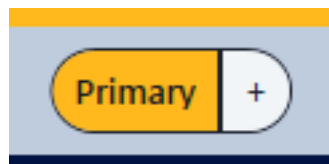
Modules listed here can be added to the configuration by clicking the arrow button beside each set of module information. When using this method, a module is added with all known properties selected. They can be removed as required using the **Edit System Module** interface.



6.4.11.2. Editing a Module

A module can be changed by clicking the **Edit** button on a particular module instance. This shows the **Edit System Module** window:

This allows the user to specify which components make up a module's identity. Additional alternate identities may be added and switched between using the toolbar buttons at the top of the window:



Note that when editing an alternate identity, only a subset of the module properties may be available for editing; in order to edit these properties, switch to the primary identity.

J1939 NAME

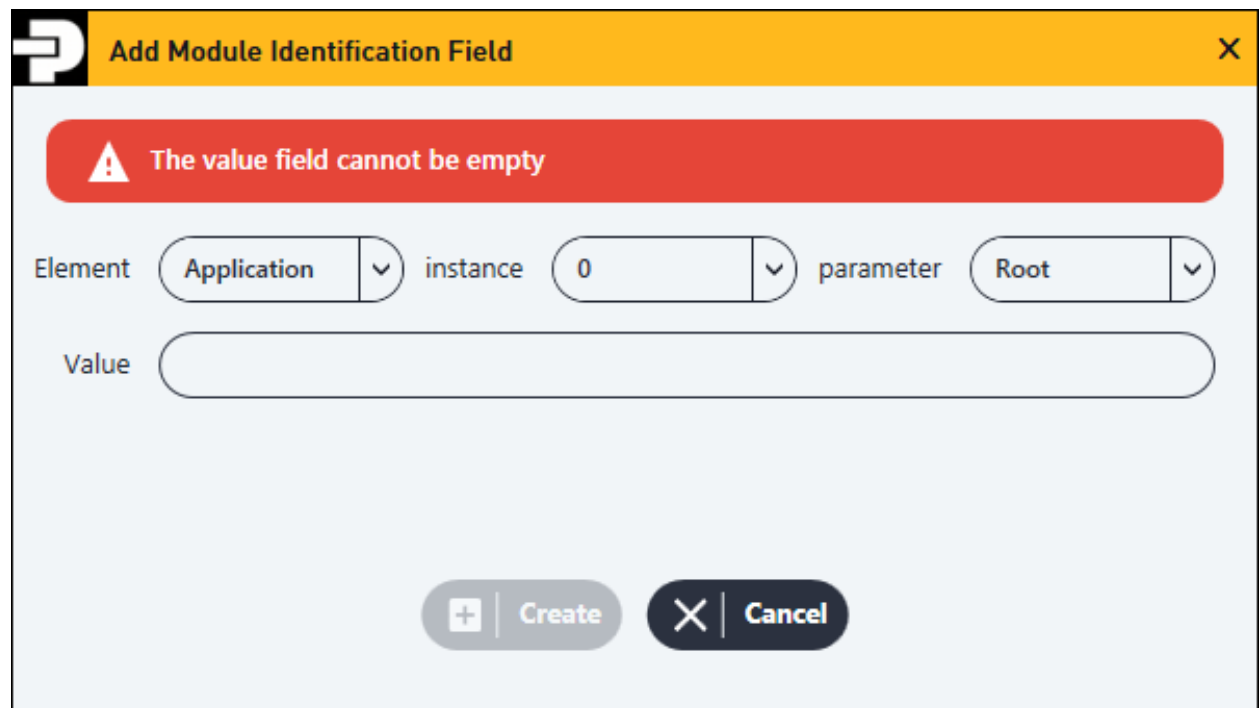
The J1939 NAME field components can be used to identify a module. To enable this, tick the box labelled **Does J1939 NAME form part of the identity?**. Values can then be specified for the individual fields of interest. For fields which are not required to be part of the identity, an asterisk (*) should be placed to indicate that any value is acceptable.

Software Identification

To make software identification a part of a module's identity, tick the box labelled **Does software identification form part of the identity?**. The SOFT message format must then be specified:


- Parker. The SOFT message uses the format defined in 983F17. Currently, R00A, R01A and R02A revisions of the standard are supported. Advanced element matching is supported.
- Raw. The SOFT message will be inspected as a raw string. Only basic value matching is provided.

When the format is chosen, use the **Add Element** button to add a new element to the identity:




The element, the instance of that element and the parameter within that element must be chosen. Refer to 983F17 for a description of the format. The value field should be populated with the ASCII string data which should be expected for the particular element and parameter combination. Click **Create** to finish.

In raw mode, only basic string comparison is supported. The user may enter any number of fields which the SOFT message data should contain:

 Add Module Identification Field ×


Value


+ Create × Cancel

 Software Identification

Does software identification form part of the identity? ☒

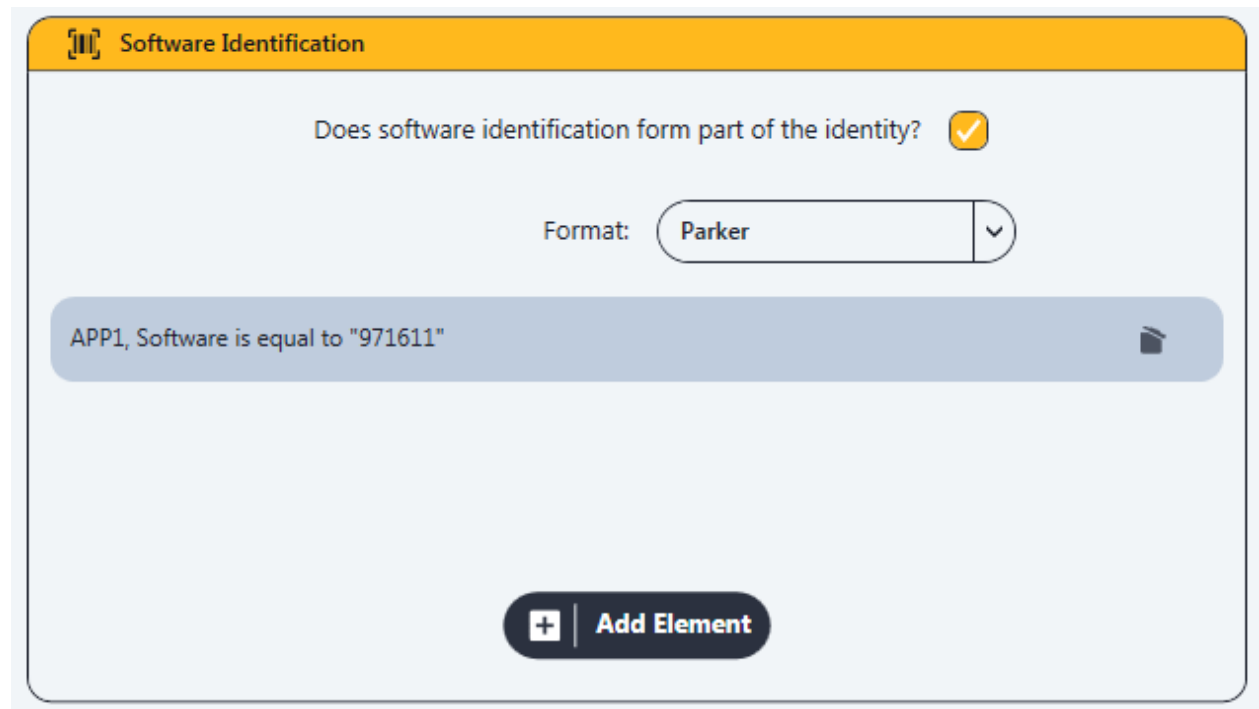
Format:

Contains "test" 

Contains "Parker" 

+ Add Element

In **Parker** format mode, the view is enhanced:



The interface is titled "Software Identification" in an orange header bar. Below the header, there is a question "Does software identification form part of the identity?" with a yellow checkmark icon to its right. Underneath, the "Format:" label is followed by a dropdown menu currently showing "Parker". A light blue box contains the text "APP1, Software is equal to '971611'" with a trash can icon on the right. At the bottom, there is a dark blue button with a plus icon and the text "Add Element".



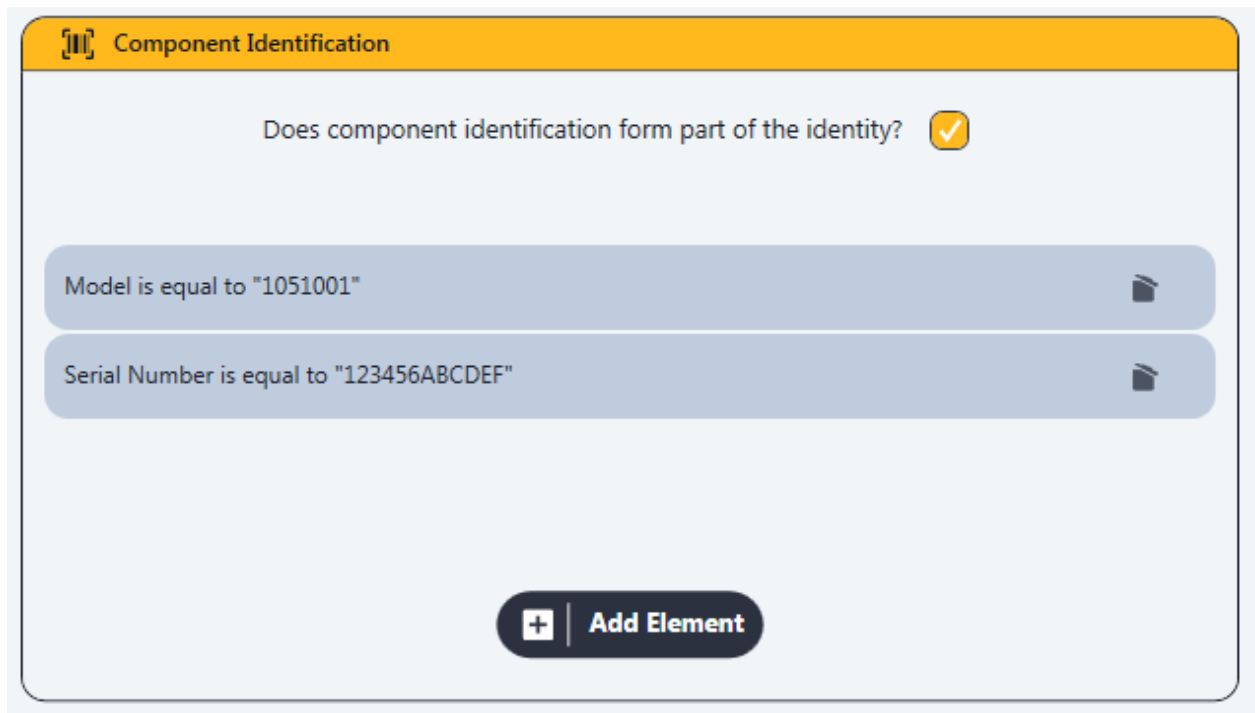
Note: Changing the software identification format when elements already exist will erase any currently stored elements.

A matching element can be removed by clicking the **Delete** icon to the far right side of the particular element to remove.

Component Identification

Component identification follows the same principle as software identification. To make component identification a part of a module's identity, tick the box labelled **Does component identification form part of the identity?**. The user may choose to match the following fields:

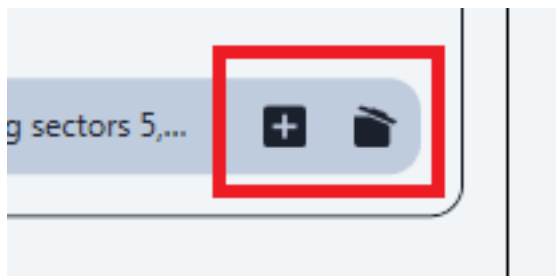
- Model. The "model" field from the component identification message. See J1939-71.
- Serial Number. The "serial number" field from the component identification message. See J1939-71.



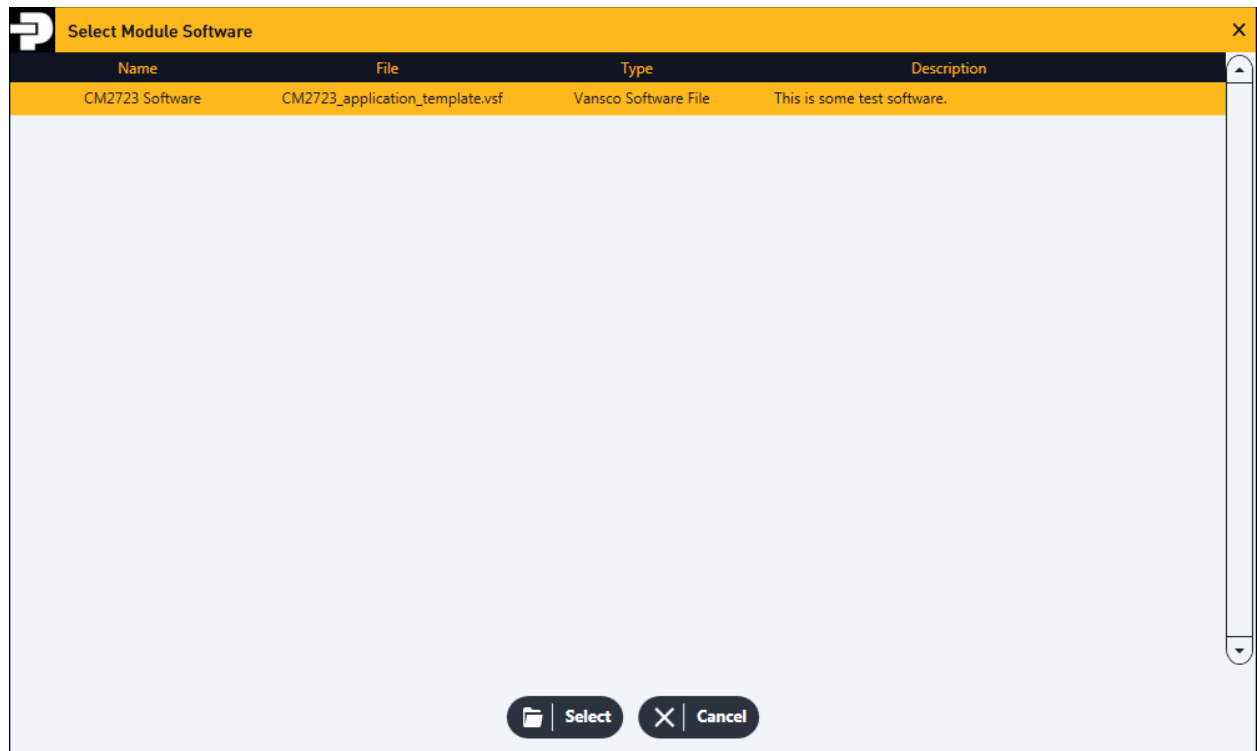
6.4.11.3. Module Software

This section controls whether the configuration stores software for this module or not, and if it does, which software is used and how and when it is deployed.

To attach a pre-configured software element to this module, tick the box labelled **Store software for this module?**. Software can be selected and removed using the **Add** and **Remove** buttons:



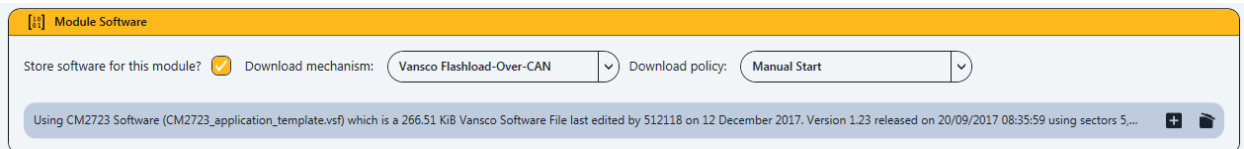
Clicking the **Add** button shows the **Select Module Software** dialog:



This dialog allows the user to select from software already loaded into the configuration via the **Software Archive** interface (see below). Clicking **Select** attaches the selected software to the module.

Note that the **Remove** button does *not* remove the software item from the configuration; it simply disassociates the software with the current module.

When selected, some detail on the software is shown:



Note that the detail shown will change depending upon the file type selected and the information actually available in the selected file.

The supported download mechanisms and download policies are per the following:

| Download Mechanism | Description |
|----------------------------------|---|
| Vansco Flashload-Over-CAN (VFOC) | The Vansco Flashload-Over-CAN-Protocol per Parker document 983F08. |
| Download Policy | Description |
| Manual Start | The module software is updated via manual invocation from a user via the PVSG dashboard (see "Dashboard" section in this document). |



6.4.11.4. Software Archive

The **Software Archive** holds all system module software for this configuration; that is, the software which is used by the external modules attached to the PVSG system.

Software must be added here before it can be used by a module.

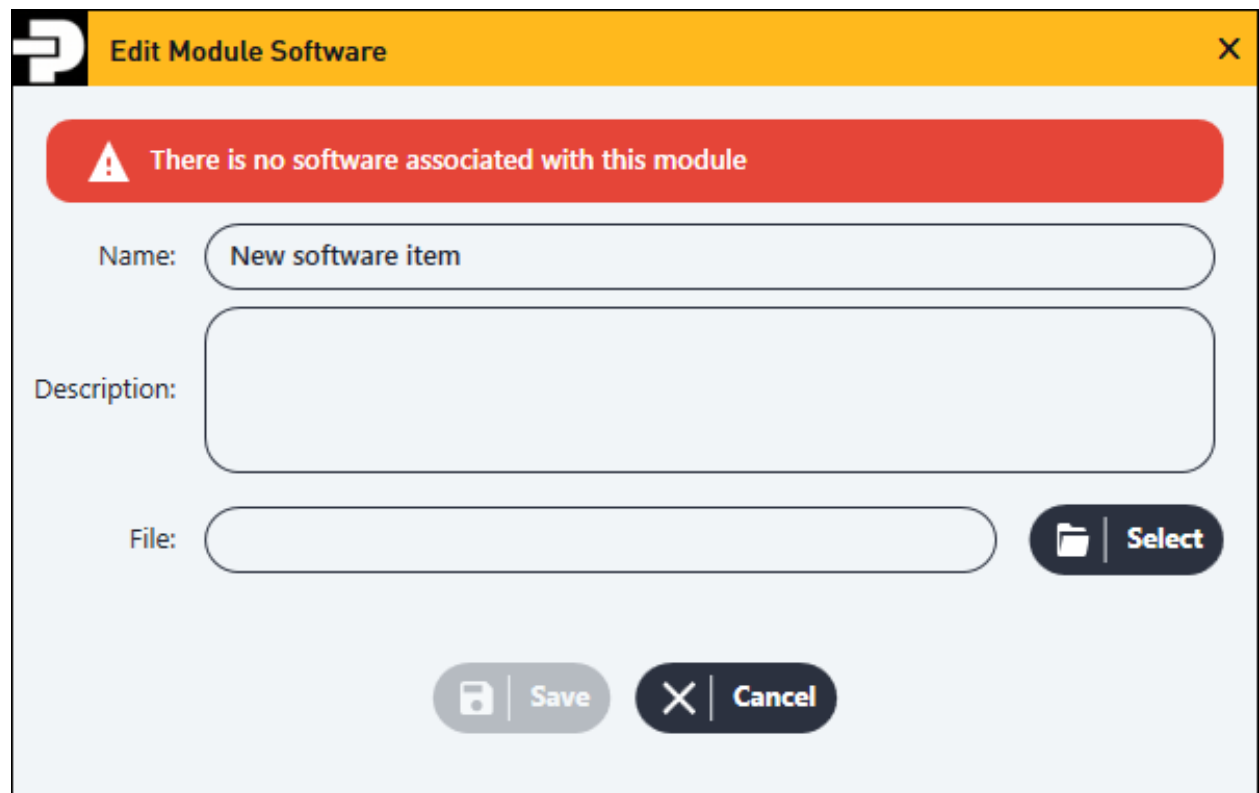


To add a software item, click the **Add** button. This adds a blank software item:




The red exclamation mark icon indicates that there is an error with the software item. This is expected because it has not yet been configured.

To edit a software item, click the **Edit** button:



Edit the **Name** and **Description** and select a software **File** to use. When complete, click **Save**.

Note that it is not required for the software item name to be unique within a configuration. The information bar at the top of the **Software Archive** applet shows information on the software stored:


 This configuration contains 266.51 KiB of software. 1 out of 2 are unused.

This includes the total size of the software stored, and whether any items are unused. Note that unused software items waste space and so it is encouraged to remove them when possible.

When software archive editing is complete, click the **Save** button to save the changes.

6.4.11.5. Module Management Settings

This section covers settings which are related to the PVSG module management system.


Unknown Modules

A "missing module" is a module which is present in the configuration but has not been found on the system. The module may have been disconnected, or be in a faulted state.

When module is missing:


When matching a module, match:

An "unknown module" is a module which is not present in the configuration but has been found on the system. The module may have been incorrectly configured, or should not be connected to the system altogether.

When an unknown module is detected:

Typically, modern vehicle systems start asynchronously. That is, multiple modules are powered on simultaneously, and are ready for operation at different times. To ensure reliable module detection, the PVSG will wait for the period defined below before testing the module configuration.

Before checking for modules, wait for:


Concurrency

Concurrency with respect to system module configuration relates to how multiple module programming operations are handled. Specifically, this concerns the action taken during the condition when multiple programming operations **could** occur concurrently.

Concurrency policy:

| Setting | Description |
|----------------------------|--|
| Missing module action | Controls the action taken when a module is determined to be missing from the system. Possible actions are Do Nothing , or Show a Fault (error code 20:1, see "Error Codes" section within this document for details) . |
| Module matching scheme | Controls how the PVSG determines whether a module matches its configured identity or not. Available options are using any identity, or requiring the primary identity. |
| Unknown module action | Controls the action taken when an unknown module is connected to the system. Possible actions are Do Nothing , or Show a Fault (error code 20:2, see "Error Codes" section within this document for details). |
| Module check hold off time | Controls the time which will be waited by the PVSG on startup before checking for modules on the system. |
| Concurrency policy | Controls the number of software update operations which may happen simultaneously. Options are limiting concurrency to one simultaneous operation, or one simultaneous operation per CAN bus. |



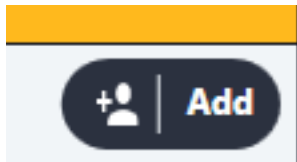
6.4.11.6. Custom Programming Plugins


The **Custom Programming Plugin** manager allows the user to add a custom programming plugins, built specifically to run on the PVSG. Consult document 1051G05, *Custom Logic User Guide* or contact Parker for more information on custom programming plugins.


6.4.12. User Accounts

6.4.12.1. User Account Management

User accounts can be managed via the **User Account Management** section. If user management is configured, certain operations can be restricted to specific users. If user management is not configured (i.e. there are no users present), all available end-user operations are possible via the anonymous user, which is logged in by default. Add a new user by clicking the **Add** button.




Add User
×



Core Properties

Username:


Display Name:


Can Login? ☒

Description:


Authentication

Authentication Mode:

Password: 



Permissions


Erase CAN Logs ☒

Erase Fault Logs ☒

Read Configuration ☒

Write Configuration ☒

 Save

 Cancel

Basic user properties may be configured, in addition to the authentication mechanism and accessible features. Possible authentication mechanisms are listed below:

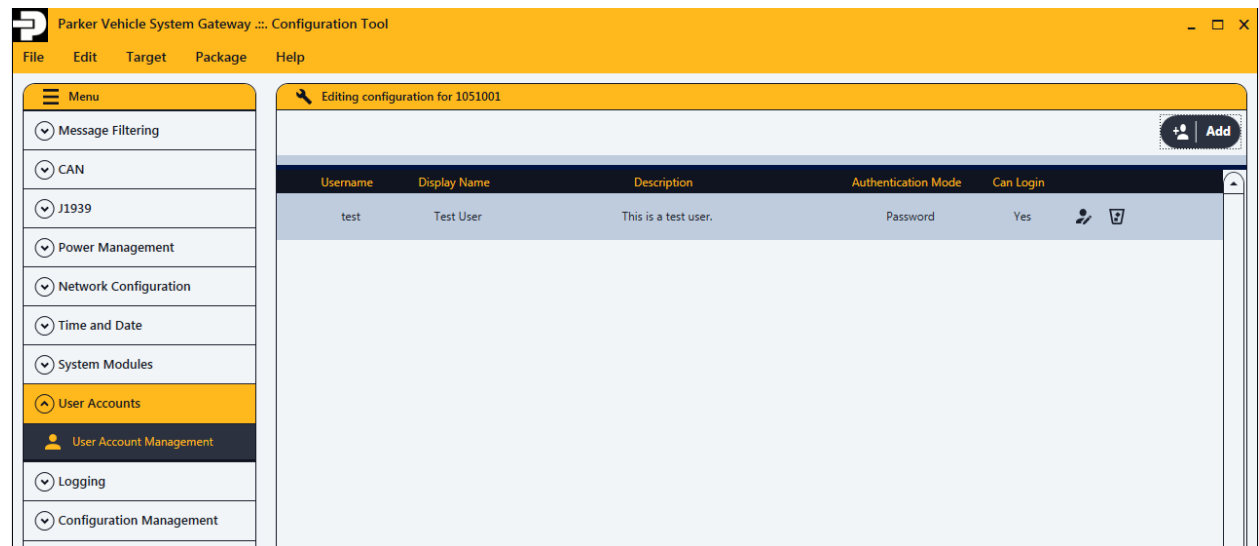
| Authentication Mechanism | Description |
|--------------------------|--|
| Password | A username and password combination is required to log in as this user. The padlock icon at the end of the password field indicates the strength of the password; to be considered secure, a password should contain at least 5 characters including upper case and lower case letters, one number and one symbol. "Weak" passwords may still be used at the discretion of the user. |

Available permissions, and their meaning, are listed below:





| Permission | Description |
|---------------------|--|
| Erase CAN Logs | Controls whether or not the CAN logs may be erased by this user. |
| Erase Fault Logs | Controls whether or not the fault logs may be erased by this user. |
| Read Configuration | Controls whether or not the configuration may be read by this user. |
| Write Configuration | Controls whether or not the configuration may be written by this user. |

Available users are listed within the main **User Account Management** applet:



A specific user may be edited or deleted using the buttons within the user information:

| Username | Display Name | Description | Authentication Mode | Can Login | |
|----------|--------------|----------------------|---------------------|-----------|---|
| test | Test User | This is a test user. | Password | Yes |   |




Note: OEM's must retain User Account details as to not lock themselves out of the unit. If a PVSG's User Accounts passwords are misplaced, the unit can be sent to Parker at the OEM's expense where it can be reset to factory setting for an additional cost.

6.4.13. Logging

6.4.13.1. Fault Logging

Fault logging configuration relates to specific J1939 Diagnostic Trouble Codes (DTCs) contained within J1939 DM1 messages which should be logged to non-volatile memory within the PVSG.

 **Add Fault to Log** ✕

Address:

0x00

▼

on

CAN 1

▼

SPN:

519712

FMI:

31

Debounce Time (ms):


2500


Fault Code:

Test

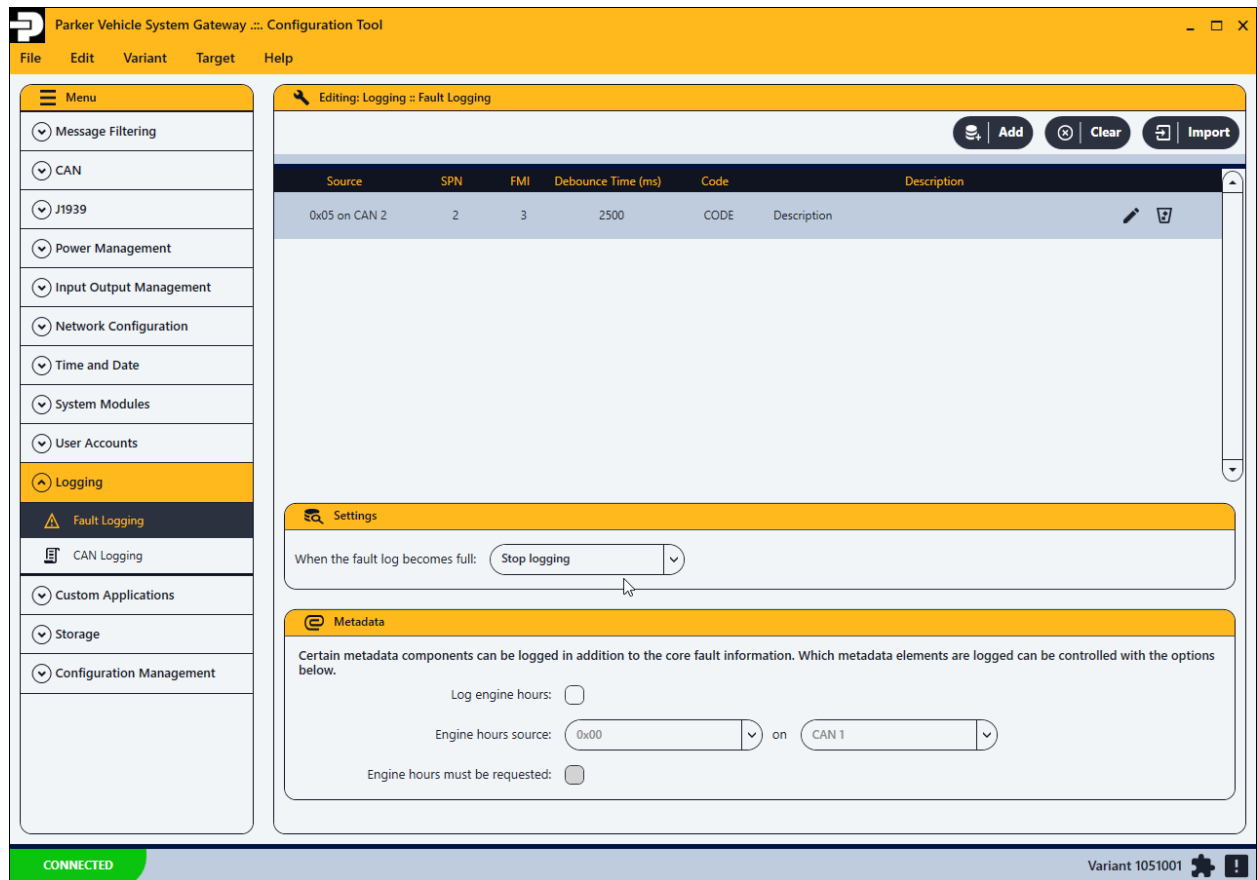
Description:

This is a test fault code.

 Save

 Cancel

Specific faults are configured in terms of Suspect Parameter Number (SPN), Failure Mode Index (FMI) and the J1939 source address and CAN bus of the originating module. A customer specific "code" can optionally be specified (which is logged with the fault information). Note that the description field is for configuration management purposes only and is not logged with the fault data. The debounce time relates to the minimum time period for which a fault must be seen to be inactive before another occurrence of the fault will be logged. This helps to prevent multiple faults from being logged for a single fault event. Note that the minimum debounce time is 2.5 seconds, which is required due to the period of the J1939 DM1 message.



The action taken when the fault log becomes full (per storage limits, see "Storage Administrator" section) can be set within the **Settings** group. The following actions are available.

| Action | Description |
|-----------------------|--|
| Stop Logging | Faults will no longer be logged until the fault log is manually cleared via the dashboard. |
| Overwrite Oldest Logs | Each time a new fault instance is required to be logged, the oldest fault log at that time will be erased. |

Optionally, metadata may be logged with each fault. Currently available metadata types are listed below.

| Metadata | Description |
|--------------|--|
| Engine Hours | The current running hours of the engine. Obtained via J1939 PGN 0xFEE5. The PVSG can optionally request this information (via the J1939 RQST message) if required. If request is enabled, the information will be queried at an interval of 5 seconds. |

Files storing fault data can be imported using the **Import** button, for adding larger quantities of faults. These files are Excel spreadsheets (.xlsx) that follow the format shown below.

| Source Address | Source Bus | SPN | FMI | Debounce Time | Code | Description |
|----------------|------------|-----|-----|---------------|------|-------------|
| 0x05 | 2 | 2 | 3 | 2500 | CODE | Description |

To use this feature, Microsoft Office must be installed on the computer. The top row will be used as a header row with the fault data under in their appropriate columns. The values accepted for these data fields are:

- Source Address: Integer values from 0x00 (0) to 0xFD (253).
- Source Bus: Integer values from 1 to 5 (for their respective CAN port bus).
- SPN: Integer values from 0 to 524287
- FMI: Integer values from 0 to 31
- Debounce Time: Integer values from 2500 to 20000
- Code: Text with a maximum length of 10 characters

All numeric fields can accept decimal and hexadecimal values. Hexadecimal values must be prefixed with "0x", such as "0xED". Note that larger files will take noticeably longer to read and import. Currently, a maximum of 1800 faults can be configured to be logged by the PVSG.

An example fault log import spreadsheet can be found in:

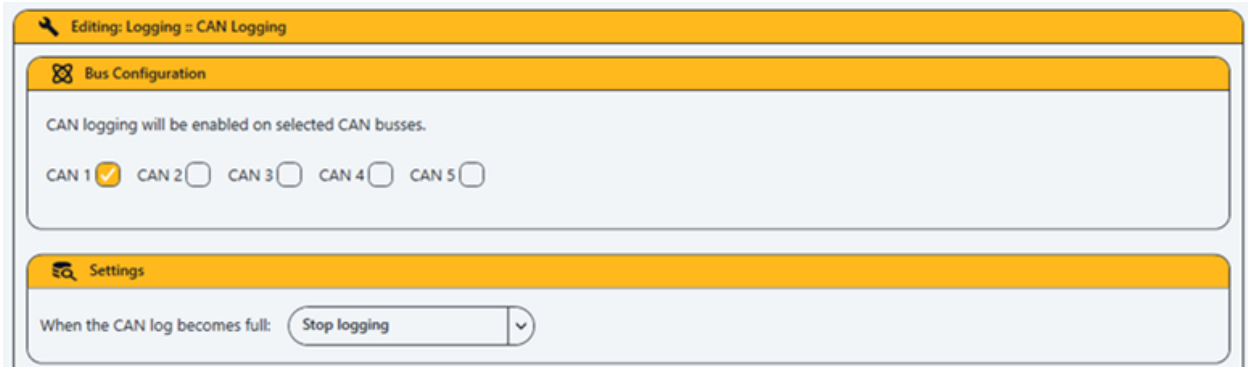
- C:\Program Files (x86)\Parker\ECD\PVSG\doc for 64-bit operating systems.
- C:\Program Files\Parker\PVSG\ECD\doc for 32-bit operating systems.

6.4.13.2. CAN Logging



Note: The CAN Logging feature is still under development and is not yet available. If CAN Logging is to be used, Sleep Mode 1 or 2 is required to ensure no loss of data in the logs.

CAN message logging on the PVSG is configurable via the CAN Logging section under Logging. All CAN traffic seen on a CAN port is recorded if configured to do so.



The action taken when the CAN log becomes full (per storage limits, see "Storage Administrator" section) can be set within the **Settings** group. The following actions are available.

| Action | Description |
|-----------------------|--|
| Stop Logging | CAN messages will no longer be logged until the CAN log is manually cleared via the dashboard. |
| Overwrite Oldest Logs | Each time new CAN messages are required to be logged, the oldest CAN messages at that time will be erased. |



Each recorded CAN log entry will contain a valid timestamp when the time and date is sent to the PVSG on power up. Refer to the **Time and Date** section for information on configuring time the PVSG to accept time. This is essential if CAN Logs are to be requested by time and date.

CAN logs are retrieved from a PVSG using the **PVSG Dashboard**. There are two ways to retrieve CAN logs, by **Time** and by **Log Number**.

To request CAN logs by Time, enter in a date and time and maximum number of entries (Max 10,000) you would like to retrieve and then click the **Request by Time** button. The PVSG will return the first CAN log entries it finds with the requested time or later, up to a max number of entries specified.

To request CAN logs by Log Number, choose a **Log Number**, **Time Since System Start** and number of entries you would like to retrieve and then click the **Request by Log** button. The Log number in the Dashboard corresponds to the log numbers on the PVSG. A new log file will be created for each PVSG power or sleep/wake cycle, empty log files will be reused. The PVSG will return the first CAN log entries it finds in the Log with the requested **Time Since System Start** or later, up to a max number of entries specified.

The screenshot shows the Parker Vehicle System Gateway Dashboard. The top navigation bar includes 'Overview', 'System', 'Logs' (selected), 'Manage', and 'Settings'. Below the navigation bar, there are tabs for 'System Log', 'Fault Log', and 'CAN Log'. The main area displays a table of CAN log entries with columns: System Time, Total Power on Time, Time Since System Start, Bus, Length, ID, and Data. The table shows several entries for '19h11m29s power on time.' with various CAN bus IDs (1, 2, 3, 4, 5) and IDs (0x123). Below the table, there are buttons for 'Previous', 'Next', and 'Export'. At the bottom, there is a row of icons for 'Configure', 'Update', 'Restart Service', 'Licenses', 'Help', 'About', and 'Shutdown'. The status bar at the very bottom shows 'CONNECTED' and a lock icon.

| System Time | Total Power on Time | Time Since System Start | Bus | Length | ID | Data |
|-------------------------|--------------------------|-------------------------|-------|--------|-------|-------|
| 01-Jan-1970 12:01:40 AM | 19h11m29s power on time. | 96s427ms | CAN 1 | 2 | 0x123 | 00 03 |
| 01-Jan-1970 12:01:40 AM | 19h11m29s power on time. | 96s427ms | CAN 2 | 2 | 0x123 | 00 03 |
| 01-Jan-1970 12:01:40 AM | 19h11m29s power on time. | 96s427ms | CAN 3 | 2 | 0x123 | 00 03 |
| 01-Jan-1970 12:01:40 AM | 19h11m29s power on time. | 96s427ms | CAN 4 | 2 | 0x123 | 00 03 |
| 01-Jan-1970 12:01:40 AM | 19h11m29s power on time. | 96s427ms | CAN 5 | 2 | 0x123 | 00 03 |
| 01-Jan-1970 12:01:41 AM | 19h11m31s power on time. | 96s28ms | CAN 1 | 2 | 0x123 | 00 03 |
| 01-Jan-1970 12:01:41 AM | 19h11m31s power on time. | 96s28ms | CAN 2 | 2 | 0x123 | 00 03 |

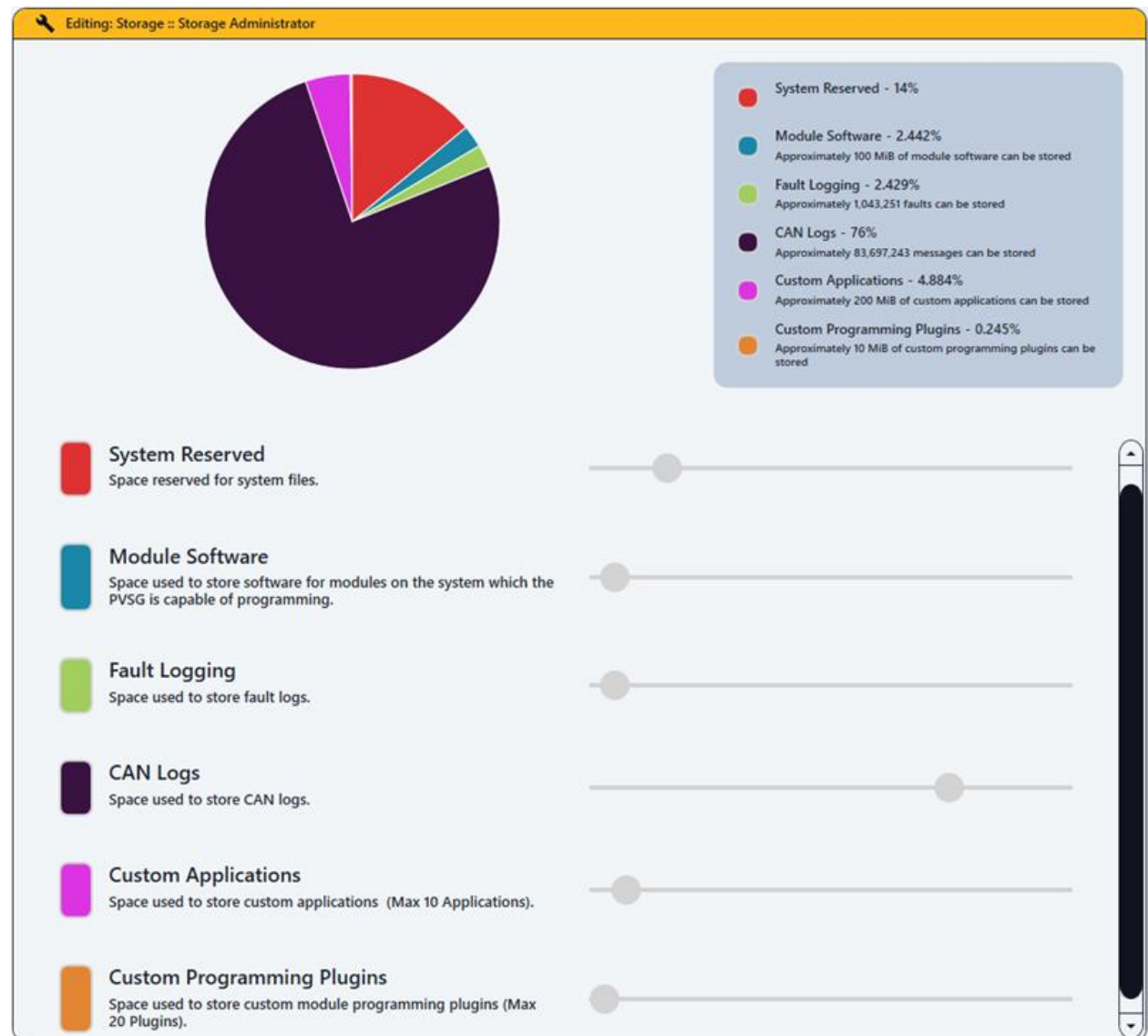
CAN logging is intended to be used as a method of viewing *past* messages. To view live messages on the PVSG, refer to the **Connecting an RP1210 Client** section. For J1939 logging or logging with more precision use another tool such as a CANalyzer.

6.4.14. Custom Applications

The **Custom Application Manager** allows the user to add a custom application, built specifically to run on the PVSG. Consult document 1051G05, *Custom Logic User Guide* for more details or contact Parker for more information on custom applications.

6.4.15. Storage Administrator

The **Storage Administrator** allows the user to view how the 'data log' memory on the PVSG is used by various features. Each feature which requires storage space on the data log memory is allocated a percentage of the available space.



In the allocation summary, a translation of percentage storage allocation to feature specific units is given, though it should be noted that this translation is approximate.

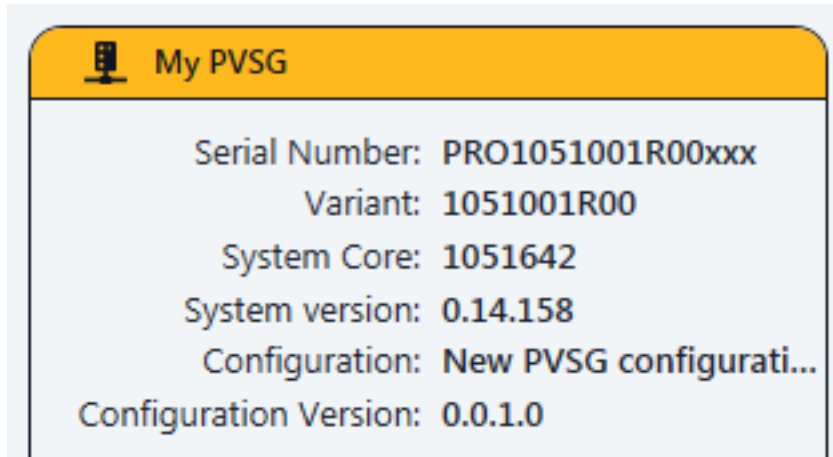
Note that storage allocation limits are approximate and subject to a certain amount of error. The PVSG platform software will do its best to achieve the desired limits, however a certain degree of variance is expected.

6.4.16. Configuration Management

It is recommended to use the **Version Information** section under the **Configuration Management** menu to properly version control your configuration files. This allows both a 3-component version number to be attached to your configuration as well as a label of your



choosing. It is recommended to increment the version number upon configuration changes according to your local version control scheme. The information inputted here will be shown in the PVSG dashboard window under the *Target Info* section:



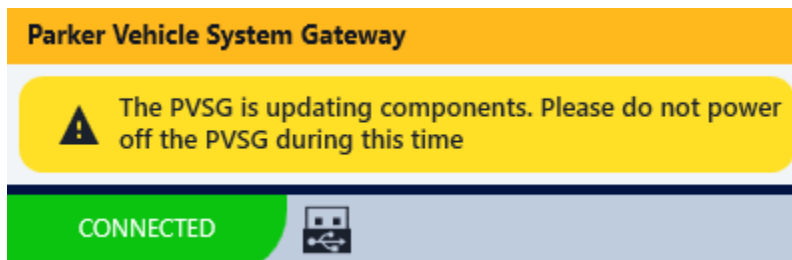
6.4.17. Exporting Configurations

A configuration report can be generated in HTML format via the **File > Export > Report** menu. Any modern web browser should be capable of viewing the report.

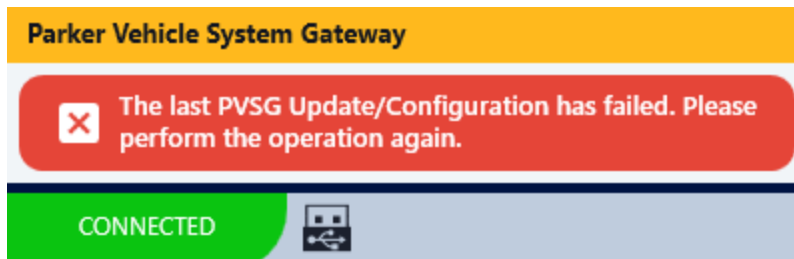
6.4.18. Transferring Configurations

The active configuration can be transferred to the target directly from the tool. With the target connected (LED status shows connected to USB, Ethernet or Wireless and dashboard reports connected), select **Target > Send Configuration** to start the process. Note that the process will require the target to be rebooted before the new configuration takes effect. In addition, after rebooting, there may be a delay until the target reports it is back online (LED status reports "Waiting" or "Connected") as it performs any necessary internal reconfiguration steps (LED status will report "Init" while reconfiguring).

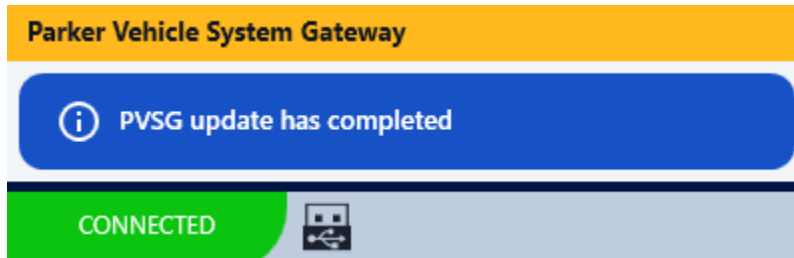
Once reconfiguration has begun, a pop up on the bottom right of the screen will appear as shown:



If the reconfiguration fails, a 2:8 error code will appear along with the following pop up:



If the reconfiguration succeeds, the following pop up will be shown:

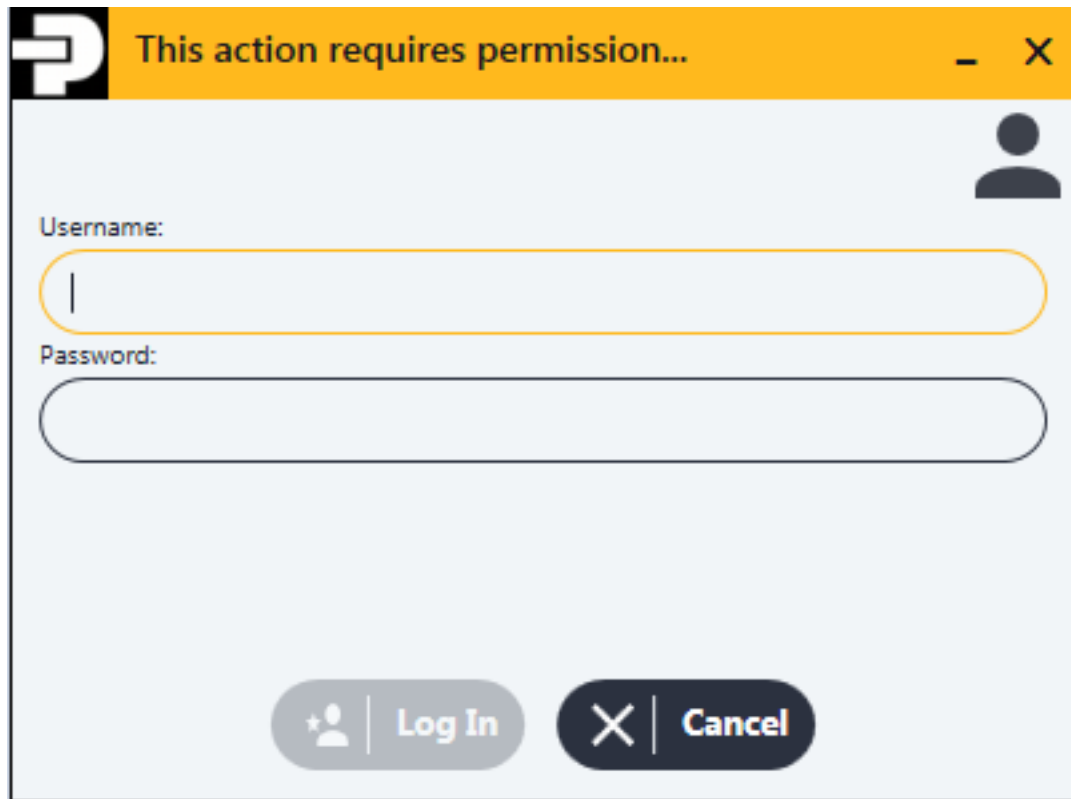


To confirm that your configuration was successful, verify that the "PVSG update has completed" pop up appears and that no new errors appear in the dashboard.

The configuration from a currently connected PVSG can be read using the **Target > Read Configuration** menu. Note if the configuration is password protected (see the "Configuration Security" section of this document for details on how to password protect a configuration), you will be prompted for this during the read procedure. Also note that if you have not reset the PVSG (either manually or via prompt from configuration tool) after transferring a configuration, the retrieved configuration is the new configuration, not the currently active configuration.

6.4.18.1. Configuration Security

If user management has been configured (see "User Account Management" section) on the configuration already installed on the PVSG, attempting to read or write the configuration will result in a request for authentication if the currently logged in user does not have permission to read/write the configuration respectively. Note that the need for user authentication is based on the configuration already installed on the PVSG, and not the configuration loaded into the configuration tool. If authentication is required, the following window will appear:



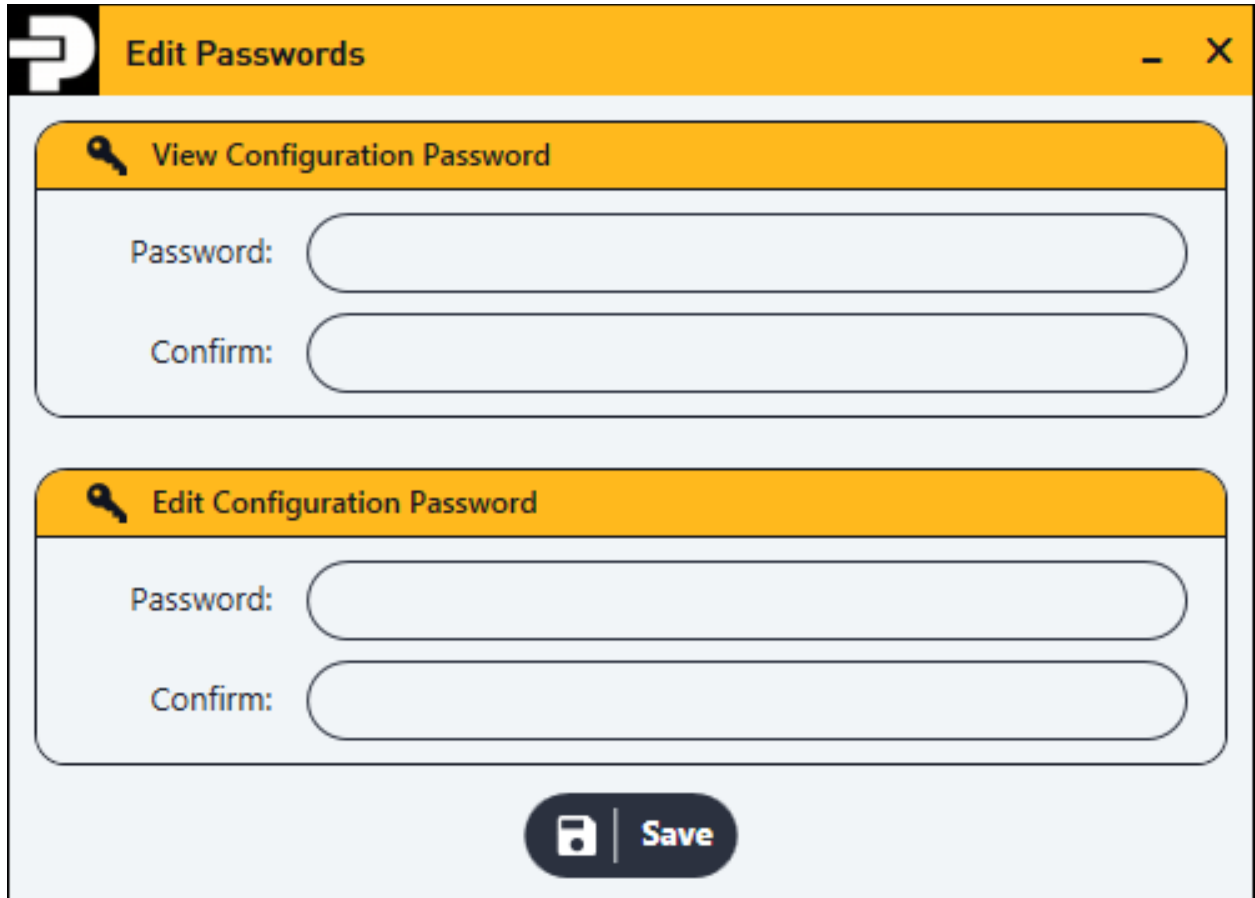
To continue, enter the username and password of a user who has permission to perform the respective operation (either read configuration or write configuration).

Configuration Overwrite

The option labelled **Force Configuration Overwrite** on the *Build Combined Target Package* window allows control over whether the configuration already installed on the target is overwritten. If selected, the combined configuration will always be deployed to the target and will overwrite any installed configuration. If not selected, the combined configuration will only be written to the target if no configuration is already present.

6.4.19. Configuration Security

A configuration can be protected with passwords to provide security. Separate passwords for 'view' and 'edit' can be set. This can be done via the **Edit > Passwords** menu.



Passwords are operated in a hierarchical manner; that is if the user has the 'edit' password, then they can of course 'view' the configuration as well. If a configuration file only has an 'edit' password is set, upon opening the configuration, cancel the login operation to view the configuration without edit abilities.

6.4.20. Tool Information

Version information for the configuration tool can be sought using the **Help > About** menu.

6.4.21. Command Line Interface

The configuration tool also provides a command line interface. Locate pvsgcfg.exe (installed as part of the installer 1051605), and run "pvsgcfg.exe -h" to get a listing of all of the available commands.

7. Recovery

In the event a PVSG is corrupted or embedded software upgrade has failed, attempt recovery via:

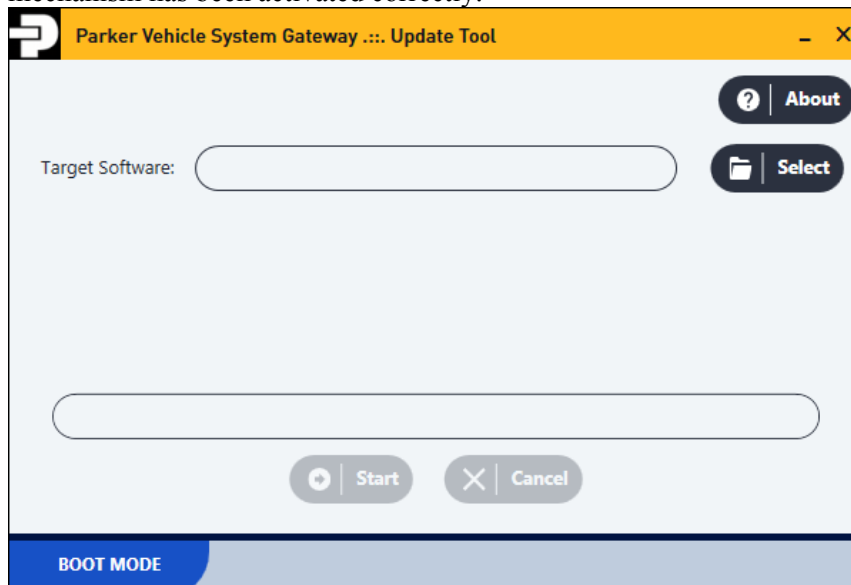
1. Run update tool (1051606),
2. (if previous step did not work) activate hardware recovery mechanism (see "Connector Pinout" section of this document for "Recovery" pin, active high), power cycle the PVSG to enter bootstrap mode (see Note below), and redo 1.



Note: The first time a PVSG is connected to a PC via USB with the "Recovery" pin active, Windows will initiate a USB Driver Software installation. The PVSG PC Software should not be used until the USB Driver Software installation has completed.



Note: update tool status will show BOOT MODE to indicate hardware recovery mechanism has been activated correctly:



8. Known Limitations

| Component | Case | Description | Workaround |
|---------------|-----------------------|--|---|
| USB | 30575 | USB interface is not isolated. This can result in damage to the PVSG or a PC when the PC is powered off of the Mains (as opposed to powered by a battery alone). This is a known limitation that was decided upon at design time and will not be changed. | Use of a USB isolator is recommended to reduce the risk of damage to the PVSG or other equipment, when connecting to the PVSG from a USB host port on a PC connected to Mains supply. |
| PVSG Software | 41399 | The PVSG currently utilises an internal system clock whereby the maximum encodable time is 03:14:07 19 January 2038. | It is expected that a workaround will be available in a future software update. |
| PVSG Software | 35254 | PVSG message routing operates according to a FIFO algorithm whereby messages are dispatched in the same order as they are received. | None. |
| PVSG Software | 45300 | Serialisation error when using trying to save configuration files created with 1051605 V0.14.x.x when using 1051605 V0.15.x.x or newer. | Go to System Modules > Module Management Settings and select something from each of the drop down boxes. |
| PVSG Hardware | 47460 | There is a known issue with wireless channel 6 where the connections can be unexpectedly dropped. | Avoid using channel 6. |
| PVSG Software | 46924 | With J1939 management and wakeup enabled on the same CAN bus, once awake, the PVSG will not go sleep due to the periodic J1939 DM1 message sent by the PVSG keeping the CAN bus active. | Avoid using J1939 management and wakeup on the same CAN bus if wake to sleep transition is required. |
| PVSG Software | 51900 | System and Fault log databases can become corrupt if the server is not properly shutdown before removing power from the PVSG. | Always use a wake up to initiate a server shutdown before powering off the PVSG. |
| PVSG Software | 53981 | Currently there is no way to clear the CAN Logs. | A future release of software will add this feature, for now configure CAN logging to overwrite oldest logs. |
| PVSG as a DLA | | The CM0504 cannot be reprogrammed using the PVSG | Use a Vansco DLA to program the CM0504. |



| Component | Case | Description | Workaround |
|-----------|------|--|--|
| | | as a DLA, since the CM0504 requires a special programming tool that is hard-coded to use the Vansco DLA. | |
| USB | | The PVSG PC Software may lose connection with the PVSG while still connected to the PVSG via USB. | Remove all unnecessary USB devices from the PC. Remove and restore USB connection to PVSG and/or restart PVSG Driver Core via the PVSG Dashboard ("Restart Service") until connection is restored. |

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